

COURSE NOTES

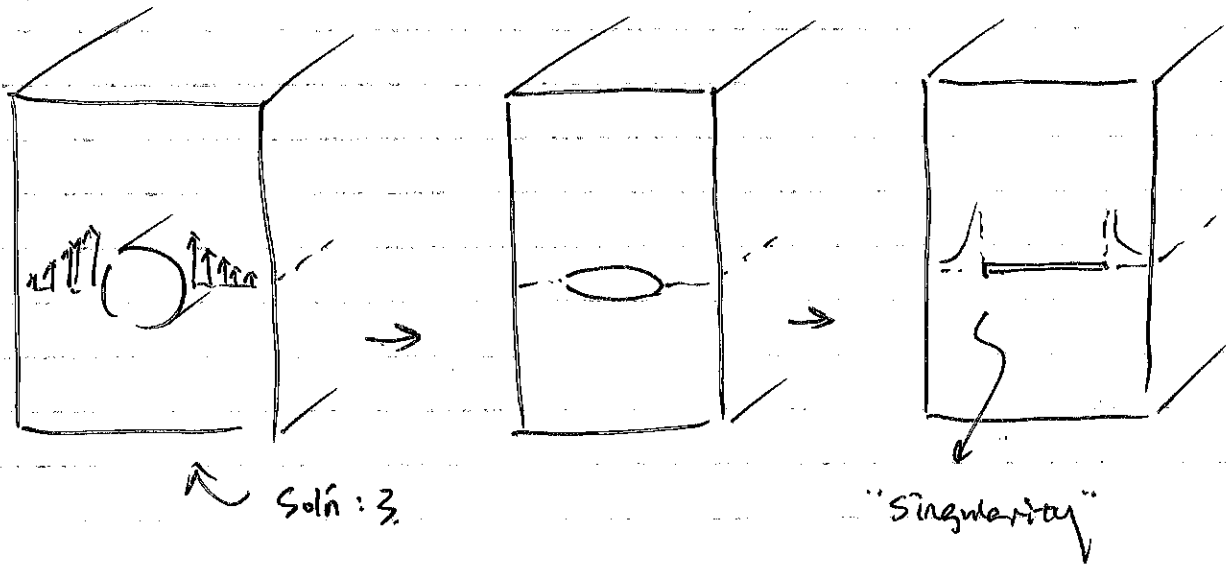
ELASTICITY & INELASTICITY

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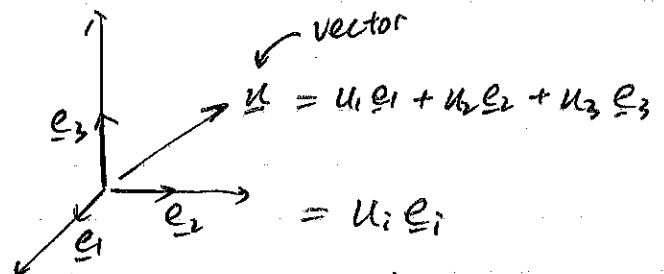
elasticity & inelasticity.

4/1/2024



• Tensor transform.

• Stress-strain relations



"not a vector" $\rightarrow u_i = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$

column vector

$u_i e_i$

$$u_i' = \begin{bmatrix} u_1' \\ u_2' \\ u_3' \end{bmatrix}$$

Define a matrix $Q_{ij} = (e_i' \cdot e_j)$

orthogonal matrix: $Q^{-1} = Q^T$

$$\begin{bmatrix} u_1' \\ u_2' \\ u_3' \end{bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} \\ Q_{21} & Q_{22} & Q_{23} \\ Q_{31} & Q_{32} & Q_{33} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

$$u_i' = Q_{ij} u_j$$

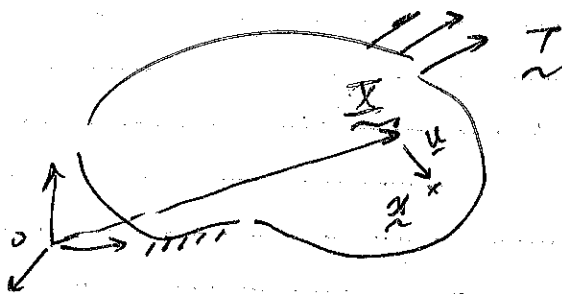
$$a_i' = Q_{ij} a_j$$

index notation

$$u_i P_{ij} = v_j$$

$$U_k P_{ij} U_j \rightarrow \mathbb{R}.$$

↑ unless we specify the element-wise multiplication



$$\underline{u} = \underline{x} - \frac{\bar{x}}{n}$$

Displacement field

$$\underline{u}(\underline{x}) \sim \underline{u}(\underline{\tilde{x}})$$

... no gradient deformation tensor here

Strain field.

$$u_{ij} = \frac{\partial u_i}{\partial x_j}$$

Small deformation
assumption

Strain: $\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) = \epsilon_{ji}$.

$$w_{ij} = \frac{1}{\sqrt{2}} (u_{ij} - u_{j+1}) \quad \leftarrow \text{perturbation}$$

No higher-order terms

$$\xi_j' = \dim \mathcal{O}_j^n \sum m_n.$$

$$\epsilonpsilon_{lonp} = Q * \epsilonpsilon_{lon} * Q'$$

$$\epsilonpsilon_{lonp} = \text{zeros}(3,3).$$

$$\text{for } i = 1:3$$

↗ equivalent.

$$\text{for } j = 1:3$$

$$\text{for } m = 1:3$$

$$\text{for } n = 1:3$$

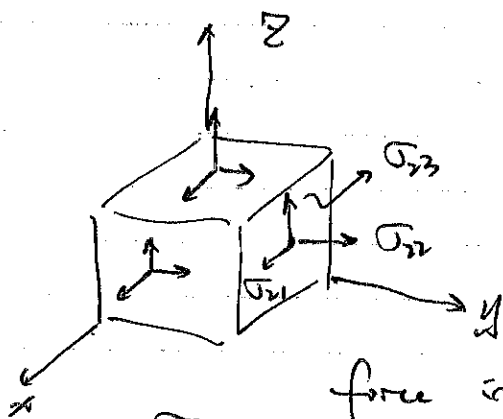
$$\epsilonpsilon_{lonp}(i,j) = \sim + Q(i,m) * Q(j,n) * \epsilonpsilon_{lon}(m,n);$$

end

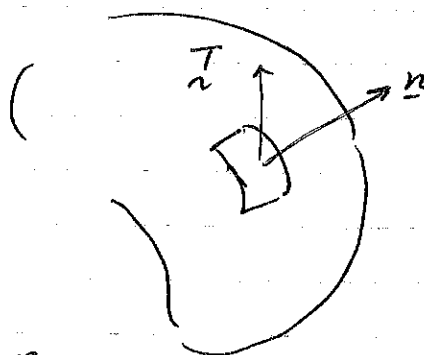
end

end

end.



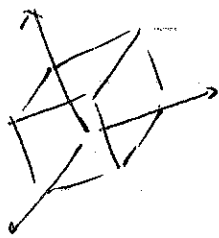
$$\sigma_{ij} = \frac{\text{force in } j\text{-th direction}}{\text{area in } i\text{-th face}}$$



$$T_j = \sigma_{ij} n_i$$

↗ Symmetric tensors,

$$\sigma_{ij} = \sigma_{ji}$$

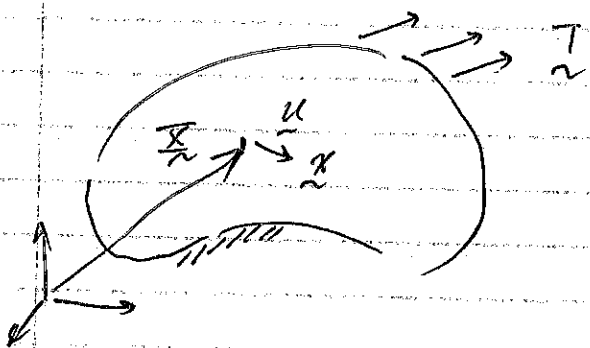


$$\sigma'_{ij} = Q_{ip} Q_{jq} \sigma_{pq}$$

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl} \rightarrow C'_{ijkl} = Q_{im} Q_{jn} Q_{kp} Q_{lq} C_{mnpq}$$

11/3/2024

Lecture 2.



Displacement field: $u_i(x)$

Strain field: $\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$

Stress field: σ_{ij}

Traction field: $T_j = \sigma_{ij} n_i$

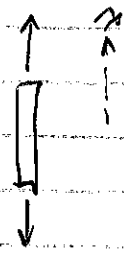
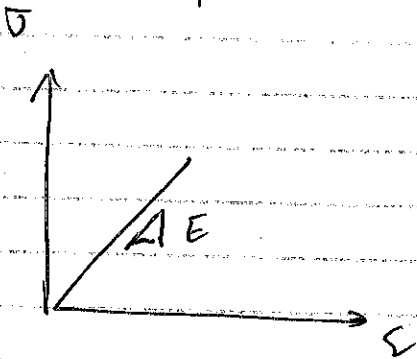
Generalized Hooke's law: $\sigma_{ij} = C_{ijkl} \epsilon_{kl}$

Today: { PDE for elasticity.

Attempt to solve it.

Anisotropic vs.

isotropic elasticity.



... generalized Hooke's law.

Voigt notation:

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \sigma_4 \\ \sigma_5 \\ \sigma_6 \end{bmatrix} = \begin{bmatrix} D_{11} \\ D_{12} \\ D_{13} \\ D_{14} \\ D_{15} \\ D_{16} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & \dots & C_{16} \\ \vdots & \ddots & & \vdots \\ C_{61} & \dots & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{31} \\ 2\epsilon_{12} \end{bmatrix} \rightarrow \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \\ \epsilon_6 \end{bmatrix}$$

$$\sigma_{11} = C_{1111} \epsilon_{11} + \underbrace{C_{1112} \epsilon_{12} + C_{1121} \epsilon_{21}}_{C_{1112} 2 \epsilon_{12}} + \dots + C_{1123} \epsilon_{23}$$

↓

$$C_{16} = C_{1112} = C_{1121}$$

$$\sigma_I = C_{IJ} \epsilon_J, \quad I, J = 1, 2, \dots, 6$$

$$\epsilon_{IJ} = S_{ijkl} \sigma_{kl}$$

↑ inverse of C_{ijkl}

$\sigma_{ij} \rightarrow 9$ components, 6 ind. comp.

$C_{ijkl} \rightarrow 81$ components, 21 ind. comp.

$$\sigma_I = \frac{\partial W}{\partial \epsilon_I}$$

$$W = \frac{1}{2} \epsilon_I C_{IJ} \epsilon_J$$

↑ Symmetric C_{ijkl} } $6+5+\dots+1=21$

Isotropic Material

$$\begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & -\frac{\nu}{E} & -\frac{\nu}{E} & 0 & 0 & 0 \\ -\frac{\nu}{E} & \frac{1}{E} & -\frac{\nu}{E} & 0 & 0 & 0 \\ -\frac{\nu}{E} & -\frac{\nu}{E} & \frac{1}{E} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix}$$

Sym

→ E, ν, G

→ S_{ijkl}

Relationship between the material parameters.

$$E = 2(1+\nu) \cdot G$$

HWs:

$$C_{ij} \rightarrow C_{ijkl} \rightarrow C'_{ijke}$$

$$S_{ij} \rightarrow S_{ijkl} \rightarrow S'_{ijke} \quad E' = \frac{1}{S_{iiii}}$$

Equations for elasticity.

- compatibility condition.

$$\epsilon_{ij,kl} + \epsilon_{kl,ij} - (\epsilon_{ik,jl} + \epsilon_{jl,ik}) = 0$$

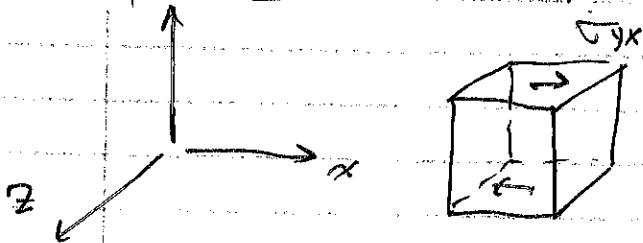
only for
small deformation

- equilibrium condition

$$\sigma_{ij,i} + f_j = 0$$

$$U(x) - 3 \text{ DoF}$$

$$\epsilon_{ij}(x) - 6 \text{ DoF}$$



$$\nabla \cdot \underline{\underline{\sigma}} + \underline{\underline{F}} = 0$$

- constitutive relation.

- B.C.s

For isotropic elasticity:

$$\sigma_{ij} = \lambda \epsilon_{kk} \delta_{ij} + 2\mu \epsilon_{ij}$$

$$\epsilon_{ij} = -\frac{\nu}{E} \sigma_{kk} \delta_{ij} + \frac{1+\nu}{E} \sigma_{ij}$$

$$\delta_{ij} = \begin{cases} 1 & , i=j \\ 0 & , i \neq j \end{cases} \quad \text{Kronecker delta}$$

$\Sigma_{kk} \rightarrow \Sigma_{\text{trace}}$ i.e., hydrostatic.

$$\Sigma_{11} + \Sigma_{22} + \Sigma_{33}$$

General strategies for sol'n.

1) $\sigma_{ij} = \lambda u_{kk} \delta_{ij} + \mu (u_{ij} + u_{ji})$

$$\mu u_{i,kk} + (\lambda + \mu) u_{k,ki} + F_i = 0$$

3 eqs.

$$\mu \nabla^2 u + (\lambda + \mu) \nabla(\nabla \cdot u) + \underline{F} = 0$$

2) write compatibility condition in terms of stress.

(2D)

↳ equilibrium condition

$$\begin{cases} \sigma_{xx,x} + \sigma_{yx,y} + \bar{F}_x = 0 \\ \sigma_{xy,x} + \sigma_{yy,y} + \bar{F}_y = 0 \end{cases}$$

2D compatibility: $\epsilon_{xx,yy} + \epsilon_{yy,xx} + 2\epsilon_{xy,xy} = 0$

trial sol'n / ansatz: $\phi(x,y)$

$$\sigma_{xx} = \phi_{,yy}$$

$$\sigma_{yy} = \phi_{,xx}$$

$$\sigma_{xy} = -\phi_{,xy}$$

} Equilibrium automatically satisfied

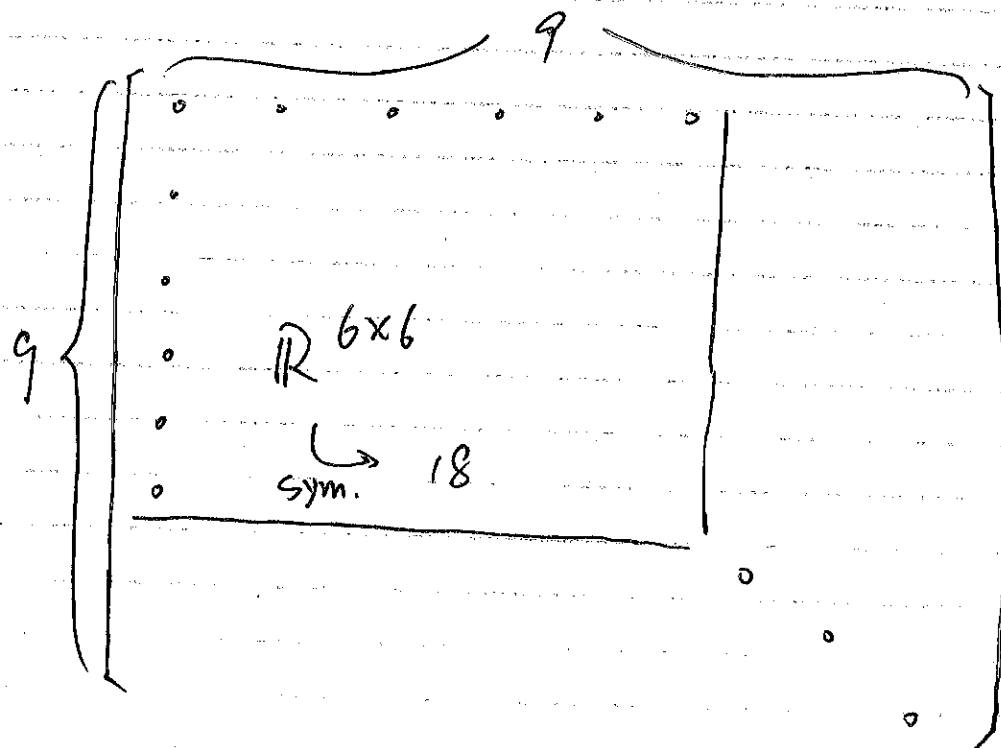
↳ compatibility condition

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0$$

↳ biharmonic eqn.

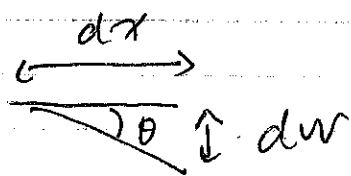
$$\Rightarrow \nabla^2(\nabla^2\phi) = 0$$

$$81 \rightarrow 21$$



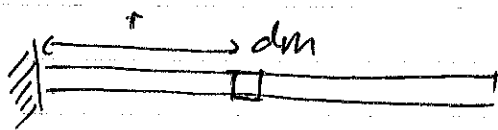
Review of Euler-Bernoulli Beam theory

- ① plane strain
- ② N.A.
- ③ small deformation
- ④ plane strain \perp N.A.
remain \perp

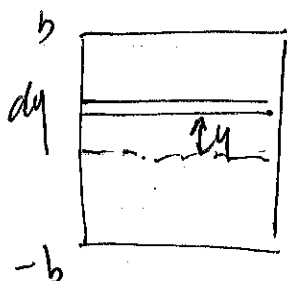


$$\tan \theta = \frac{dw}{dx} \sim \theta$$

$$K = \frac{d\theta}{dx} = \frac{\text{moment}}{\text{resistance to bending}}$$



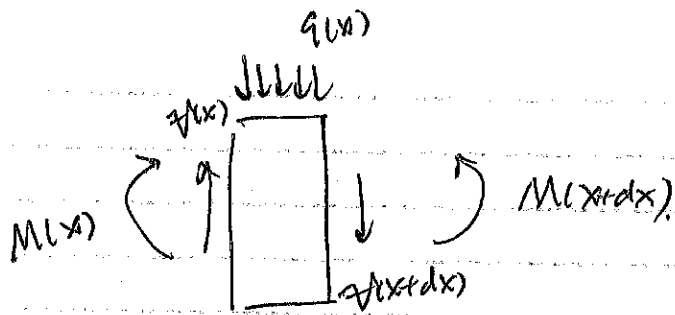
$$I = \int r^2 dm$$



$$E \int_{-b}^b y^2 dy \quad \text{area moment of inertia}$$

$$EI_z = \frac{2Eb^3}{3}$$

$$K = \frac{M}{EI_z} = \frac{d^2w}{dx^2} \dots \textcircled{1}$$



$$q(x) dx + V(x+dx) - V(x) = 0$$

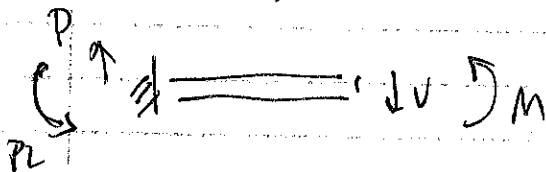
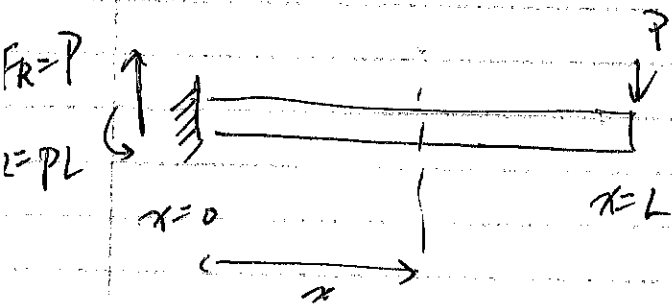
$$q(x) = \frac{dV(x)}{dx} \quad \dots (2)$$

$$M(x) + V(x) \frac{dx}{2} + V(x+dx) \frac{dx}{2} = M(x+dx)$$

$$V(x) = \frac{dM(x)}{dx} \quad \dots (3)$$

$$EI \frac{d^4 w}{dx^4} = -q(x)$$

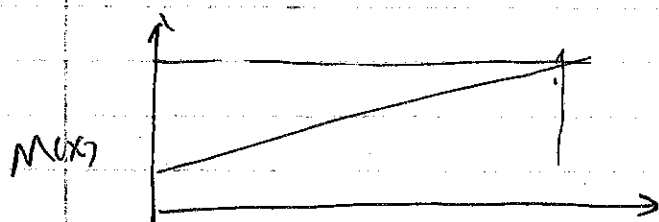
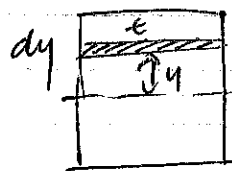
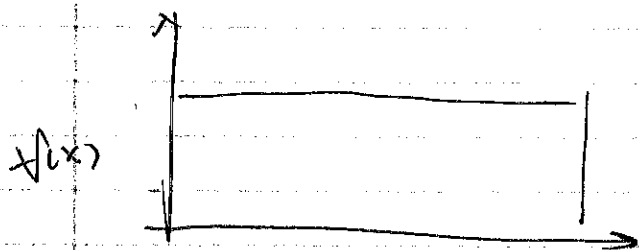
Examples:



$$V(x) = P$$

$$PL + M = Px$$

$$M = P(x-L)$$



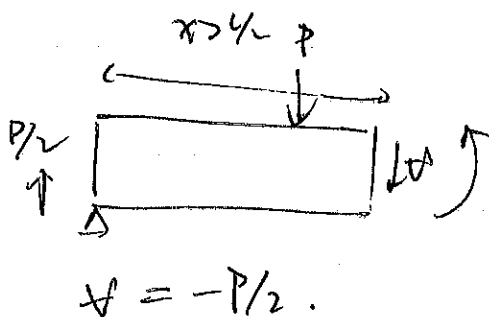
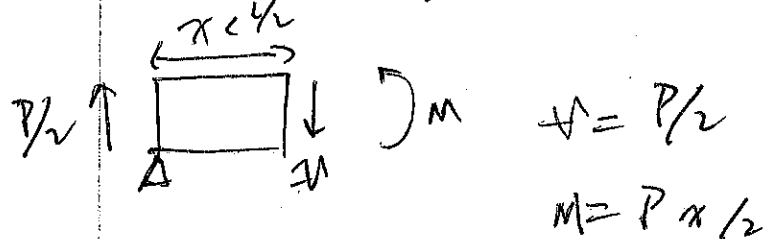
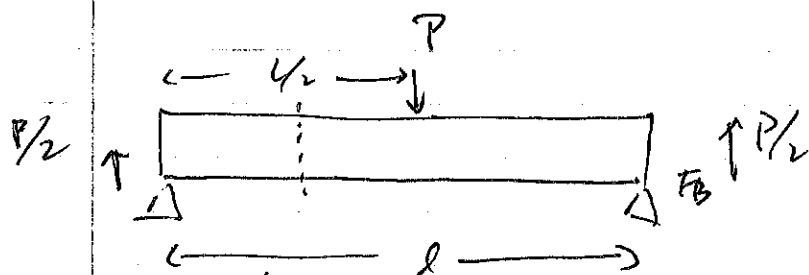
$$M(x) = \int_{-b}^b y \sigma_{xx}(x, y) t dy.$$

$$\sigma_{xx} = \frac{-M y}{I_z}$$

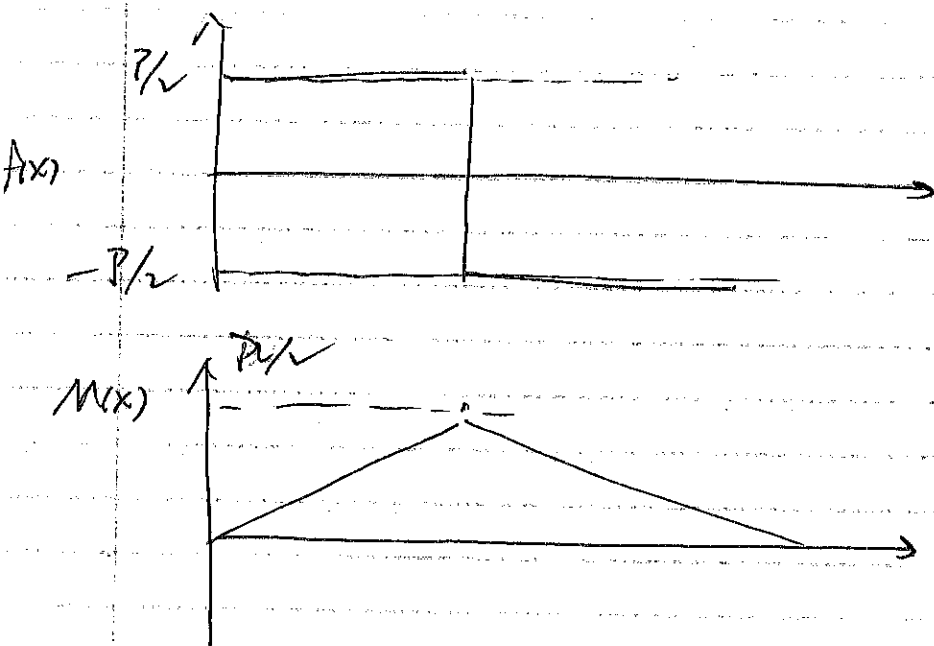
$$h(x) = \int_{-b}^b \sigma_{xy}(x, y) t dy.$$

$$\bar{y}_{xy} = \frac{3 h(x)}{2A} \left[1 - \left(\frac{y}{b} \right)^2 \right]$$

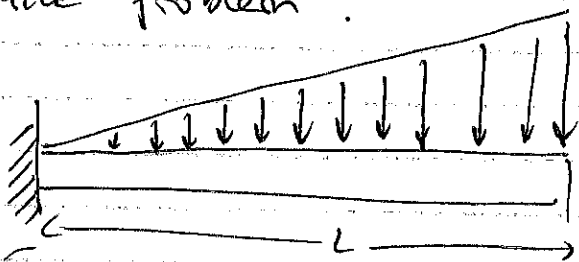
$A = 2tb$



$$P l / 2 - P x / 2 = M \quad \frac{P}{2} (l - x)$$

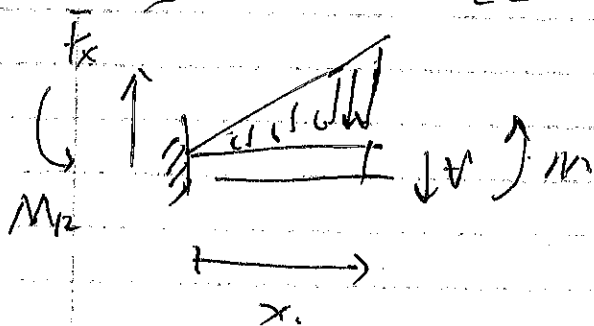


Practice Problem .



$$q(x) = \frac{kx}{L}$$

$$\int_0^L q(x) dx$$



$$F_x = \frac{kL}{2}$$

$$M_R = \int_0^L \frac{kx}{L} x dx$$

$$F_x = \frac{k(L^2 - x^2)}{2L}$$

$$= \frac{1}{L} \frac{1}{3} kx^3 \Big|_0^L$$

$$M(x) = \frac{k}{2L} (L^2 - x^2) x + \frac{k}{3L} x^3 - \frac{kL^3}{3L}$$

$$= \frac{1}{3} kL^2$$

$$= N \cdot x + \int_0^x q(x) \cdot x dx - M_R$$

Stiffness tensor

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl}$$

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{21} \\ \sigma_{31} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} & \dots & C_{16} \\ \vdots & \ddots & \vdots \\ C_{61} & \dots & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \vdots \\ \epsilon_{12} \end{bmatrix}$$

4/8/2024.

Lecture 3.

Elasticity equations.

- compatibility. $\epsilon_{ij,k\ell} + \epsilon_{k\ell,ij} - \epsilon_{ik,j\ell} - \epsilon_{j\ell,ik} = 0.$

- equilibrium. $\sigma_{ij,i} + F_i = 0$

Approach ①: (3D). \leftarrow solve displacements.

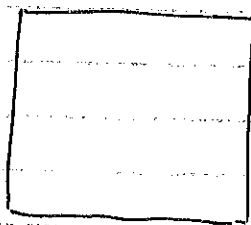
$$\sigma_{ij} = \lambda u_{k,k} \delta_{ij} + \mu (u_{i,j} + u_{j,i})$$

$$\mu u_{i,kk} + (\lambda + \mu) u_{k,ki} + F_i = 0$$

$$i = x \quad \mu \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) u_x + (\lambda + \mu) \frac{\partial}{\partial x} \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + F_x = 0$$

Approach ②: (2D).

- plane strain.



$$u_x(x, y)$$

$$u_y(x, y)$$

$$u_z = 0 \quad \Rightarrow \quad \frac{\partial}{\partial z} = 0$$

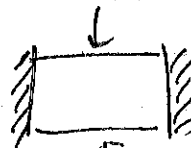
$$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{xy} \rightarrow \epsilon_{xz} = 0, \epsilon_{yz} = 0, \epsilon_{zx} = 0$$

$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy} \rightarrow \sigma_{xz} = 0, \sigma_{yz} = 0, \sigma_{zx} = 0$$

$$\epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \sigma_{yy} - \frac{\nu}{E} \sigma_{zz}$$

$$\sigma_{zz} = \nu (\sigma_{xx} + \sigma_{yy})$$

$$\epsilon_{yy} = -\frac{\nu}{E} \sigma_{xx} + \frac{1}{E} \sigma_{yy} - \frac{\nu}{E} \sigma_{zz}$$



(under plane strain assumption).

$$\begin{cases} \frac{1-\nu^2}{E} \sigma_{xx} - \frac{\nu(1+\nu)}{E} \sigma_{yy} \\ -\frac{\nu(1+\nu)}{E} \sigma_{xx} + \frac{1-\nu^2}{E} \sigma_{yy} \end{cases}$$

Equilibrium. $\begin{cases} \sigma_{xx,x} + \tau_{xy,y} + F_x = 0 \\ \sigma_{xy,x} + \sigma_{yy,y} + F_y = 0 \end{cases}$

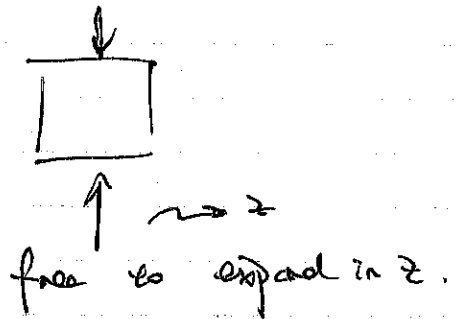
compatibility: $\epsilon_{xx,yy} + \epsilon_{yy,xx} - 2\epsilon_{xy,xy} = 0$

• plane stress.

$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}, \quad \sigma_{xz}=0, \sigma_{yz}=0, \sigma_{zx}=0.$

$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{xy}, \quad \epsilon_{xz}=0, \epsilon_{yz}=0, \epsilon_{zx} \neq 0$

$$\begin{cases} \epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \sigma_{yy} \\ \epsilon_{yy} = -\frac{\nu}{E} \sigma_{xx} + \frac{1}{E} \sigma_{yy} \\ \epsilon_{xy} = \frac{1}{2\mu} \sigma_{xy} \end{cases}$$



Kolosov's constant $K = 3 - 4\nu$ \rightarrow plane strain.

$K = \frac{3-\nu}{1+\nu} \rightarrow$ plane stress.

Ansatz: \rightarrow Any stress function, $\phi(x, y).$

$$\begin{cases} \sigma_{xx} = \phi,_{yy} \\ \sigma_{yy} = \phi,_{xx} \\ \sigma_{xy} = -\phi,_{xy} \end{cases}$$

\rightarrow equilibrium condition automatically satisfied

$$\left(\frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial y^4} + 2 \frac{\partial^2}{\partial x^2} \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0.$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0$$

$$\nabla^2 (\nabla^2 \phi) = 0$$

$$\nabla^4 \phi = 0 \quad \leftarrow \text{biharmonic eqn.}$$

Examples.

$$\phi(x,y) = \alpha x + \beta y + \delta$$

\rightarrow stresses are zero

$$\phi(x,y) = \frac{1}{2} A x^2 + \frac{1}{2} B y^2 - C x y$$

$$\rightarrow \sigma_{xx} = B$$

$$\sigma_{yy} = A$$

$$\sigma_{xy} = C$$

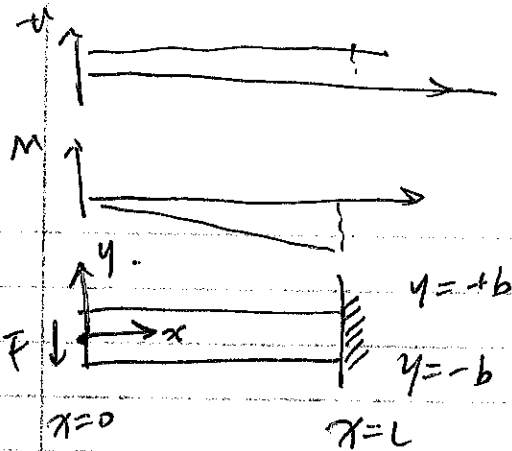
$$\left[\begin{array}{c} \leftarrow \rightarrow \sigma_0 \end{array} \right] \rightarrow \sigma_0$$

$$\phi = \frac{1}{2} \sigma_0 y^2$$



$$\phi = -\frac{1}{6} \frac{M}{E} y^3$$

$$\sigma_{xx} = -\frac{M}{I} y$$



B.V.P.

Top. Bottom. \rightarrow traction free. $\begin{cases} \sigma_{xy} = 0 \\ \sigma_{yy} = 0 \end{cases} \quad y = \pm b$

$\downarrow \uparrow$

\oint (work) $\sigma_{xx} \dots ?$

"Strong B.C."

Left side

$$\int_{-b}^b \sigma_{xy} dy = F$$

... weak B.C.s

$$\int_{-b}^b \sigma_{xx} y dy = 0$$

$$\int_{-b}^b \sigma_{xx} dy = 0$$

$x=0$

Right side

\hookrightarrow automatically satisfied $x=L$
(only for stress).

$$u_x = 0, \quad u_y = 0,$$

$x=L$ \leftarrow Strong B.C.s.

Guess. $\phi = C_1 xy^3$

all the stress field

$-3C_1 b^2 xy$

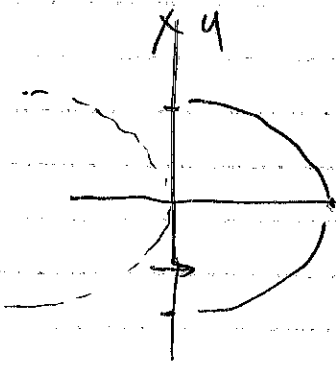
$$\begin{cases} \sigma_{xx} = 6C_1 xy \\ \sigma_{yy} = 0 \end{cases}$$

$\frac{3F}{2b^3} xy$

$\sigma_{xy} = -3C_1 y^2 \{ + 3C_1 b^2 \}$

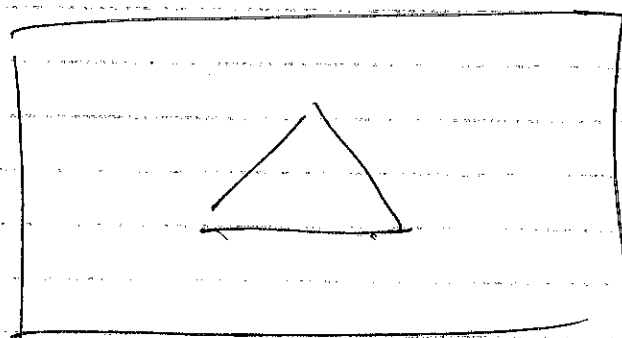
$\frac{3F}{4b^3} (b^2 - y^2)$

$\sigma_{xy} = -3C_1 b^2, \quad -y = \pm b$



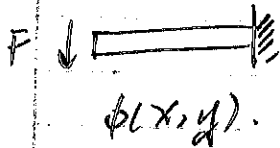
$(x=0) \int_{-b}^b \sigma_{xy} dy = F$

$C_1 = \frac{F}{4b^3}$



$\frac{I_3}{2} = 0.5994 < 0.6$

lecture 4. 4/10/2014



$\rightarrow \sigma_{xx}, \sigma_{yy}, \sigma_{xy}$

$$\epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \sigma_{yy} = \frac{3F}{2Eb^3} xy$$

$$\epsilon_{yy} = -\frac{\nu}{E} \sigma_{xx} + \frac{1}{E} \sigma_{yy} = -\frac{3F\nu}{2b^3} xy$$

$$\epsilon_{xy} = \frac{1}{2\mu} \sigma_{xy} = \frac{1+\nu}{E} \sigma_{xy} = \frac{3F(1+\nu)}{4Eb^3} (b^2 - y^2)$$

$$u_x = \int \epsilon_{xx} dx = \frac{3F}{4Eb^3} x^2 y + f(y)$$

$$u_y = \int \epsilon_{yy} dy = -\frac{3F\nu}{4Eb^3} xy^2 + g(x)$$

$$\epsilon_{xy} = \frac{1}{2} (u_{xy} + u_{yx})$$

$$2. \frac{3F(1+\nu)}{4Eb^3} (b^2 - y^2) = \frac{3F}{4Eb^3} x^2 + f'(y) - \frac{3F\nu}{4Eb^3} y^2 + g'(x)$$

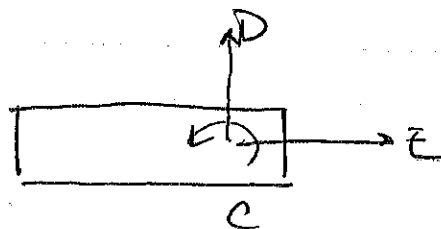
$$\underbrace{\frac{3F}{4Eb^3} x^2 + g'(x)}_{\text{function of } x} = \underbrace{\frac{3F(1+\nu)}{2Eb^3} (b^2 - y^2) + \frac{3F\nu}{4Eb^3} y^2 - f'(y)}_{\text{function of } y} = \text{const.}$$

$$g'(x) = C - \frac{3F}{4Eb^3} x^2$$

$$g(x) = Cx - \frac{F}{4Eb^3} x^3 + D$$

$$f(y) = \dots$$

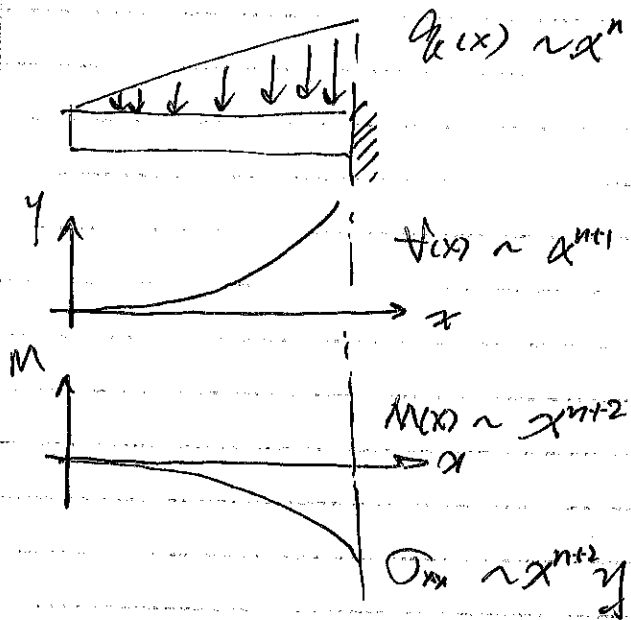
$$f(y) = -Cy + \dots + E$$



Weak B.C.s \rightarrow St. Venant's principle.

Q
Discussion on exactly
Satisfying the imposed B.C.s.

... collection term decays exponentially.



B.C.S.

$$\sigma_y(x, y=b) = -q(x)$$

$$\sigma_{yy}(x, y = -b) = 0$$

stay BC
has to satisfy

$$\phi \sim x^{n+2} y^3$$

$$\phi(x, y) = C_1 x^2 + C_2 xy + C_3 y^2 + C_4 x^3 + \dots$$

Max oder $AT5 \ll$ \hookrightarrow isothermisch

$$\nabla \phi = 0$$

B.C.S

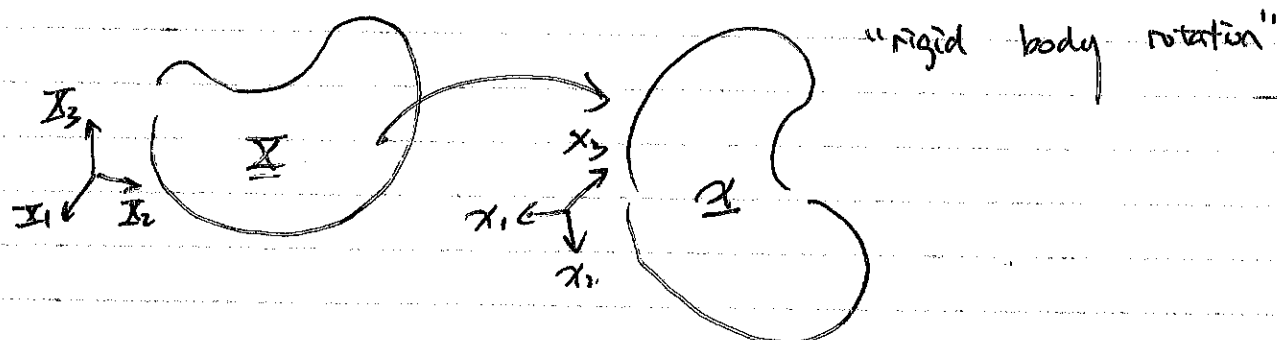
Satisfy to

determine the coeff.

$$\begin{array}{ccccccc}
 & & & & \downarrow & & \\
 & & x & & y & & 1 \\
 \hline
 & x^2 & & xy & & y^2 & \\
 x^3 & & x^2y & & xy^2 & & y^3
 \end{array}$$

Derivation of rotational tensor

Begin with the continuum potato:

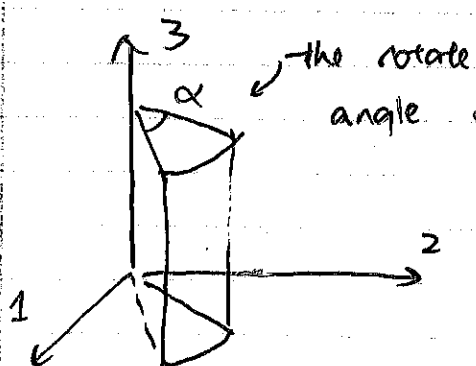


Let's assume there's no deformation in the potato, i.e., pure rigid body rotation. The original coordinate writes $\underline{X} = [X_1, X_2, X_3]^T$, and the rotated coordinate is $\underline{x} = [x_1, x_2, x_3]^T$.

Now let's assume if we just rotate the X_3 axis (or z -axis), the transformation writes

$$\begin{aligned} x_1 &= X_1 \cos \alpha - X_2 \sin \alpha, & x_2 &= X_1 \sin \alpha + X_2 \cos \alpha \\ x_3 &= X_3 \end{aligned}$$

→ it looks something like:



How we introduce the rotational tensor

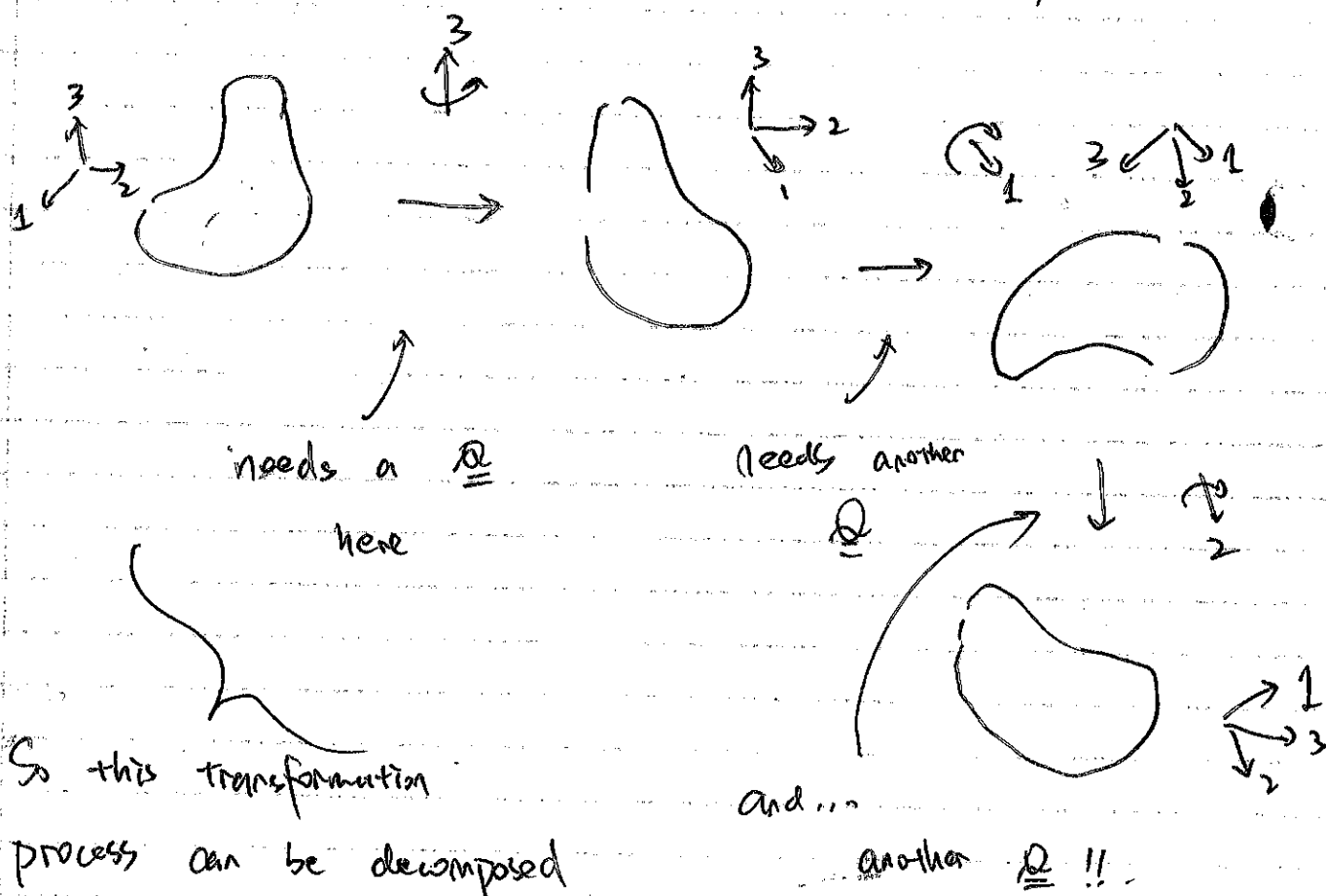
Now, this process can be written as $\underline{x} = \underline{Q} \cdot \underline{X}$

this \underline{Q} is

$$\begin{bmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

LINEAR ALGEBRA

From \underline{X} to \underline{x} if we just rotate along the 3-axis, we need 1 \underline{Q} tensor, if we want to rotate for both 1, 2, 3 axes then we will need a bunch of \underline{Q} tensors to represent the transformations, something like



So this transformation process can be decomposed

into a bunch of \underline{Q} 's.

→ that's why you'll need to multiply by many \underline{Q} s if you want to rotate around many directions.

← that example just illustrates how we rotate
a vector $\underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \rightarrow$ or x_i .

if we want to rotate a tensor,

$$\underline{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \rightarrow \text{or } A_{ij}, \text{ (indexial notation)}$$

we'll need to rotate both the two axes,

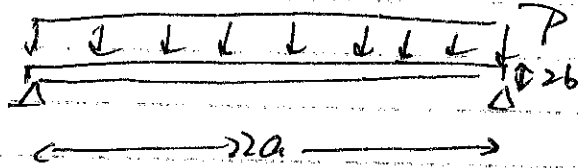
we then need two transformation tensors,

because a second-order tensor can be think
of the out. product of 2 vectors (axes in
our example). \rightarrow So, if you want to rotate
a second-order tensor, you'll need 2 Qs.

Similarly, if you want to rotate a fourth
order tensor, you then need 4 Qs to
transform (rotate) the 4 axes in that tensor

Problem Session #2

Problem 1 using Airy stress function.



$$q(x) \propto x^0$$

$$V(x) \propto x^1$$

$$\phi(x, y) = C_1 x^2 \dots C_{18}$$

$$M(x) \propto x^2$$

$$t_1 = \sigma_{yy}(x, y = \pm b) = S_1 x^3 + S_2 x^2 \dots$$

$$\sigma_{xx} \propto M(x), y$$

$$\phi \propto x^{n+5}$$

t_1
 t_2
 t_3
 t_4

"
P

4 strong B.C.s \rightarrow 16 coefficients.

$$F_{xx} = \int_{-b}^b \sigma_{xx} dy = 0$$

Weak B.C.s

$$F_{y1} = \int_{-b}^b \sigma_{xy} dy = -pa$$

$$M = \int_{-b}^b \sigma_{xx} y dy = 0$$

\rightarrow 6 equations

\downarrow
6 coefficients

$$\nabla^4 \phi = 0$$

\rightarrow 3 eqns

Obtain the exact form of ϕ

↓

get $\sigma_{xx}, \sigma_{yy}, \dots$

$$u_x = \int \epsilon_{xx} dx + f(y)$$

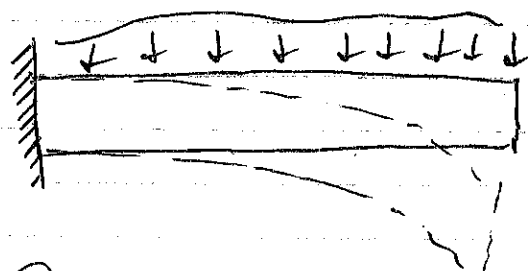
$$u_y = \int \epsilon_{yy} dy + f(x)$$

$$\epsilon_{xy} = \frac{1}{2} \left[\frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \right]$$

↓

$$F(x) = G(y) = C \quad (\text{separate variables}).$$

$$C_x + D, \\ C_y + E$$



$$a) x=0, \forall y.$$

$$u_x=0, u_y=0$$

"not satisfied"

Weak B.C.s

$$x=0, y=0$$

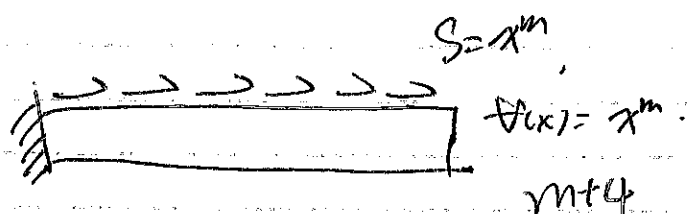
$$\frac{\partial u_y}{\partial x} = 0 \quad \leftarrow \text{horizontal.}$$

$$\Rightarrow \frac{\partial u_x}{\partial y} = 0$$

$$\int u_x dy = 0$$

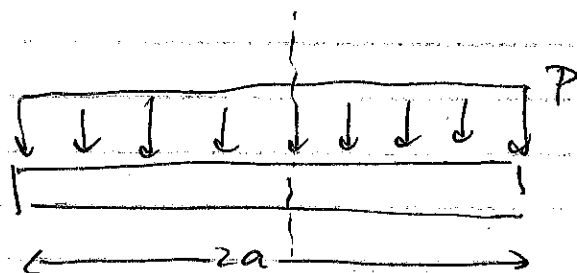
$$\int u_y dx = 0$$

$$\text{moment. } \int u_{xy} dy = 0$$



den 2

Using Fourier Series.



$$f(x) = a_0 + \underbrace{\sum_{n=1}^N a_n \cos(\lambda_n x)}_{\text{even func.}} + \underbrace{\sum_{n=1}^N b_n \sin(\lambda_n x)}_{\text{odd func.}}$$

$$\lambda_n = \frac{2n\pi}{2a} = \frac{n\pi}{a}$$

$$P = \sum_{n=1}^N a_n \cos(\lambda_n x)$$

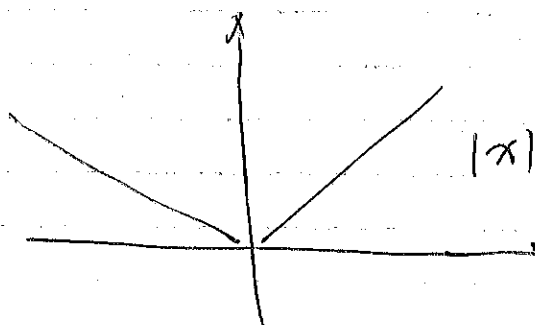
$$\lambda_n = \frac{(2n-1)\pi}{2a}$$

$$a_n = \frac{2}{2a} \int_{-a}^a P \cdot \cos(\lambda_n x) dx$$

Integration to

determine the

coefficients



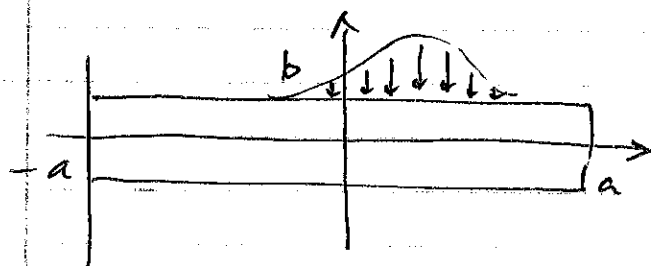
4/15/2024. Lecture 5

Stress function. $\phi(x, y)$. (Recap).

$$\left\{ \begin{aligned} \sigma_{xx} &= \phi,_{yy} \\ \sigma_{yy} &= \phi,_{xx} \\ \sigma_{xy} &= -\phi,_{xy} \end{aligned} \right.$$

$$\rightarrow \nabla^4 \phi = 0$$

$$\sigma_{xy} = -\phi,_{xy}$$



trial $\phi(x, y)$ polynomials.

$$\sigma_{yy}(x, y=\pm b) = \pm t_{y\pm}(x).$$

$$\sigma_{xy}(x, y=\pm b) = \pm t_{x\pm}(x)$$

trial soln: $\phi(x, y) = e^{\alpha x} e^{\beta y}$

... separation of var.

$$e^{ikx} = \cos kx + i \sin kx$$

$$\nabla^2 \phi = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) (e^{\alpha x} e^{\beta y}) = (\alpha^2 + \beta^2) (e^{\alpha x} e^{\beta y}).$$

$$\nabla^2 \phi = 0 \quad \dots \quad \text{harmonic eqn} \rightarrow \alpha^2 + \beta^2 = 0$$

General form of the soln: $\hookrightarrow \alpha^2 = -\beta^2$

$$\phi(x, y) = e^{\pm i\alpha x} e^{\pm \alpha y} \quad \leftarrow \alpha = \pm i\beta.$$

if not harmonic.

$$\nabla^2(\nabla^2\phi) = 0$$

$\phi(x, y)$

$$e^{i\lambda x} e^{\lambda y}, e^{i\lambda x} e^{-\lambda y}, e^{i\lambda x} y e^{\lambda y}, e^{i\lambda x} y e^{-\lambda y}$$

general expression for ϕ .

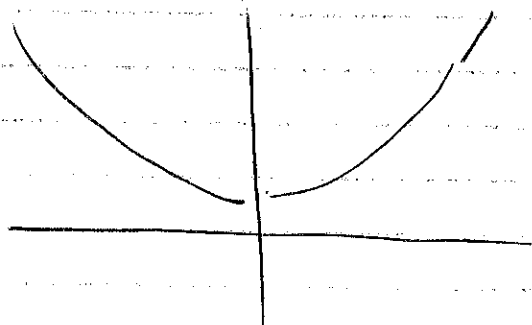
$$\phi(x, y) = e^{i\lambda x} \left[(A + C_1 y) e^{\lambda y} + (C_2 + C_4 y) e^{-\lambda y} \right]$$

$$\cosh y = \frac{e^{\lambda y} + e^{-\lambda y}}{2}$$

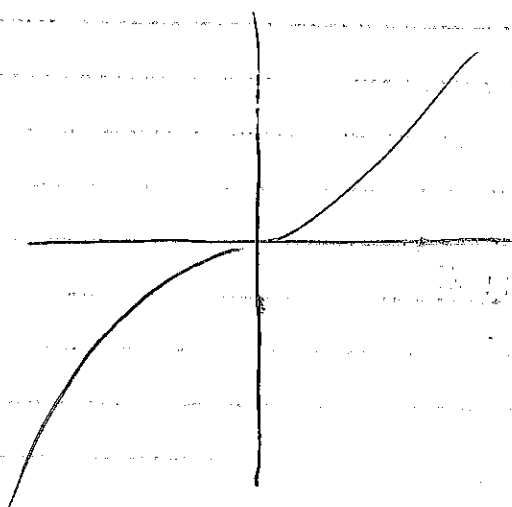
$$\sinh y = \frac{e^{\lambda y} - e^{-\lambda y}}{2}$$

$$\cos kx = \frac{e^{ikx} + e^{-ikx}}{2}$$

$$\sin kx = \frac{e^{ikx} - e^{-ikx}}{2i}$$



$\cosh y$



$\sinh y$

even func. of x .
(prob. even w.r.t. x).

$$\phi(x, y) = \cos \lambda x \left[\underbrace{Ae^{\lambda y}}_{\sin \lambda x} \quad \underbrace{Be^{\lambda y}}_{\sin \lambda x} \quad \underbrace{Ce^{-\lambda y}}_{\sin \lambda x} \quad \underbrace{De^{-\lambda y}}_{\sin \lambda x} \right]$$

$$+ B'y \cosh \lambda y + D'y \sinh \lambda y$$

$$A' \cosh \lambda y + C' \sinh \lambda y$$

$$= \frac{A'}{2}(e^{\lambda y} + e^{-\lambda y}) + \frac{C'}{2}(e^{\lambda y} - e^{-\lambda y})$$

$$= \frac{A'+C'}{2} e^{\lambda y} + \frac{A'-C'}{2} e^{-\lambda y}$$

(try to group them...)

$$\phi(x, y) = \cos \lambda x [A' \cosh \lambda y + D'y \sinh \lambda y]$$

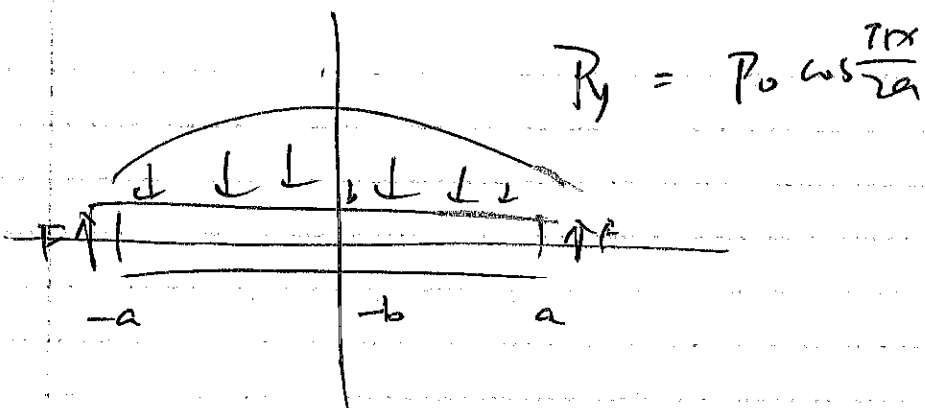
even in both x and y .

$$\cos \lambda x [B'y \cosh \lambda y + C' \sinh \lambda y]$$

even in x ,
odd in y .

$$\sin \lambda x [\dots]$$

$$\sin \lambda x [\dots]$$



B.C. $\left\{ \begin{aligned} \sigma_{yy}(x, y = \pm b) &= -p_0 \cos \frac{\pi x}{2a} \end{aligned} \right.$

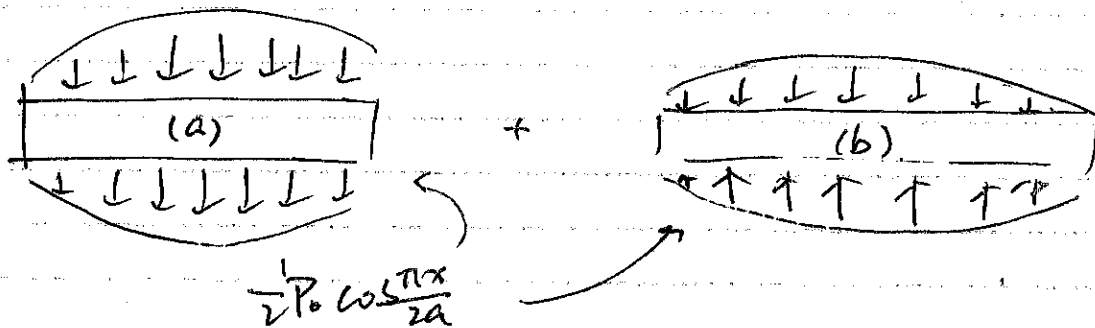
$\sigma_{yy}(x, y = -b) = 0.$

$\sigma_{xy}(x, y = \pm b) = 0$

$\sigma_{xy}(x, y = -b) = 0$

find c_1, c_2, c_3, c_4 (with $\lambda = \frac{\pi}{2a}$)

... principles of superposition.



σ_{yy} even in x ,
odd in y .

σ_{yy} even in x
even in y .

ϕ even in x ,
odd in y . σ_{xy} odd x ,
even y .

ϕ even in x ,
even in y .

σ_{xx} even in x

$$(a). \phi = \cos \lambda x [B y \cosh \lambda y + C \sinh y]$$

$$\text{B.C. } \sigma_{yy}(x, y=b) = -\frac{1}{2} P_0 \cos \frac{\pi x}{2a}$$

$$\sigma_{xy}(x, y=b) = 0$$

$$\lambda = \frac{\pi}{2a}$$

$$\cosh \lambda x$$

$$\sigma_{yy} = -\lambda^2 \cos \lambda x [\dots]$$

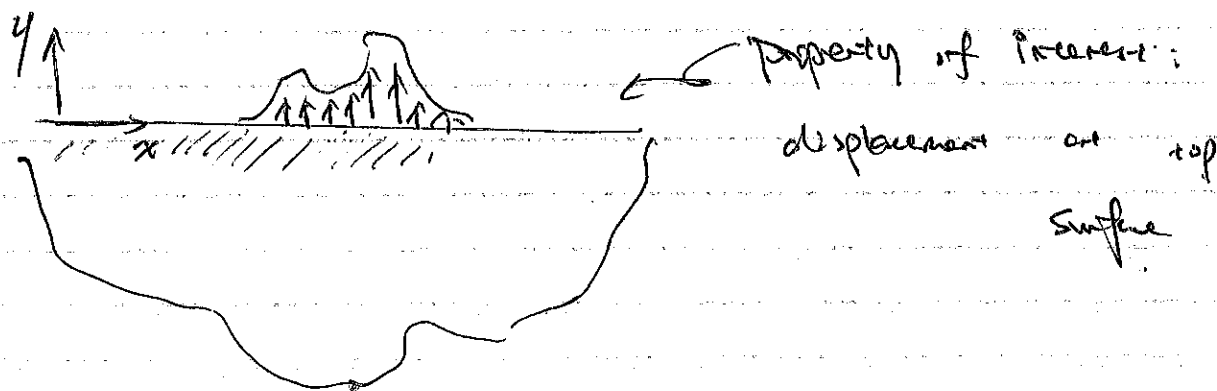
$$\sigma_{xy} = \dots$$

$$\text{plug in } y=b$$

Lecture 6

4/17/2024.

Elastic half space



① Euler-Bernoulli beam theory.

$$w(x) \propto \frac{1}{I}$$

$$V(x) \propto \sigma_{xy}(x) \propto \frac{1}{I}$$

$$M(x) \propto \sigma_{xx}(x) \propto \frac{1}{I}$$

② Airy stress function approach $\dots \phi$

$$\nabla^4 \phi = 0$$

$$\sigma_{xx} = \phi_{,yy}$$

$$\sigma_{yy} = \phi_{,xx}$$

$$\sigma_{xy} = -\phi_{,xy}$$

$$v \rightarrow \xi \rightarrow u$$

Find my displacement at (on surface) due to a force at x' .

$$u(x, x') = \underbrace{T(x, x')}_{\downarrow} T_y(x')$$

$$u(x) = \int_{\Omega_x} u(x, x') dx' = \int_{\Omega_x} G_s(x - x') T_y(x') dx'$$

$i \in \{x, y\}$.

$$u_i(x) = \int_{\Omega_x} G_{sij}(x - x') T_j(x') dx'$$

\downarrow

if we just replace by e^{-ikx}

\downarrow

we then get into Fourier trans.

$$T_y(x) = e^{ikx}$$

$$u_y(x) = \int_{-\infty}^{\infty} G_s(x - x') e^{ikx'} dx'$$

$$x'' = x - x' \rightarrow dx' = -dx''$$

$$u_y(x) = \int_{-\infty}^{\infty} G_s(x'') e^{ikx} \cdot e^{-ikx''} (-dx'')$$

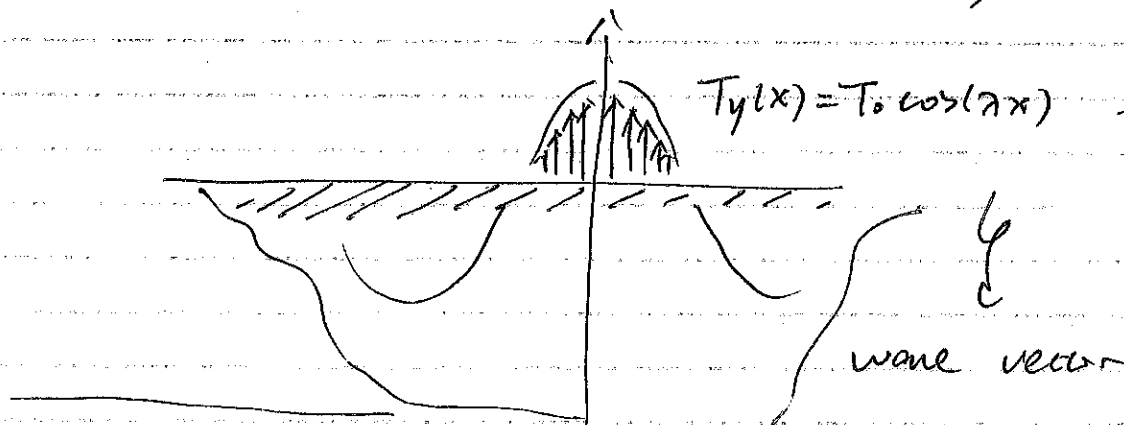
$$= e^{ikx} \int_{-\infty}^{\infty} \underbrace{G_s(x'') e^{-ikx''}}_{\text{Fourier trans. of } G_s(x)} dx''$$

$$u_y(x) = G_L(1/2) T_y(x).$$

or

$$T_0 \cos(kx)$$

$$G_s \text{ set: } G_{sxx}, G_{sxy}, G_{syx}, G_{syy}$$



$$\text{B.C.s: } \sigma_{yy}(y=0, x) = T_y(x).$$

$$\sigma_{xy}(y=0, x) = 0$$

Stress function:

$$\phi(x, y) = \cos kx [A + B y] e^{\gamma y}$$

$$\sigma_{yy} = \phi_{,xx} = -k^2 \cos kx [A + B y] e^{\gamma y} \quad \text{reject } e^{-\gamma y}.$$

$$\sigma_{xy} = -\phi_{,xy}$$

$$\lim_{y \rightarrow -\infty} e^{-\gamma y} \rightarrow \infty$$

$$= k \sin kx [A \gamma + B + B \gamma y] e^{\gamma y}.$$

$$B = -A \gamma$$

$$A = -\frac{T_0}{k^2}$$

$$B = T_0 / k$$

$$\sigma_{xx} = \phi_{,yy} = \cos kx [A k^2 + 2B \gamma + B k^2 y] e^{\gamma y}$$

$$\sigma_{xx} = T_0 \cos kx (1 + \gamma y) e^{\gamma y}$$

$$\sigma_{yy} = T_0 \cos kx (1 - \gamma y) e^{\gamma y}$$

$$\sigma_{xy} = T_0 k \sin kx y e^{\gamma y}$$

Under plane-strain assumption

$$\Sigma_{xx} = \frac{1-\nu^2}{E} \sigma_{xx} - \frac{\nu(1+\nu)}{E} \sigma_{yy}$$

$$\Sigma_{yy} = -\frac{\nu(1+\nu)}{E} \sigma_{xx} + \frac{1-\nu^2}{E} \sigma_{yy}$$

$$\Sigma_{xy} = \frac{\sigma_{xy}}{2\mu} = \frac{1+\nu}{E} \sigma_{xy}$$

$$u_x = \int \Sigma_{xx} dx = \text{~~~~~} + C(y)$$

$$u_y = \int \Sigma_{yy} dy = \text{~~~~~} + D(x)$$

$$\frac{1}{2}(u_{x,y} + u_{y,x}) = \Sigma_{xy} \rightarrow \begin{matrix} C(y) = C \\ D(x) = D \end{matrix}$$

We can then obtain forms

for u_x & u_y :

$$u_x(x, y) = \frac{T_0}{\pi E} \sin \lambda x [(1-\nu-2\nu^2) + (1+\nu)\lambda y] e^{\lambda y} + C$$

$$u_y(x, y) = \frac{T_0}{\pi E} \cos \lambda x [(2-2\nu^2) - (1+\nu)\lambda y] e^{\lambda y} + D$$

$$u_x(x, y=0) = \tilde{u}_x(x) = \frac{T_0}{\pi E} \sin \lambda x (1-\nu-2\nu^2)$$

$$u_y(x, y=0) = \tilde{u}_y(x) = \frac{T_0}{\pi E} \cos \lambda x (2-2\nu^2)$$

$$\hat{u}_y(x) = \frac{T_y(x)(1-\nu^2)}{kE}$$

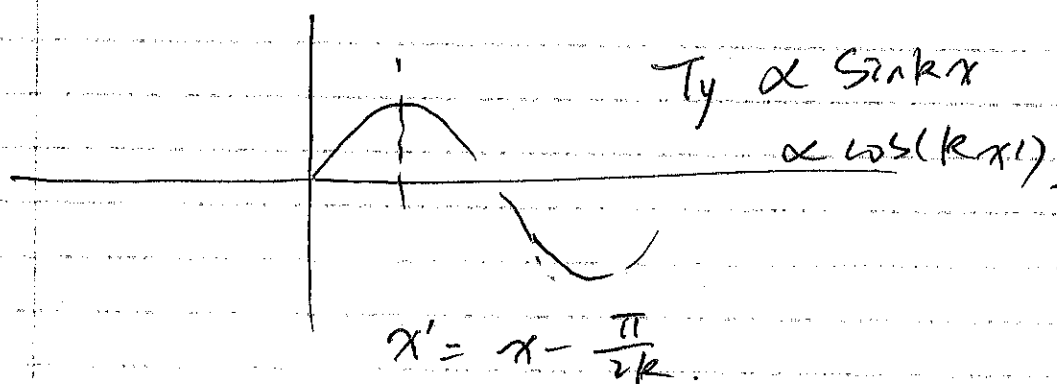
$$\hat{G}_{sy}(k) = \frac{2(1-\nu^2)}{kE}$$

↳ can be replaced by $2\mu(1+\nu)$

$$= \frac{1-\nu}{k\mu}$$

$$\hookrightarrow \frac{1-\nu}{|k|\mu}$$

↳ the positiveness does not really matter here



$$T_y(x) = e^{ikx} = \cos kx + i \sin kx$$

$$\hat{u}_y(x) = T_y(x) \frac{1-\nu}{|k|\mu}$$

where:

$$\mathcal{F}^{-1}\left[\frac{1}{|k|}\right] = \frac{-\log(x)}{\pi}$$

$$G_{sy}(x) = \mathcal{F}^{-1}\left[\frac{1}{|k|}\right] \frac{1-\nu}{\mu}$$

$$G_{\text{sys}}(x) = \frac{(1-v)}{\pi\mu} - \log(x)$$

$$K = 3 - 4v$$

$$G_{\text{sys}}(x) = - \frac{K+1}{4\pi\mu} \log(x)$$

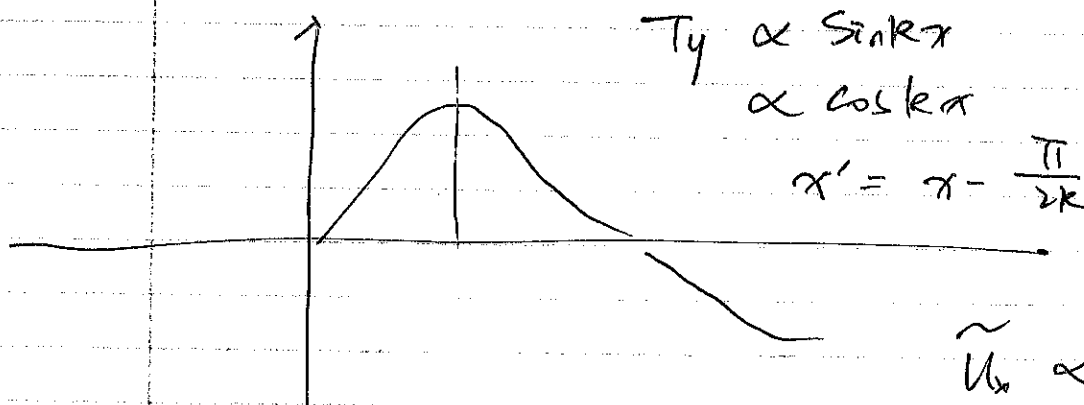
$$\tilde{u}_x = \frac{T_0 \sin \lambda x}{\lambda E} (1-v-2v^2)$$

$$= \frac{T_0 \sin \lambda x (1+v)(1-2v)}{\lambda 2\mu (1+v)}$$

$$= \frac{T_0 \sin \lambda x (1-2v)}{2\mu \lambda}$$

loading of $\cos \lambda x$

k & λ 's are interchangeable



$$x' = x - \frac{\pi}{2k}$$

$$\tilde{u}_x \propto \sin(kx - \frac{\pi}{2})$$

$$T_y = e^{ikx} = \cos kx + i \sin kx$$

$$\leftarrow = \propto - \cos kx$$

$$\tilde{u}_x = A [\sin kx - i \cos kx]$$

$$\tilde{U}_x = -iA \left[\cos kx - \frac{1}{i} \sin kx \right]$$

$$-i^{-1} = i$$

$$\tilde{U}_x = -iA e^{ikx}$$

$$= \left[-i(1-2\nu) / 2\mu k \right] e^{ikx}$$

$$\hat{U}_{sxy}(k)$$

$$F^{-1} [\hat{G}_{sxy}(k)] = \frac{-(1-2\nu)}{2\mu} F^{-1} \left[\frac{i}{k} \right]$$

are strain.

$$K = 3 - 4\nu \rightarrow \frac{K-1}{2} = 1-2\nu$$

$$= \frac{-(K-1)}{4\mu} \cdot \frac{\sin(x)}{2}$$

		Fourier	Real space
y-loading	G_{syy}	$\frac{K+1}{4\mu} \frac{1}{ k }$	$-\frac{K+1}{4\pi\mu} \log(x)$
	G_{sxy}	$\frac{-(K-1)}{4\mu} \left(\frac{i}{k} \right)$	$-\frac{(K-1)}{8\mu} \sin(x)$
x-loading	G_{sxx}	$\frac{K+1}{4\mu} \frac{1}{ k }$	$-\frac{K+1}{4\pi\mu} \log(x)$
	G_{syx}	$\frac{K+1}{4\mu} \left(\frac{i}{k} \right)$	$-\frac{(K-1)}{8\mu} \sin(x)$

$$T(x) = T_y(x) \hat{e}_y + T_x(x) \hat{e}_x$$

$$\tilde{u}_x = \int_{-\infty}^{\infty} -\frac{k+1}{4\pi\mu} \log(x-x') T_x(x') dx'$$

$$+ \int_{-\infty}^{\infty} \frac{k+1}{8\mu} \operatorname{sgn}(x-x') T_y(x') dx'$$

Problem Session #3

Generalized Airy Stress function.

$$\phi(x,y) = \sum_i C_i \phi_i(x,y) \quad \left\{ \begin{array}{l} \text{not universal} \\ \text{unstable} \end{array} \right.$$

$\nabla^4 \phi = 0$ not guaranteed

$$\phi(x,y) = e^{\alpha x} e^{\beta y}$$

$$\nabla^2 \phi = 0$$

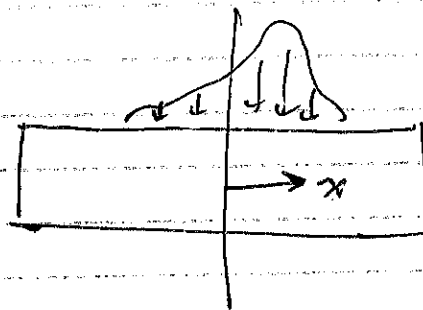
$$= e^{i\lambda x} e^{\lambda y} \quad (1)$$

$$\alpha = \pm i\beta \rightarrow \lambda$$

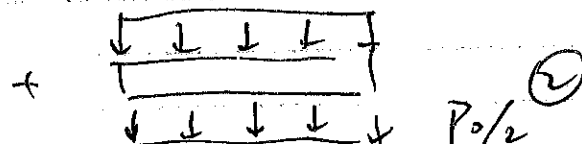
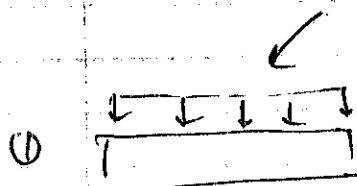
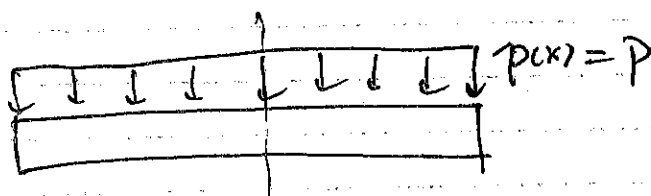
$$e^{i\lambda x} e^{-\lambda y} \quad (2)$$

$$e^{i\lambda x} y e^{\lambda y} \quad (3)$$

$$e^{i\lambda x} y e^{-\lambda y} \quad (4)$$



$$\phi(x,y) = e^{i\lambda x} [(C_1 + C_2 y) e^{\lambda y} + (C_3 + C_4 y) e^{-\lambda y}]$$



Problem ①. σ_{yy} $\begin{matrix} x \\ \text{even} \end{matrix}$ $\begin{matrix} y \\ \text{even} \end{matrix}$.
 ϕ

Problem ②. σ_{yy} $\begin{matrix} x \\ \text{even} \end{matrix}$ $\begin{matrix} y \\ \text{odd} \end{matrix}$.

② expand the loading as Fourier series.

$$\phi(x) = \sum_{n=1}^{\infty} A_n \cos(\lambda_n x)$$

$$\hookrightarrow \lambda_n = \frac{(2n-1)\pi}{2a}$$

③ B.C.s: $\sigma_{yy}(x, y=b) - P_0/2 = -\frac{1}{2} \sum_{n=1}^{\infty} q_n \cos(\lambda_n x)$

$$\sigma_{yx}(x, y=0) = 0$$

$$\left. \sigma_{yy} \right|_{x, y=b} = \sum_{n=1}^{\infty} -\lambda_n^2 \cos(\lambda_n x) [B_n \sinh(\lambda_n b) \dots]$$

$$-\frac{Q_n}{2} = -\lambda_n^2 \left[B_n \sinh(\lambda_n b) + C_n b \cosh(\lambda_n b) \right]$$

$$\sigma_{xx}, \sigma_{yy}, \sigma_{yx}$$

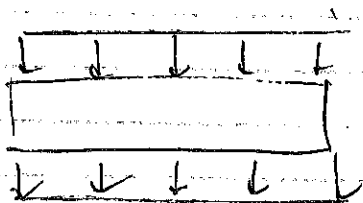


$$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{yx}$$



$$\epsilon_{xx} = u_{x,x}$$

$$\epsilon_{xx} = -\frac{1}{E'} \sigma_{xx} + \frac{\nu'}{E'} \sigma_{yy}$$



$$u_x = \int \epsilon_{xx} dx$$



odd in x ,

odd in y

$$u_x = \sum_{n=1}^{\infty} \sin(\lambda_n x) \left[D_n \sinh(\lambda_n y) + E_n y \cosh(\lambda_n y) \right]$$

$$u_y = \dots$$

$$u_{x,x} = \epsilon_{xx} = \frac{\sigma_{xx}}{E'} - \frac{\nu' \sigma_{yy}}{E'}$$

even in x , odd in y .

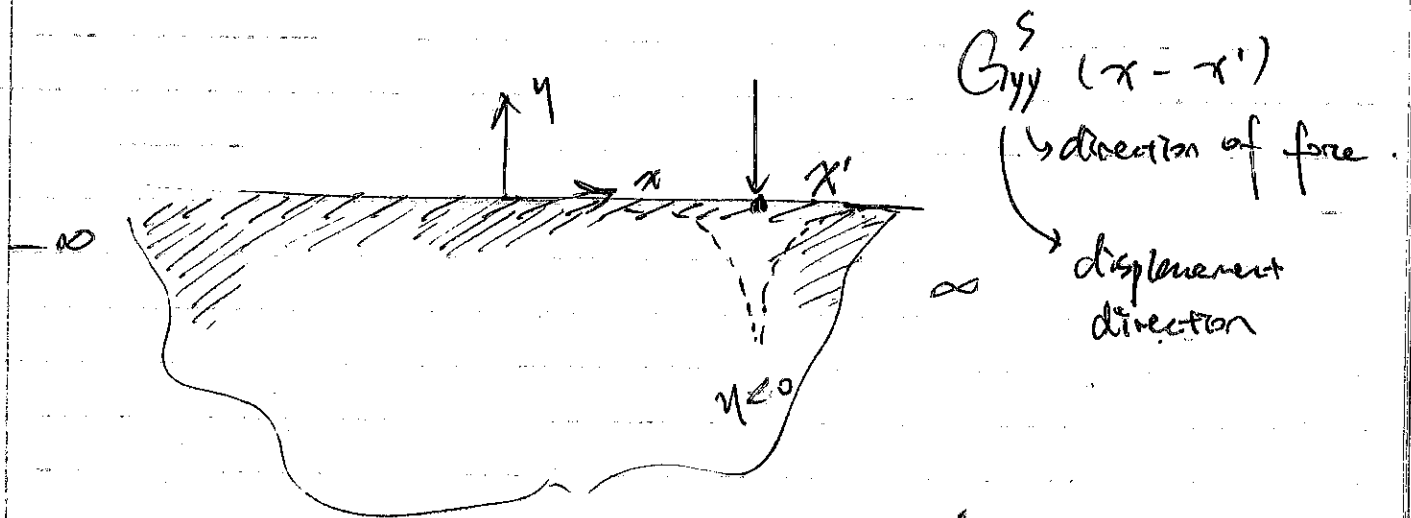
ϕ_{yy}



even in x ,

odd in y .

2) Surface Greens function



distributed loading

$$\int_{-\infty}^{\infty} G^S_{yy}(x-x') f(x') dx'$$

$$\tilde{u}_y = \int_{-\infty}^{\infty} G^S_{yy}(x-x') T_y(x') dx'$$

$$+ \int_{-\infty}^{\infty} G^S_{yx}(x-x') T_x(x') dx'$$

↳ general form of surface displacement.

Recap. apply loading e^{ikx} .

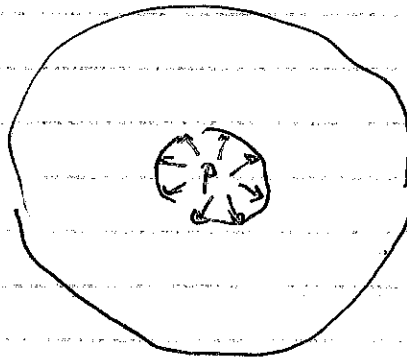
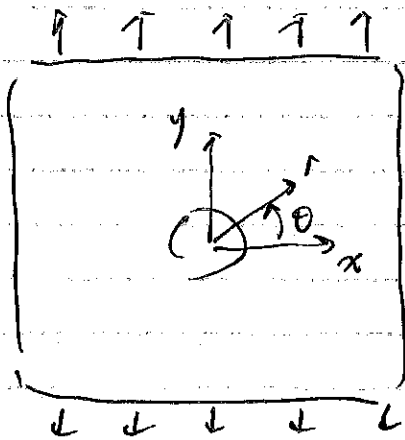
$$\tilde{u}_y = G^S_{yy}[k] \cdot e^{ikx}$$

$$F(G^S_{yy}(x))$$

Lecture 7

4/22/2024.

→ Polar Coordinates



Stress Concentration. ~ 3 .

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \rightarrow \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \arctan \frac{y}{x} \end{cases}$$

... Cartesian coordinate.

$$\sigma_{xx} = \phi_{,yy}(x,y).$$

$$\sigma_{yy} = \phi_{,xx}(x,y).$$

$$\sigma_{xy} = -\phi_{,xy}(x,y).$$

... Polar coordinate.

$$\sigma_{rr} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$\sigma_{\theta\theta} = \phi_{,rr}, \quad \sigma_{r\theta} = -\frac{1}{r} \left(\frac{\partial}{\partial r} \frac{\partial \phi}{\partial \theta} \right)$$

r, θ

$$\phi(r, \theta) = \phi(x, y).$$

$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}$$

↓ coord. trans.

$$\sigma_{rr}, \sigma_{\theta\theta}, \sigma_{r\theta}$$

$$\frac{\partial}{\partial x} \cdot \frac{\partial}{\partial y} \rightarrow \frac{\partial}{\partial r} \cdot \frac{1}{r} \frac{\partial}{\partial \theta}$$

chain rule.

Vector calculus.

$$\nabla f = \underline{e}_x f_{,x} + \underline{e}_y f_{,y}$$

gradient operator

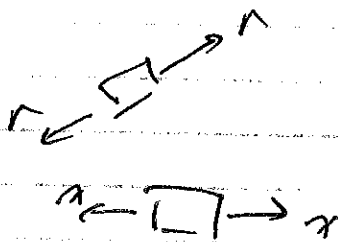
$$\nabla = \underline{e}_x \frac{\partial}{\partial x} + \underline{e}_y \frac{\partial}{\partial y}$$

$$= \underline{e}_{x'} \frac{\partial}{\partial x'} + \underline{e}_{y'} \frac{\partial}{\partial y'}$$

$$\nabla^2 = \nabla \cdot \nabla = \frac{\partial^2}{\partial x'^2} + \frac{\partial^2}{\partial y'^2}$$

$$= \frac{\partial^2}{\partial x'^2} + \frac{\partial^2}{\partial y'^2}$$

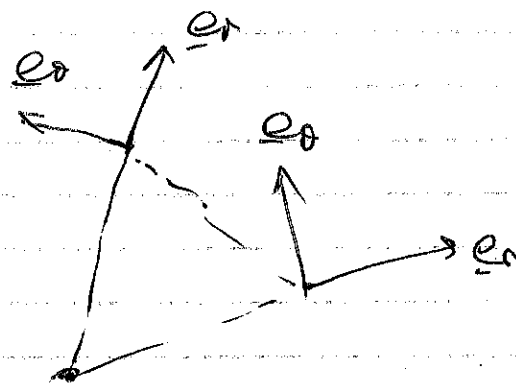
... Laplacian in polar coordinates?



ii polar coordinates.

$$\underline{\nabla} = \underline{e}_r \frac{\partial}{\partial r} + \underline{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta}$$

(grad).



Laplacian.

$$\nabla^2 = \underline{\nabla} \cdot \underline{\nabla} = \left(\underline{e}_r \frac{\partial}{\partial r} + \underline{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} \right) \cdot \left(\underline{e}_r \frac{\partial}{\partial r} + \underline{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} \right)$$

One can show that:

Your Laplacian:

$$= \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

$$\begin{cases} \frac{\partial \underline{e}_r}{\partial \theta} = \underline{e}_\theta \\ \frac{\partial \underline{e}_\theta}{\partial \theta} = -\underline{e}_r \end{cases}$$

$$\underline{\nabla} \neq \underline{\nabla} \otimes \underline{\nabla} \phi$$

Not true !!

$$\begin{cases} \frac{\partial \underline{e}_r}{\partial r} = 0 \\ \frac{\partial \underline{e}_\theta}{\partial r} = 0 \end{cases}$$

$$\underline{\nabla}^a = \underline{\nabla} \times \underline{e}_z$$

$$= \left(\underline{e}_x \frac{\partial}{\partial x} + \underline{e}_y \frac{\partial}{\partial y} \right) \times \underline{e}_z$$

$$= \left(-\underline{e}_y \frac{\partial}{\partial x} + \underline{e}_x \frac{\partial}{\partial y} \right)$$

$$\underline{\underline{\Omega}} = \underline{\underline{\nabla}}^2 \otimes \underline{\underline{\nabla}}^a \phi$$

↖ for Cartesian

in polar coordinates.

$$\underline{\underline{\nabla}}_r^a = \left(\underline{\underline{e}}_r \frac{\partial}{\partial r} + \underline{\underline{e}}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} \right) \times \underline{\underline{e}}_\theta$$

$$= \left(-\underline{\underline{e}}_\theta \frac{\partial}{\partial r} + \underline{\underline{e}}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} \right)$$

$$\underline{\underline{\nabla}}_r^a \otimes \underline{\underline{\nabla}}^a = \underline{\underline{e}}_\theta \otimes \underline{\underline{e}}_\theta \frac{\partial^2}{\partial r^2} + \dots$$

Stress function satisfies biharmonic ...

$$\nabla^4 \phi = 0$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi = 0$$

→ in polar coordinates

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) \phi = 0$$

displacement v.s. Strain

$$\epsilon_{ij} = \frac{1}{2} (u_{ij} + u_{ji}) \rightarrow \text{Cartesian}$$

$$\underline{\underline{\Sigma}} = \frac{1}{2} \left[\underline{\nabla} \otimes \underline{u} + (\underline{\nabla} \otimes \underline{u})^T \right]$$

$$\underline{u} = u_r \underline{e}_r + u_\theta \underline{e}_\theta$$

$$\left\{ \begin{array}{l} \Sigma_{rr} = \frac{\partial u_r}{\partial r} \end{array} \right.$$

$$\Sigma_{\theta\theta} = \frac{1}{r} \cdot \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r}$$

$$\Sigma_{r\theta} = \frac{1}{2} \left(\frac{1}{r} \cdot \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right)$$

Generalized Hooke's law.

$$\underline{\underline{\sigma}} = \lambda + \mu [\underline{\underline{\Sigma}}] \underline{\underline{I}} + 2\mu \underline{\underline{\Sigma}}$$

Traction force vs. Stress.

$$\underline{T}_j = \underline{\sigma}_{ij} n_i$$

$$\underline{I} = \underline{n} \cdot \underline{\underline{\sigma}}$$

$$\left\{ \begin{array}{l} T_r = \sigma_{rr} n_r + \sigma_{\theta r} n_\theta \\ T_\theta = \sigma_{r\theta} n_r + \sigma_{\theta\theta} n_\theta \end{array} \right.$$

Equilibrium Condition.

$$\sigma_{ij,j} + F_j = 0$$

$$\underline{\nabla} \cdot \underline{G} + \underline{f} = 0$$

" automatically satisfied by stee's func. approach."

PDE to be solved:

$$\nabla^4 \phi(r, \theta) = 0$$

expect $\phi(r, \theta) = \phi(r, \theta + 2\pi)$

$$\phi(r, \theta) = f(r) e^{in\theta} \quad (n=0, 1, 2, \dots)$$

$$\frac{\partial}{\partial \theta} \phi = in \phi, \quad \frac{\partial^2}{\partial \theta^2} \phi = -n^2 \phi$$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) f(r) e^{in\theta} = 0$$

Try $f(r) = r^m$

$$\frac{1}{r} \cdot \frac{\partial}{\partial r} f(r) = m r^{m-2}$$

$$\frac{\partial^2}{\partial r^2} f(r) = m(m-1) r^{m-2}$$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) r^m = (m^2 - n^2) r^{m-2}$$

deriv. replaced
by $-n^2$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) r^{m-2} = ((m-2)^2 - n^2) r^{m-4}$$

$$[(m-2)^2 - n^2] (m^2 - n^2) r^{m-4} = 0$$

... four possibilities:

$$\begin{cases} m = \pm n \\ m = 2 \pm n \end{cases}$$

$$\phi(r, \theta) = (A_{n1} r^{n+2} + A_{n2} r^{-n+2} + A_{n3} r^n + A_{n4} r^{-n})$$

$n=0$
 $n=1$ \rightarrow not four solns. $e^{in\theta}$

$$n=0 \quad m \quad 0 \quad 0 \quad 2 \quad 2$$

only 2 solns for ϕ .

$$n=1 \quad m \quad 1 \quad -1 \quad 3 \quad 1$$

Mitchell Solns.

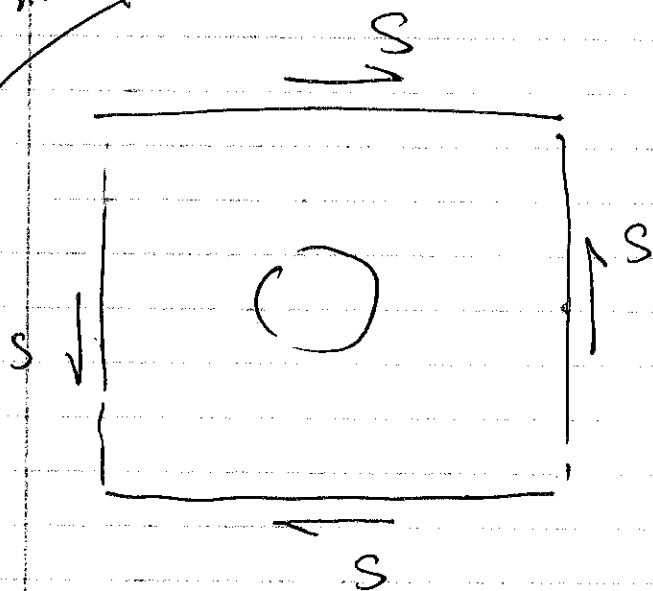
$$f_0(r) = A_{01} r^2 + A_{02} r^2 + A_{03} + A_{04}$$

... \downarrow same with tricks

$$A_{01} r^2 + A_{02} r^2 \ln r + A_{03} \ln r + A_{04}$$

take deriv. w.r.t. \downarrow parameters

Example 1



$$\begin{cases} \sigma_{xx} = \sigma_{yy} = 0 & r \rightarrow \infty \\ \sigma_{xy} = S & r \rightarrow \infty \end{cases}$$

on the hole boundary: -

$$\begin{cases} \sigma_{\theta\theta} = 0 & r = a \\ \sigma_{rr} = 0 & r = a \end{cases}$$

$$\phi = \phi^{(0)} + \phi^{(1)}$$

$$\begin{aligned} \downarrow \\ \sigma_{xy}^{(0)} &= S \\ \hookrightarrow \phi^{(0)} &= -Sxy \end{aligned}$$

in polar coordinate.

$$\begin{aligned} \phi^{(0)} &= -S r^2 \sin\theta \cos\theta \\ &= -\frac{1}{2} S r^2 \sin 2\theta \end{aligned}$$

$$\begin{cases} \sigma_{rr}^{(0)} = \frac{1}{r} \cdot \frac{\partial \phi^{(0)}}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 \phi^{(0)}}{\partial \theta^2} = S \sin 2\theta \\ \sigma_{\theta\theta}^{(0)} = -S \sin 2\theta \\ \sigma_{r\theta}^{(0)} = S \cos 2\theta \end{cases}$$

→ satisfies infinite far B.C.s

but does not satisfy hole B.C.s

we need to come up $\phi^{(1)}$, s.t.

ϕ satisfies the B.C.s but do not mess up the infinite for B.C.s.

We should pick $n=2$ to cancel the $\sin(2\theta)$ term.

$$\phi^{(1)} = (A_{01} r^4 + A_{02} + A_{03} r^2 + A_{04} r^{-2}) \sin 2\theta$$

Want to cancel these terms

terms survived. (much B.C.s)

Write the stress function:

$$\phi^{(1)} = (A + B r^2) \sin 2\theta$$

max. $\sigma_{rr} = 0$

... some vls.

$$A = S a^2, B = -\frac{1}{2} S a^2$$

$$\begin{cases} \sigma_{rr} = \left(S - \frac{4A}{r^2} - \frac{6B}{r^4} \right) \sin 2\theta \\ \sigma_{\theta\theta} = \left(S + \frac{2A}{r^2} + \frac{6B}{r^4} \right) \cos 2\theta \end{cases}$$

$$\sigma_{\theta\theta} = \left(-S + \frac{6B}{r^4} \right) \sin 2\theta$$

Problem Session 4

Polar Coordinates. & Michell Solns.

$$\phi(r, \theta) \rightarrow \text{compatibility} \quad \nabla^4 \phi(r, \theta) = 0$$

$$\phi(r, \theta) = f(r) \cdot e^{in\theta} \rightarrow \phi(r, \theta + 2\pi) = \phi(r, \theta)$$

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \quad f(r) = r^m$$

$$\nabla^2 \phi = \left(\dots - \frac{n^2}{r^2} \right) \phi \quad \hookrightarrow r^m e^{in\theta}$$

$$\nabla^4 = \nabla^2 \cdot \nabla^2 r^m e^{in\theta} = 0$$

\downarrow
Not zero everywhere

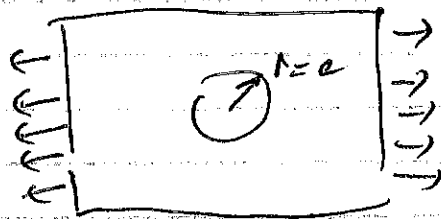
$$m = (2+n, 2-n, +n, -n)$$

... 4 unique solns.

$$\phi(r, \theta) = (A_{n1} r^{2+n} + A_{n2} r^{2-n} + A_{n3} r^n + A_{n4} r^{-n}) e^{in\theta}$$

Michell solns.

Sample



(α) No hole
uniform axial stress

(β) hole w/o loading

problem (α):

$$\sigma_{xx} = S$$

$$\sigma_{yy} = \sigma_{xy} = 0$$

[IMPORTANT]

$$\phi^{(1)}(x,y) = \frac{Sy^2}{2} = \frac{Sr^2 \sin^2 \theta}{2}$$

$$\left(\frac{1 - \cos 2\theta}{2} \right)$$

$$\phi^{(1)}(x,y) = \frac{Sr^2}{4} - \frac{Sr^2 \cos 2\theta}{4}$$

$n=0$

"base solution".

$n=2$

$$\phi^{(1)}(r,\theta) = (\cancel{A_0 r^2} + \cancel{A_0 r^2 \ln(r)} + \cancel{A_0 r^2 \ln r} + \cancel{A_0 \theta})$$

$$+ (\cancel{A_4 r^4} + \cancel{A_2} + \cancel{A_3 r^3} + \frac{A_0}{r^2}) \cos 2\theta + \dots$$

At $r=a$.

B.C.s traction free. $\sigma_{rr} = \sigma_{r\theta} = 0, \quad \forall \theta$.

$$\sigma_{rr} = C_1 \cos 2\theta - \frac{S r^2}{4} \cos 2\theta = 0$$

$$\phi^{(1)}(r, \theta) = A \ln r + \underbrace{B \theta}_{\downarrow} + C \cos 2\theta + \frac{D}{r^2} \cos 2\theta.$$

not periodic:

$$\phi^{tot} = \frac{S r^2}{4} + A \ln r + B \theta + \left(C + \frac{D}{r^2} - \frac{S r^2}{4} \right) \cos 2\theta$$

$$\sigma_{rr} = \frac{1}{r} \cdot \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$= \frac{S}{2} + \frac{A}{r^2} + 0 + \frac{1}{r} \cdot \left(\frac{-4D}{r^3} - \frac{2S r}{4} \right) \cos 2\theta$$

$$+ \frac{(1-4)}{r^2} \left(C + \frac{D}{r^2} - \frac{S r^2}{4} \right) \cos 2\theta$$

Go to Mindell's table

From Mindell's sol'n table,

$$\sigma_{rr} = \frac{S}{4}(2) + A \left(\frac{1}{r^2} \right) + 0 \left(\frac{-4C}{r^2} - \frac{4D}{r^4} + \frac{S}{2} \right) \cos 2\theta$$

Get A, B, C, D just as in class.

Given disp. B.C.s -

Say $u_r = 0$ at $r = a$ $\forall \theta$

From Michell. tab., $2\mu u_r = \frac{S}{4}(k-1)r$
 $+ A(-\frac{1}{r}) \dots$

$$u_r \Big|_{r=a} = 0$$

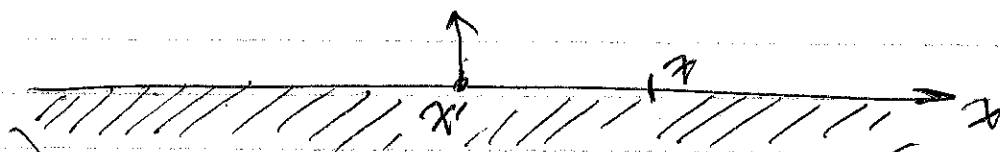
Stress concentration factor

$$\sigma_{\theta\theta} = \frac{S}{2} \left(1 + \frac{a^2}{r^2} \right) - S \cos 2\theta \left(\frac{3a^4}{r^4} + 1 \right)$$

Lecture 9

4/29/2014

Contact → Surface Green function

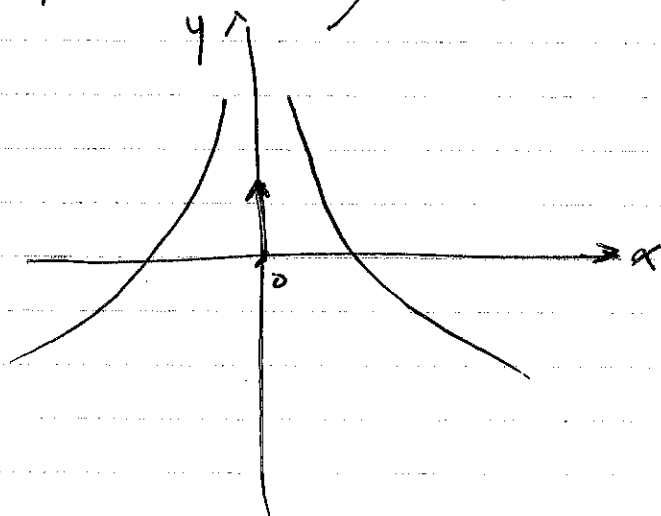


$G_{ij}(x, x')$

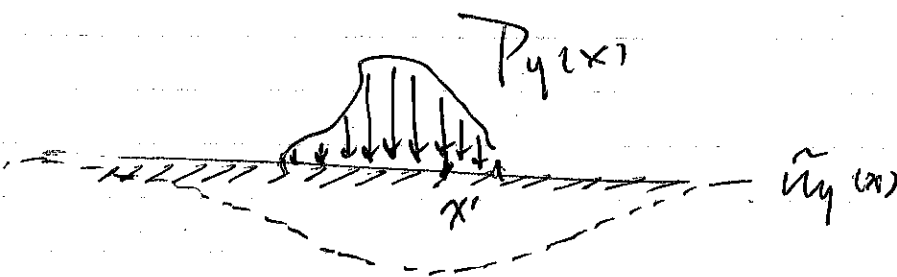
direction of the displacement

direction of the force

$$G_{yy}^s(x) = -\frac{\kappa+1}{4\pi\mu} \log|x|$$



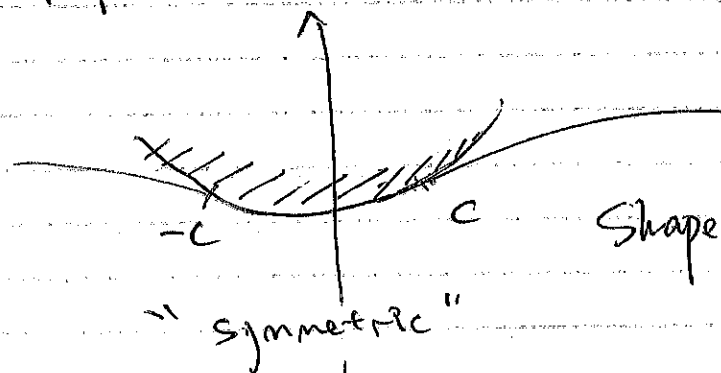
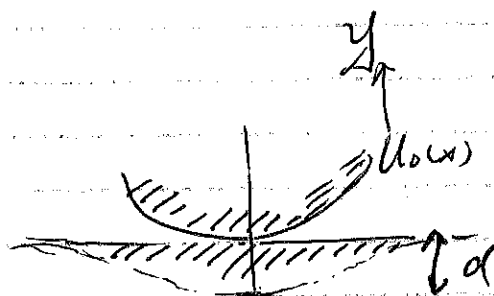
$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} -P_y(x') G_{yy}^s(x-x') dx'$$



$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} \frac{\kappa+1}{4\pi\mu} P_y(x') \log|x-x'| dx'$$

Set up frictionless contact problem

- Simplification: rigid indenter



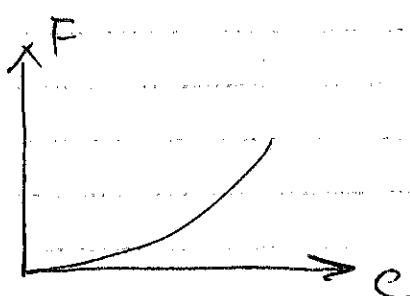
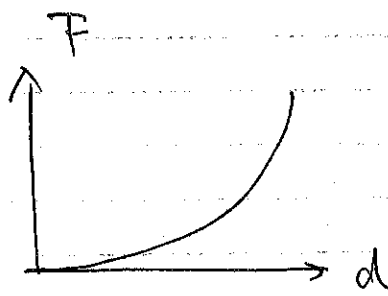
$$u_0(x) - d = \int_{-\infty}^{+\infty} P_H(x')$$

$$[-c < x < c \quad \text{(contact area)}]$$

$$\text{or } \int_{-c}^{+c} \frac{k+1}{4\pi\mu} \log|x-x'| dx'$$

"compact support"

$$\hookrightarrow F = \int_{-c}^c P_H(x') dx'$$



B.C.s ① contact area.

$$-c < x < c, \quad \left\{ \begin{array}{l} \tilde{u}_y(x) = u_0(x) - d \\ (q=0) \quad \sigma_{yy}(x) = -P_y(x) < 0 \\ \sigma_{xy}(x) = 0 \end{array} \right.$$

② gap area.

$$|x| > c, \quad q=0, \quad \left\{ \begin{array}{l} \tilde{u}_y(x) < u_0(x) - d \\ \sigma_{yy}(x) = 0 \\ \sigma_{xy}(x) = 0 \end{array} \right.$$

try to invert $u_0(x) - d$

Johnson & Barber provided some approaches

$$\frac{du_0(x)}{dx} = \int_{-c}^c P_y(x') \frac{k+1}{4\pi n} \frac{1}{x-x'} dx'$$

$$= \frac{k+1}{4\pi n} \int_{-c}^c \frac{P_y(x')}{x-x'} dx'$$

does not
have def. val.

... $(-c < x < c)$.

(*)

Eqn. (*) is a general relationship

between 2 functions.

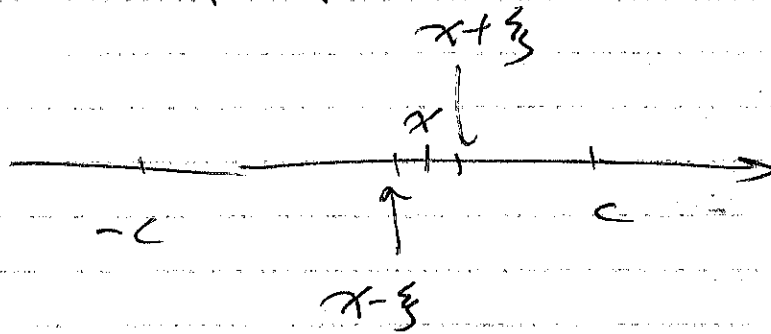
$$g(x) = \int_{-c}^c \frac{f(x')}{x-x'} dx'$$

↳ integral eqn.

"the kernel is singular" \leftarrow (implicit).



the principle value



$$\int_{-c}^c \rightarrow \int_{-c}^{x-\xi} + \int_{x+\xi}^c$$

Introducing:

$$g(x) = \frac{1}{\pi} \int_{-\infty}^{+\infty} \frac{f(x')}{x-x'} dx'$$

← Hilbert transform

"Hilbert transform is its own inverse".

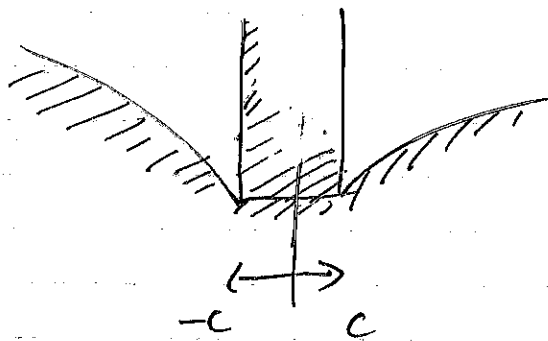
the answer is

$$f(x) = - \frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} g(x')}{x - x'} dx'$$

indenter force $\rightarrow + \frac{\dot{F}}{\pi \sqrt{c^2 - x^2}}$

Example 1

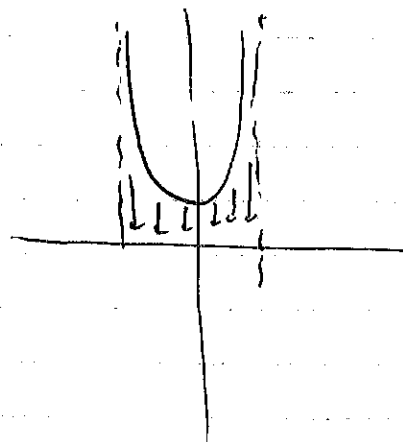
Flat punch



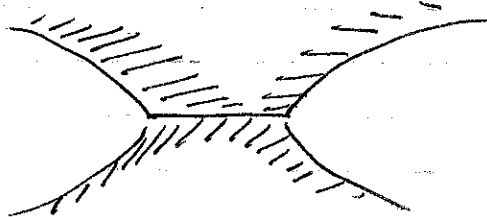
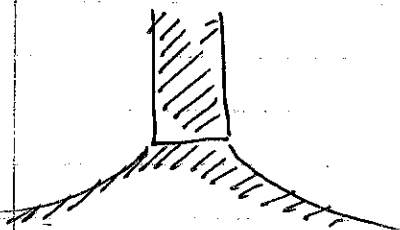
$$x = c - r \rightarrow 0$$

$$\sigma \sim \frac{1}{\sqrt{r}}$$

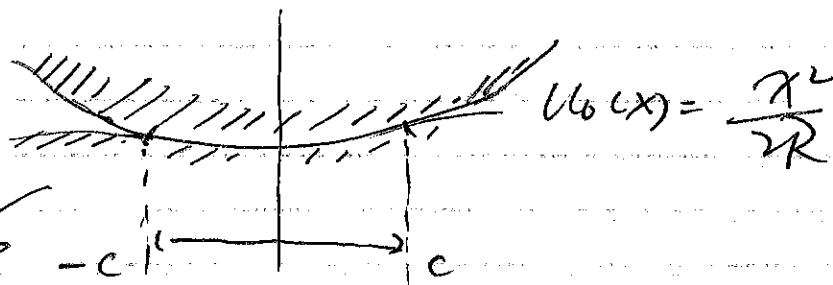
$$p_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}} \quad \text{plot it}$$



Other similar examples



Example 2 Cylindrical Punch



$$u_0(x) = \frac{x^2}{2R}$$

↳ sharp corner?
no singularities
(theoretically)

$$\frac{du_0(x)}{dx} = \frac{x}{R}$$

$$p_y(x) = \frac{4\mu}{(k+1)R} (\sqrt{c^2 - x^2})$$

$$\left\{ -\frac{c^2}{2\sqrt{c^2 - x^2}} \right\}$$

has to cancel
to avoid
singularities

$$+ \frac{F}{\pi \sqrt{c^2 - x^2}}$$

Q: what is c ? How does c depend on F ?

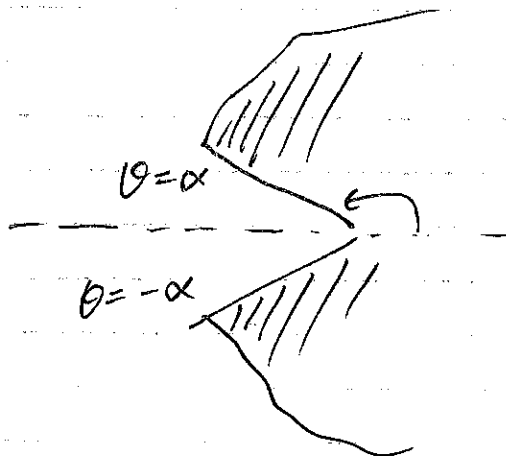
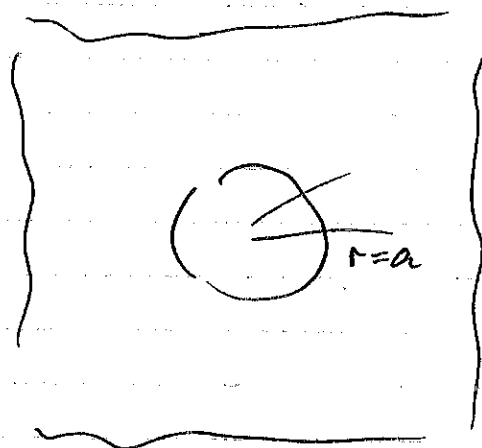
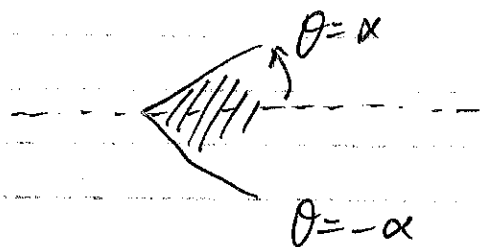
Stress Singularities?

$$\frac{F}{\pi} = \frac{2\mu c^2}{(k+1)R}$$

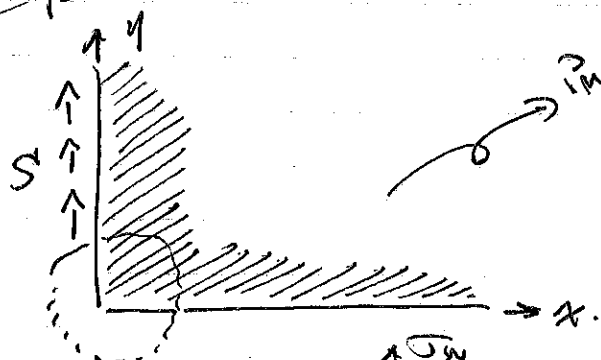
Lecture 10

5/1/2024

Wedge and Notch

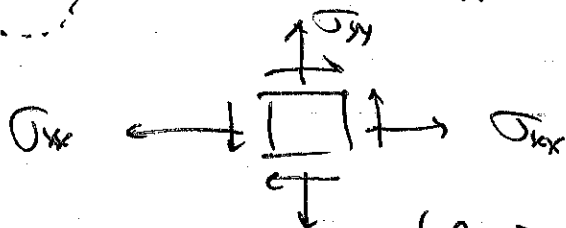


Example 1



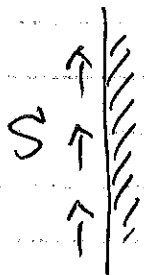
Imagine an infinite large block.

Look at area of interest, i.e., corner



traction free B.C.s

$$\sigma_{xy} = \sigma_{yx} = 0, \quad y=0$$

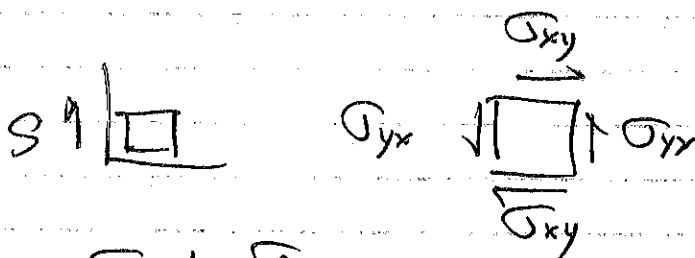


B.C.s.

$$\sigma_{xx} = 0$$

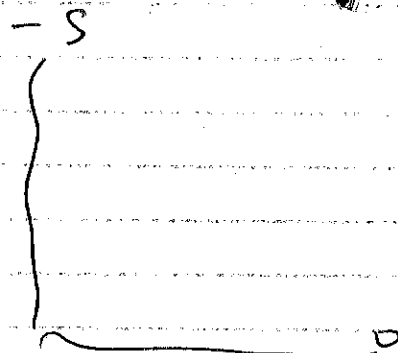
$$\sigma_{xy} = -S$$

$$\left. \begin{array}{l} \sigma_{xx} = 0 \\ \sigma_{xy} = -S \end{array} \right\} x=0$$

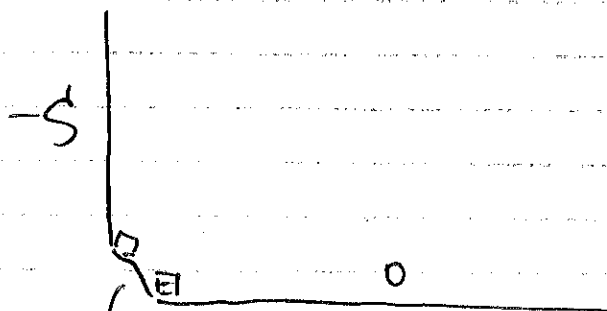


$$\sigma_{xy} \neq \sigma_{yx}$$

$$\sigma_{xy} = \sigma_{yx} = -\phi_{,xy}$$



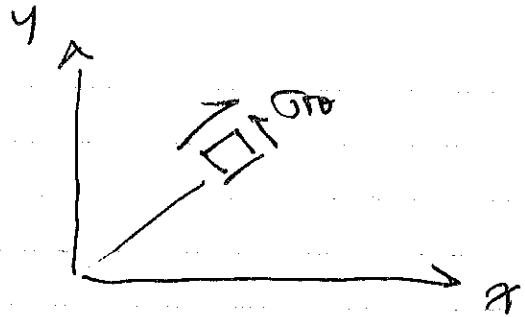
we will have



dig a corner to
avoid singularity

$$\nabla^4 \phi(r, \theta) = 0.$$

$$\phi(r, \theta) = r^m e^{in\theta}$$



$$m = n, -n, 2+n, 2-n.$$

$$\sigma_{\theta\theta} \sim r^0, \quad \phi \sim r^2.$$

$$m=2, \quad n=2, 0$$

Barber. Tab. 8.1.

we check it manually.

$$\phi = r^2, \quad r^2 \cos 2\theta, \quad r^2 \sin 2\theta, \quad r^2 \theta$$

$$\begin{matrix} \sigma_{rr} \\ \sigma_{\theta\theta} \\ \sigma_{\theta r} \end{matrix} \left. \vphantom{\begin{matrix} \sigma_{rr} \\ \sigma_{\theta\theta} \\ \sigma_{\theta r} \end{matrix}} \right\} \downarrow$$

satisfies biharmonic eqn.

find corresponding terms in table.

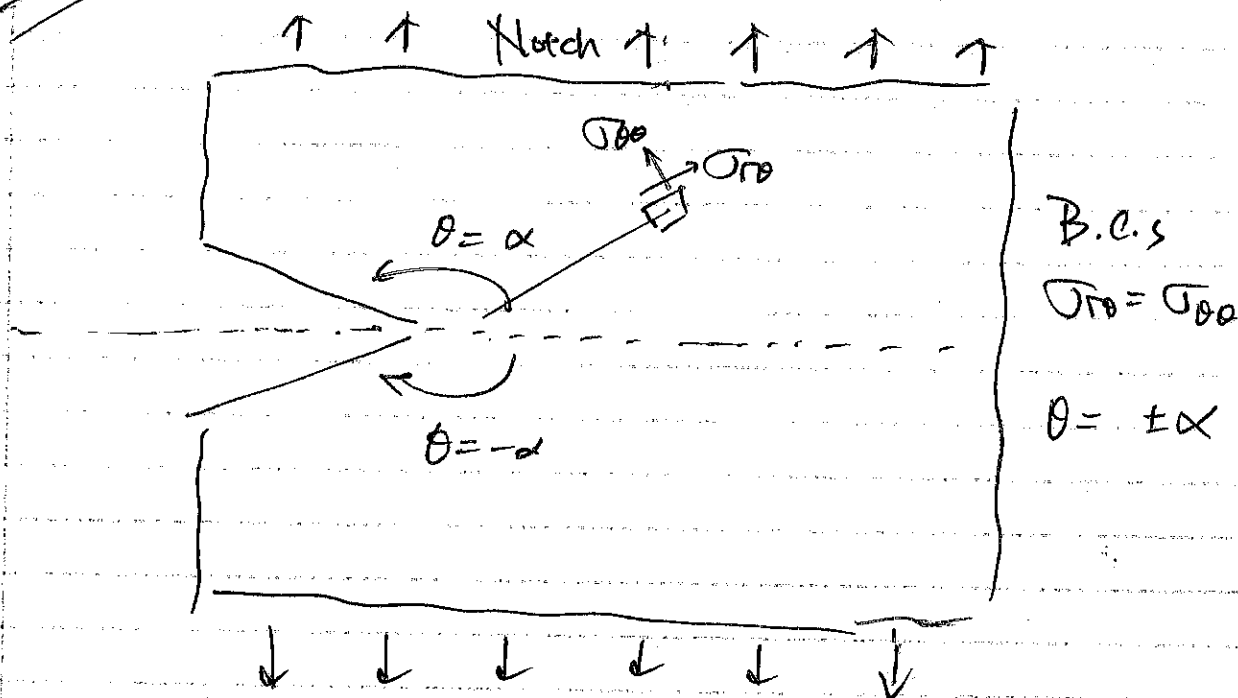
$$\text{for } r^2 \theta \rightarrow \begin{matrix} 2\theta & -1 & 2\theta \\ (\sigma_{rr}) & (\sigma_{\theta\theta}) & (\sigma_{\theta r}) \end{matrix}$$

$$\phi = S \left(-\frac{\pi r^2 \cos 2\theta}{8} + \frac{\pi r^2}{8} + \frac{r^2 \sin 2\theta}{4} - \frac{r^2 \theta}{2} \right)$$

$$\rightarrow \phi(x, y) \rightarrow \sigma_{xy} = \sigma_{yx} = - \frac{\partial^2 \phi}{\partial x \partial y}$$

$$= - \frac{5y^2}{x^2 + y^2}$$

Notch problem



William's solution

$$\phi = r^{n+2} \{ A_1 \cos(n+2)\theta + A_2 \cos n\theta + A_3 \sin(n+2)\theta + A_4 \sin n\theta \}$$

$$n = \lambda - 1, \quad n+2 = \lambda + 1.$$

$$\phi = r^{\lambda+1} \{ \dots \}$$

$$\sigma_{rr} = r^{\lambda-1} \{ \dots$$

$$\sigma_{\theta\theta} = r^{\lambda-1} \{ \dots$$

$$\sigma_{\theta\theta} = r^{\lambda-1} \{ \dots$$

if $\lambda < 1$, Stress field is singular

$$\sigma \sim A \cdot r^{\lambda-1}$$

Substitute $\begin{cases} \theta = \alpha \\ \theta = -\alpha \end{cases}$

$$\sigma_{rr} = 0, \quad \theta = \alpha, \quad \theta = -\alpha,$$

$$\sigma_{\theta\theta} = 0, \quad \theta = \alpha, \quad \theta = -\alpha$$

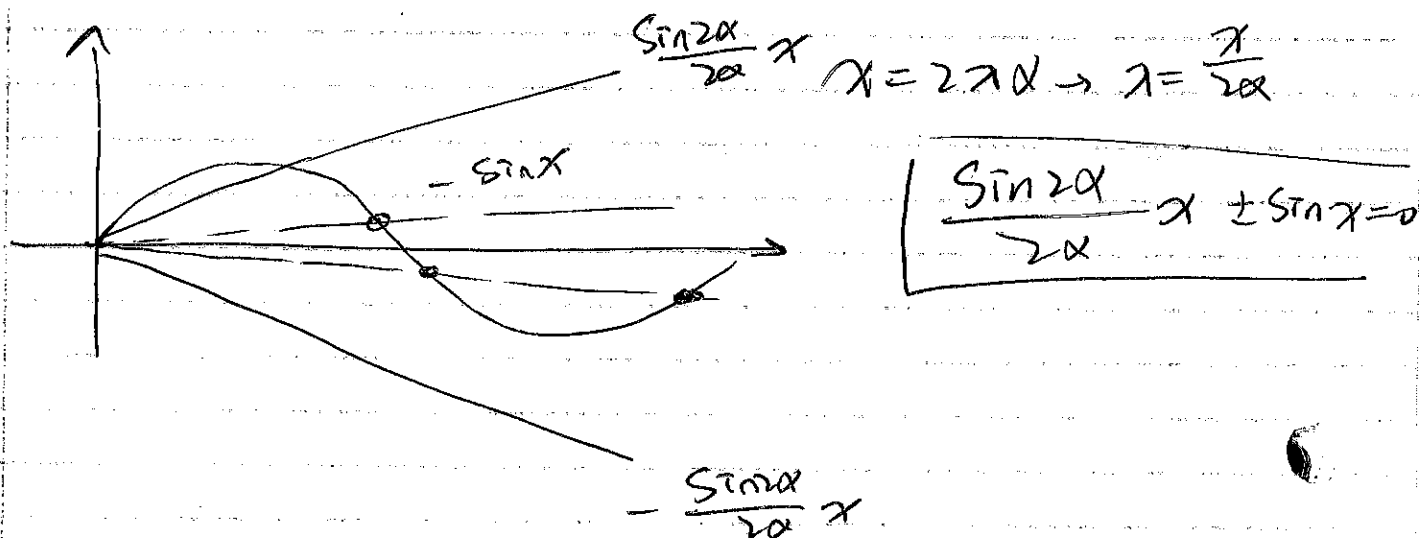
$$\begin{bmatrix} M_1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & M_2 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$[M_1] \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad [M_2] \begin{bmatrix} A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

In order to have non-trivial soln.

then, $\det(M_1) = 0 \Rightarrow \lambda \sin 2\alpha + \sin 2\lambda\alpha = 0$

or $\det(M_2) = 0 \Rightarrow \lambda \sin 2\alpha + \sin 2\lambda\alpha = 0$

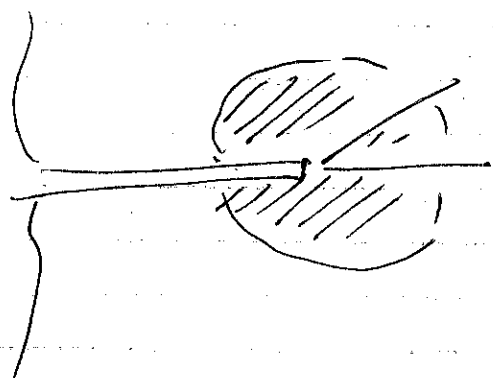


$\alpha \rightarrow \pi: \lambda = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$

$\sigma \sim \frac{1}{r}, \frac{1}{\sqrt{r}}, \dots$ non-singular

reject

this soln term.

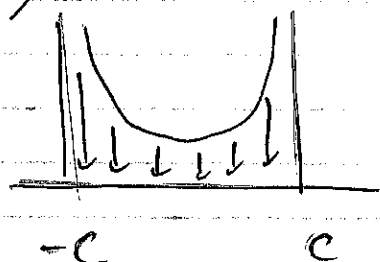


$\sigma \sim \frac{1}{\sqrt{r}}, \quad \varepsilon_r \sim \frac{1}{\sqrt{r}}$

$w = \frac{1}{2} \sigma \varepsilon \sim \frac{1}{r}$

$\Sigma = \int w r dr = \int \frac{1}{r} r dr$
 \hookrightarrow finite

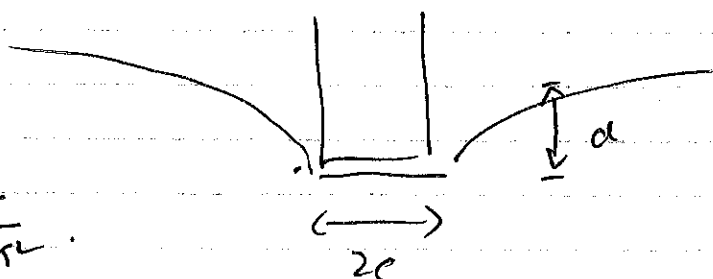
Problem Session #5



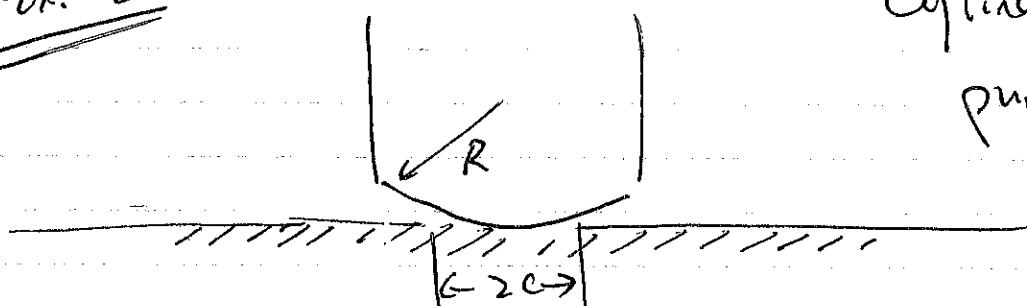
$$u_0(x) = 0$$

$$g(x) = 0$$

$$p_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}}$$



Ex. 2



Cylindrical
punch

$$d < R$$

$$u_0(x) = \frac{x^2}{2R} \quad (\text{parabolic})$$

$$g(x) = \frac{4\pi\mu}{k+1} \left(\frac{x}{R} \right)$$

$$\hookrightarrow \frac{du_0(x)}{dx}$$

$$p_y(x) = \frac{-1}{\pi \sqrt{c^2 - x^2}} \text{ p.v.} \int_{-c}^c \frac{\sqrt{c^2 - x'}}{k - x'} \cdot \frac{4\pi\mu}{k+1} \left(\frac{x'}{R} \right) dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

P.T. $\int_{-1}^1 \frac{\sqrt{1-t^2}}{x-t} dt = \pi \left[x^{n+1} - \frac{x^{n+1}}{2} \dots \right]$

$n=1. \quad I_1 = \pi \left(x^2 - \frac{1}{2} \right). \quad I_0 = \pi(x)$

$t \rightarrow \frac{x'}{c}$

transform

Applying change of variables.

$$\int_{-1}^1 \frac{\sqrt{1-t^2}}{\left(\frac{x}{c} - t\right)} c t c dt = c^2 \pi \left(\left(\frac{x}{c}\right)^2 - \frac{1}{2} \right)$$

Final expression:

$$\pi \left(x^2 - \frac{c^2}{2} \right) = \pi (x^2 - c^2) + \frac{\pi c^2}{2}$$

$$P_g(x) = \frac{4\mu}{(k+1)R} \sqrt{c^2 - x^2} + \left(\frac{F}{\pi} \frac{-2\mu c^2}{(k+1)R} \right) \frac{1}{\sqrt{c^2 - x^2}}$$

$$f(x) = \frac{-1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2}}{x - x'} g(x') dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

the second term has a singularity.

... we want to vanish the $\left(\frac{F}{\pi} - \frac{2\mu c}{(k+1)R} \right) \frac{1}{\sqrt{c^2 - x^2}}$

we set it to zero.

$$F = \frac{2\pi \mu c}{(k+1)R}$$

total indentation force

$$F = \int_{-c}^c P_y(x) dx.$$

$$\hookrightarrow P_y(x) = \frac{4\mu}{(k+1)R} \sqrt{c^2 - x^2}$$

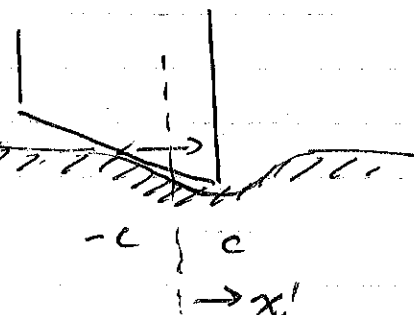
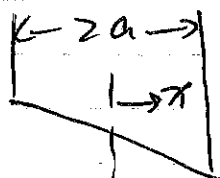
$$\frac{F}{\pi} - \frac{2\mu c}{(k+1)R} = 0$$

Ex. 3

$$u_0(x) = \beta(a-x)$$

$$\frac{du_0(x)}{dx} = -\beta$$

$$P_y(x) = \frac{-1}{\pi^2 \sqrt{c^2 - x^2}} \text{ p.v. } \left[\int_{-c}^c \dots \frac{4\mu}{k+1} (-\beta) dx' + \dots \right]$$



transformed coordinate.

$$\tilde{x} = x - (a-c)$$

Subs. \tilde{x} into the eqn.

$$P_j(x) = \frac{-1}{\pi^2 \sqrt{a^2 - \tilde{x}^2}} \text{P.v.} \left[\int_{-c}^c \dots \frac{4\pi\mu}{(k+1)(-\beta)} d\tilde{x}' + \dots \right]$$

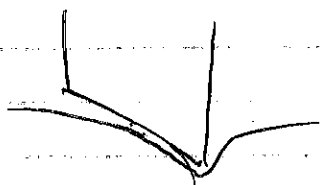
$$I_0 = C \frac{\pi x}{c}$$

$$\pi(x) \leftarrow t^0$$

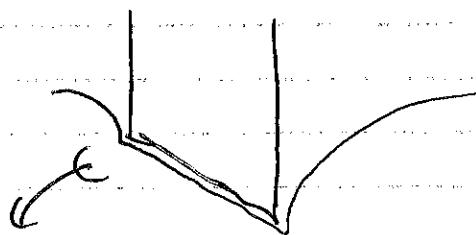
$$= \frac{4\pi\mu\beta}{\pi^2 \sqrt{a^2 - \tilde{x}^2}} \frac{C\pi \cdot x}{c} + \frac{F}{\pi \sqrt{a^2 - \tilde{x}^2}} \quad t = \frac{x'}{c}$$

We know $P_j(-c) = 0$

$$\frac{F}{\pi} - \frac{4\mu\beta c}{(k+1)} = 0 \quad \Rightarrow \quad F = \frac{4\pi\mu\beta c}{(k+1)}$$



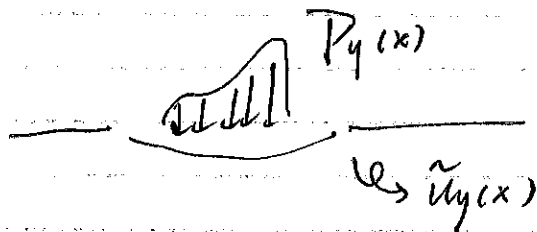
$$C \leq a$$



critical point.

$$F_{\text{total}} = \frac{\cancel{4\pi} \mu \beta a}{(k+1)}.$$

Raviar notes for contact problems.



Surface displacement.

$$\tilde{u}_x(x) = \int_{-\infty}^{+\infty} -P_y(x') \cdot G_{xy}^S(x-x') dx'$$

$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} -P_y(x') \cdot G_{yy}^S(x-x') dx' \quad (*)$$

compressive

Green's function for 2D plane strain.

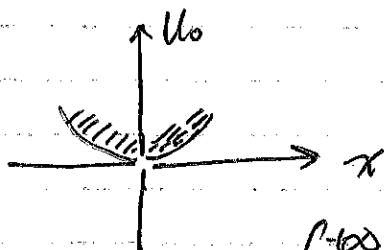
$$G_{xy}^S(x) = \frac{(k-1)}{8\mu} \text{eqn}(x).$$

$$G_{yy}^S(x) = -\frac{k+1}{4\pi\mu} \log|x|.$$

frictionless contact.

$$T_x(x) = 0$$

integrating Green's function ...



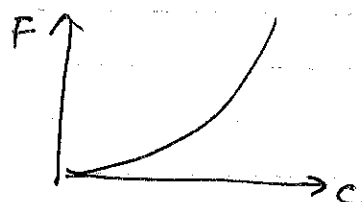
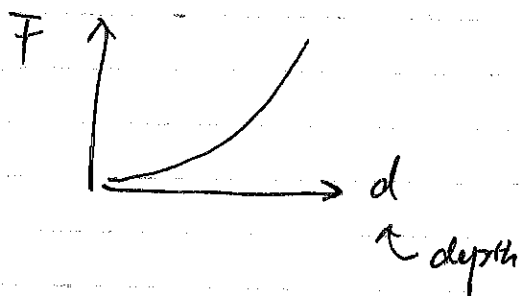
Eqn. (*) gives us:

$$u_0(x) - d = \int_{-\infty}^{+\infty} P_y(x') \cdot \frac{k+1}{4\pi\mu} \log|x-x'| dx'$$

(**)

total indenting force is the integral of the load:

$$F = \int_{-c}^c P_y(x) dx$$



contact radius

we want to know this.

#IMPORTANT: in $-c \sim c$ area:

$$\begin{cases} u_y(x) = u_0(x) - d & \text{indenter shape} \\ \sigma_{yy}(x) \leq 0 & \text{compressive} \\ \sigma_{xy}(x) = 0 & \text{frictionless.} \end{cases}$$

outside contact region.

$$\begin{cases} u_y(x) < u_0(x) - d & \text{no overlap.} \\ \sigma_{yy}(x) = 0 \\ \sigma_{xy}(x) = 0 & > \text{traction free.} \end{cases}$$

Direct inversion of integral eqn. (differentiating (**)).

$$\frac{du_0(x)}{dx} = \frac{k+1}{4\pi\mu} \cdot \int_{-c}^c \frac{P_y(x')}{x-x'} dx'$$

of the form: $g(x) = \int_{-c}^c \frac{f(x')}{x-x'} dx'$

General sol'n to the integral equation

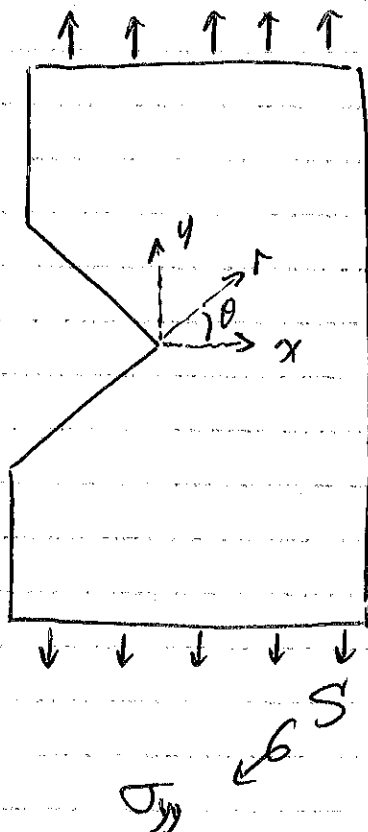
inducing force
↓

$$f(x) = - \frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} \cdot g(x')}{x - x'} dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

Since $\int_{-c}^c \frac{f(x')}{x - x'} dx'$ is singular, we need to

interpret its singular values, i.e., P.V.

Practice midterm.



Without notch.

$$\underline{\underline{\sigma}} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & S & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow 2D$$

from $\sigma_{yy} = S, \Rightarrow \phi = \frac{1}{2} S x^2$

↑
 $\phi_{,xx}$

↓
 $\phi(r, \theta) = \frac{1}{2} S r^2 \cos^2 \theta$

↓
 $\phi = \frac{1}{2} S r^2 \left(\frac{1}{2} + \cos 2\theta \right) \quad n=2$

← $n=0$

$= \frac{1}{4} S r^2 + \frac{1}{2} S r^2 \cos 2\theta$

#IMPORTANT RELATIONSHIPS.

$$\cos^2 \theta = \frac{1 + 2 \cos 2\theta}{2}$$

$$\sin^2 \theta = \frac{1 - 2 \cos 2\theta}{2}$$

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\sigma_{xx} = S' \quad \sigma_{yy} = S'$$

uniform stress field.

$$\frac{1}{4} S'^2 + \frac{1}{4} S'^2 \cos 2\theta + \dots$$

uniform.

Residual stress.

$$\left. \begin{aligned} -2 \cos 2\theta \cdot (\sigma_{xx}) \\ + 2 \cos 2\theta \cdot (\sigma_{yy}) \\ + 2 \sin 2\theta \cdot (\tau_{xy}) \end{aligned} \right\}$$

We need to create

$$+ 2 \cos 2\theta \cdot (\sigma_{xx})$$

Can be applied

$$\left[\begin{aligned} -2 \cos 2\theta \cdot (\sigma_{yy}) \\ -2 \cos 2\theta \cdot (\tau_{xy}) \end{aligned} \right]$$

to cancel the angle variation & terms in stress.

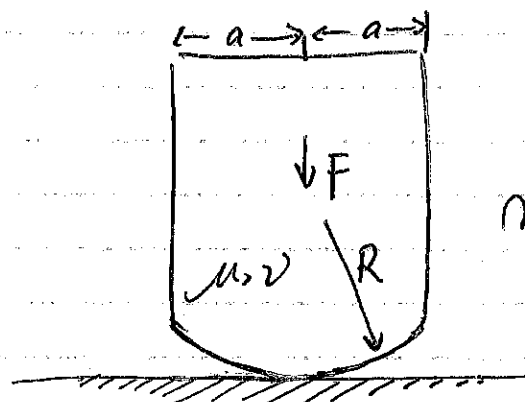
@ $\theta = \pm 135^\circ$: apply shear $\tau_{xy} = -2 \cos 2\theta$

$$\phi = \frac{1}{2} S x^2 + A y + B$$

$$\phi' = \frac{1}{2} S x^2 + \frac{1}{2} S y^2 - S x y$$

$$\rightarrow \text{goal: } \sigma_{xy} = S \quad \sigma_{yy} = S \quad \frac{1}{2} S x^2 \cos 2\theta + \frac{1}{2} S x^2 \sin 2\theta - \frac{1}{2} S \sin 2\theta$$

2#2



normal load dist. $P_y(x)$.

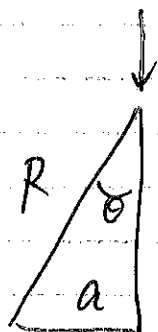
elastic half space

$$P_y(x) = \frac{2F}{\pi c^2} \sqrt{c^2 - x^2} \quad \text{where } c = \sqrt{\frac{2F(1-\nu)R}{\pi\mu}}$$

non-truncated cylindrical punch

$$f(x) = - \frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - \xi^2} g(\xi)}{x - \xi} d\xi$$

$$+ \frac{F}{\pi \sqrt{c^2 - x^2}}$$

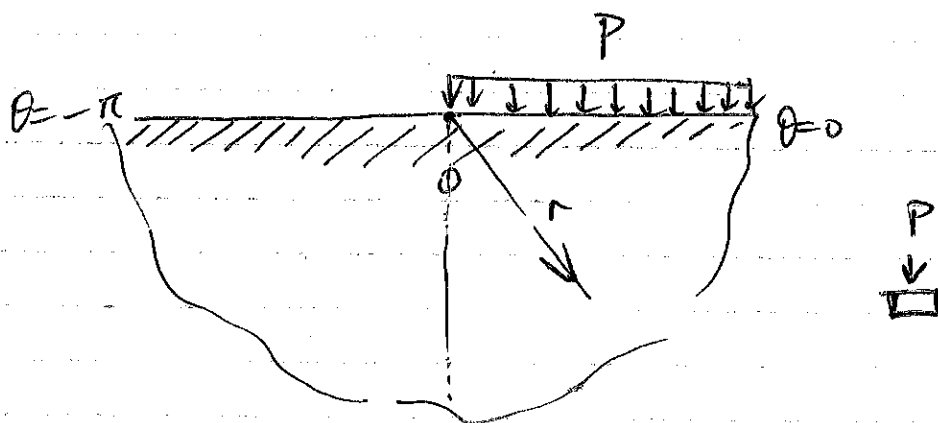


$$\sin \theta = \frac{a}{R}$$

$$\theta = \arcsin\left(\frac{a}{R}\right)$$

$$P_y(x) = \begin{cases} \frac{2F}{\pi c^2} \sqrt{c^2 - x^2} & \theta < \arcsin\left(\frac{a}{R}\right) \\ \frac{2F}{\pi c^2} \sqrt{c^2 - x^2} + \frac{F}{\pi \sqrt{c^2 - x^2}} \theta & \theta > \arcsin\left(\frac{a}{R}\right) \end{cases}$$

Pb #3



$$(a) \quad \begin{cases} \sigma_{\theta\theta} = -P \\ \sigma_{r\theta} = 0 \end{cases} \quad (a) \quad \theta = 0$$

$$\begin{cases} \sigma_{\theta\theta} = 0 \\ \sigma_{r\theta} = 0 \end{cases} \quad (a) \quad \theta = -\pi$$

(b) From the problem, we know that $\sigma_{\theta\theta}$ has θ dependence.

$$(a) \quad \theta = 0 \rightarrow \sigma_{r\theta} = 0$$

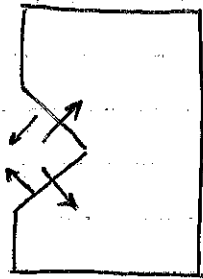
$$(a) \quad \theta = -\pi \rightarrow \begin{matrix} \sigma_{\theta\theta} = 0 \\ \sigma_{r\theta} = 0 \end{matrix} \Rightarrow \text{no term gone.}$$

$$\phi = A r^2 + B r^2 \cos 2\theta$$



$$\sigma_{\theta\theta} = 2A + B 2 \cos 2\theta \rightarrow \begin{matrix} 2A + B = P \\ 2A - 2B = 0 \end{matrix}$$

$$\sigma_{r\theta} = B 2 \sin 2\theta$$



$$\begin{cases} \underline{n}_1 = \begin{bmatrix} -\frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \end{bmatrix} \\ \underline{n}_2 = \begin{bmatrix} -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} \end{cases}$$

$$\underline{Q} = \begin{bmatrix} 0 & 0 \\ 0 & S \end{bmatrix}$$

rotation matrix

$$\begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

transform from Cartesian
to Polar coord.

Notes on beam theory.

Euler-Bernoulli.



$$\frac{d}{dx} V(x) = -q(x)$$



$$\frac{d}{dx} M(x) = V(x)$$



$$K(x) = \frac{M(x)}{EI}$$

Solving beam problem using Airy stress function.

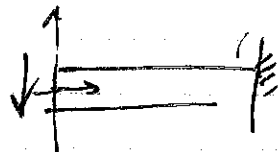
Strong B.C.s on top & bottom surfaces.

$$\begin{cases} \sigma_{xy} = 0 \\ \sigma_{yy} = 0 \end{cases}$$

$$y = \pm b$$

On two edges, apply the weak B.C.s

$$\int_{-b}^b \sigma_{xy} dy = F$$



→ collection of weak B.C.s.

$$\left. \begin{aligned} \int_{-b}^b \sigma_{xy} dy &= F \\ \int_{-b}^b \sigma_{xx} y dy &= 0 \\ \int_{-b}^b \sigma_{xx} dy &= 0 \end{aligned} \right\} x=0$$

$$\left. \begin{aligned} \int_{-b}^b \sigma_{xy} dy &= F \\ \int_{-b}^b \sigma_{xx} y dy &= Fa \\ \int_{-b}^b \sigma_{xx} dy &= 0 \end{aligned} \right\} x=a$$

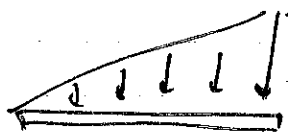
← left

Polynomial stress function (Analytic).

$$\phi = C_1 x y^3 \rightarrow \begin{cases} \sigma_{xx} = 6C_1 x y \\ \sigma_{xy} = -3C_1 y^2 \\ \sigma_{yy} = 0 \end{cases}$$

General Solution Strategies for beam problem.

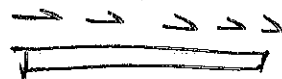
1. Determine the maximum order of polynomials.



Normal loading $\sim x^n$.

Shear $\sim x^{n+1} \rightarrow$ moment $\sim x^{n+2}$

$$\rightarrow \phi \sim x^{n+2} y^3$$



loading $\sim x^m$.

shear $x^m \rightarrow$ moment x^{m+1}

$$\rightarrow \phi \sim x^{m+1} y^3$$

2. Polynomial trial function.

$$\phi(x, y) = C_1 x^2 + C_2 xy + C_3 y^3 + \dots$$

3. Impose compatibility condition $\nabla^4 \phi = 0$

4. Apply strong & weak B.C.s.

two constraints

5. Determine the constants.

Fourier expansion.

$$f(x) = \sum_{i=0}^{\infty} C_i \varphi_i(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos \lambda_n x + b_n \sin \lambda_n x$$

expansion coefficients.

$$\begin{cases} a_0 = \frac{1}{a} \int_{-a}^a f(x) dx. \\ a_n = \frac{1}{a} \int_{-a}^a f(x) \cos \lambda_n x dx. \\ b_n = \frac{1}{a} \int_{-a}^a f(x) \sin \lambda_n x dx. \end{cases}$$

if even function:

$$f(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi}{a} x.$$

or

$$f(x) = \sum_{n=1}^{\infty} a_n \cos \lambda_n x, \quad \lambda_n = \frac{(2n-1)\pi}{2a}$$

Fourier transform.

$$e^{ikx} \equiv \cos kx + i \sin kx.$$

expansion of $f(x)$ in terms of e^{ikx} .

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k) e^{ikx} dk.$$

(inverse Fourier transform)

↪ little confusing?

Source: Image sampling & reconstruction
fink @ princeton.edu, [CS426].

• Fourier transform:

$$\hat{f}(k) = \int_{-\infty}^{\infty} f(x) e^{-i2\pi x} dx.$$

• Inverse Fourier transform:

$$f(x) = \int_{-\infty}^{\infty} \hat{f}(k) e^{i2\pi k} dk$$

Fourier solution (beam problem).

... how to construct stress function based on sym.

$$\phi(x, y) = \begin{cases} \cos \lambda x [A \cosh \lambda y + D y \sinh \lambda y] & \text{even } x, y \\ \cos \lambda x [B y \cosh \lambda y + C \sinh \lambda y] & \text{even } x \text{ odd } y \\ \sin \lambda x [A \cosh \lambda y + D y \sinh \lambda y] & \text{odd } x \text{ even } y \\ \sin \lambda x [B y \cosh \lambda y + C \sinh \lambda y] & \text{odd } x \text{ odd } y \end{cases}$$

IMPORTANT.

➤ Generalised Hooke's law for 2D.

$$\epsilon_{xx} = \frac{k+1}{8\mu} \sigma_{xx} - \frac{3-k}{8\mu} \sigma_{yy}$$

$$\epsilon_{yy} = -\frac{3-k}{8\mu} \sigma_{xx} + \frac{k+1}{8\mu} \sigma_{yy}$$

$$\epsilon_{xy} = \frac{1}{2\mu} \sigma_{xy}$$

plane strain: $k = 3 - 4\nu$

plane stress: $k = \frac{3-\nu}{1+\nu}$

➤ Weak B.C.s applied at the beam end.

$$\begin{cases} u_x = 0 \\ u_y = 0 \\ \frac{\partial u_y}{\partial x} = 0 \end{cases} \quad \leftarrow \text{ (a) beam end (subs. pos.)}$$

$$\begin{cases} u_x = 0 \\ u_y = 0 \\ \frac{\partial u_x}{\partial y} = 0 \end{cases}$$

$$\text{or} \quad \begin{cases} \int_{-b}^b u_x dy = 0 \\ \int_{-b}^b u_y dy = 0 \\ \int_{-b}^b u_{xy} dy = 0 \end{cases}$$

~ Additional Notes for Contact.

$$g(x) = \frac{4\pi\mu}{(k+1)} \frac{dU_0(x)}{dx} \quad f_y(x) = P_y(x)$$

$$f(x) = - \frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} g(x')}{x - x'} dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

$$f(x') = - \frac{q\mu}{(k+1) \sqrt{c^2 - x'^2}} \sum_{n=1}^{\infty} n a_n \cos n \vartheta + \frac{P_0 c}{2 \sqrt{c^2 - x'^2}}$$

➤ # Flat punch. $P_y = \frac{F}{\pi \sqrt{c^2 - x^2}}$

$$\rightarrow P_y \sim \frac{F}{2\sqrt{\pi c}} \frac{1}{\sqrt{r}} \rightarrow \sigma_{yy} \propto \frac{1}{\sqrt{r}}$$

➤ # Cylindrical punch.

$$U_0(x) = \frac{x^2}{2R}, \quad \frac{dU_0(x)}{dx} = \frac{x}{R}.$$

$$c = \sqrt{\frac{(k+1)R}{2\pi\mu} F} \quad \rightarrow \quad P_y(x) = \frac{2F}{\pi c^2 \sqrt{c^2 - x^2}}$$

~ Polar Coordinates.

$$\sigma_{rr} = \frac{1}{r} \cdot \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$\sigma_{\theta\theta} = \frac{\partial^2 \phi}{\partial r^2}$$

$$\begin{aligned}\sigma_{r\theta} &= \frac{1}{r} \frac{\partial \phi}{\partial \theta} - \frac{\partial}{\partial r} \left(\frac{1}{r} \cdot \frac{\partial \phi}{\partial \theta} \right) \\ &= -\frac{\partial}{\partial r} \left(\frac{1}{r} \cdot \frac{\partial \phi}{\partial \theta} \right)\end{aligned}$$

$$\sigma_{rr} = (\lambda + 2\mu) \epsilon_{rr} + \lambda \epsilon_{\theta\theta} + \lambda \epsilon_{zz}$$

$$\sigma_{\theta\theta} = \lambda \epsilon_{rr} + (\lambda + 2\mu) \epsilon_{\theta\theta} + \lambda \epsilon_{zz}$$

$$\sigma_{zz} = \lambda \epsilon_{rr} + \lambda \epsilon_{\theta\theta} + (\lambda + 2\mu) \epsilon_{zz}$$

$$\sigma_{r\theta} = 2\mu \epsilon_{r\theta}$$

$$\sigma_{\theta z} = 2\mu \epsilon_{\theta z}$$

$$\sigma_{rz} = 2\mu \epsilon_{rz}$$

$$\epsilon_{rr} = \frac{\partial u_r}{\partial r}$$

$$\epsilon_{\theta\theta} = \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r}$$

$$\epsilon_{r\theta} = \frac{1}{2} \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right)$$

$$\triangleright \quad \sin 3\theta = 3\sin\theta - 4\sin^3\theta \quad \sin 2\theta = 2\sin\theta \cos\theta$$

↓

$$\sin^3\theta = \frac{3\sin\theta - \sin 3\theta}{4}$$

$$\cos 2\theta = \cos^2\theta - \sin^2\theta$$

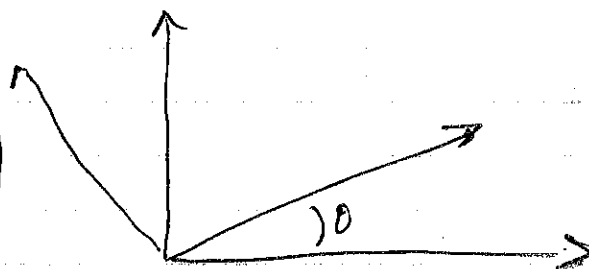
$$= 1 - 2\sin^2\theta$$

$$\cos 3\theta = 4\cos^3\theta - 3\cos\theta$$

$$= 2\cos^2\theta - 1$$

Rotation tensor

$$\underline{Q} = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



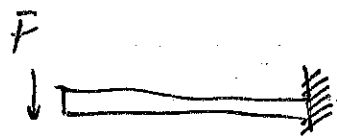
$$\underline{\sigma}' = \underline{Q} \underline{\sigma} \underline{Q}^T$$

\triangleright Beam free end weak B.C.s.

$$\int_{-b}^b \sigma_{xy} dy = F$$

$$\int_{-b}^b \sigma_{xx} dy = 0$$

$$\int_{-b}^b \sigma_{xx} y dy = 0$$



One integral / differentiation will change the odd / evenness of the function in that specific direction.

HW example: $\epsilon_{xx} \rightarrow$ even in x , even in y
 \downarrow
 $u_x = \int \epsilon_{xx} dx$ odd in x , even in y

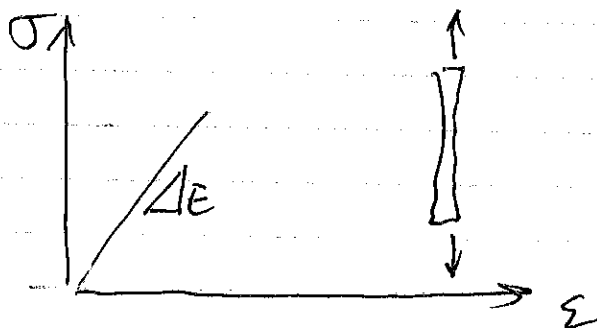
Lecture 12

5/8/2014

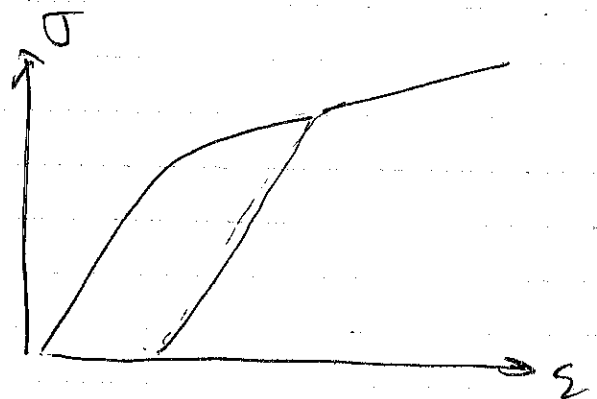
Inelasticity

Plasticity.

tensile test.

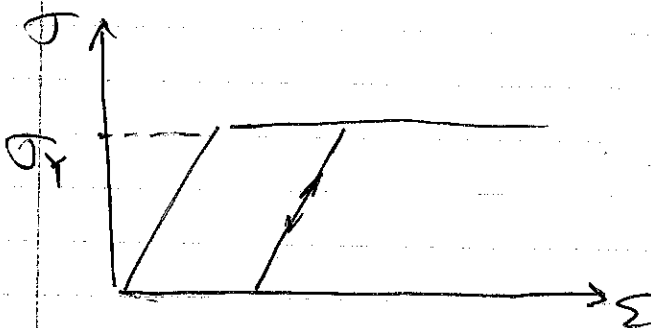


linear plasticity.



"real material"

Simplest model.



perfectly plasticity.

➤ Displacement field.

$$\underline{u} = \underline{x} - \underline{X} \quad u_i(x_i)$$

➤ Strain field.

$$\epsilon_{ij} = \frac{1}{2} (u_{ij} + u_{ji})$$

➤ Stress field, traction.

$$T_j = \sigma_{ij} n_i.$$

➤ Equilibrium condition.

$$\sigma_{ij,j} + F_j = 0$$

➤ Compatibility condition.

$$\epsilon_{ij,kl} + \epsilon_{kl,ij} = \epsilon_{il,jk} + \epsilon_{jk,il} = 0$$

Strain decomp.

$$\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$$

↳ Satisfy the compatibility.

(Continuous body assumption)

Constitutive Equation.

~ Generalized Hooke's law.

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl}^{el}$$

isotropic elasticity.

$$\sigma_{ij} = \lambda \sum_k \epsilon_{kk}^e \delta_{ij} + 2\mu \epsilon_{ij}^e.$$

where $\lambda = \frac{2\mu\nu}{1-2\nu}$

$$\sigma_{xx} = (\lambda + 2\mu) \epsilon_{xx}^e + \lambda \epsilon_{yy}^e + \lambda \epsilon_{zz}^e$$

$$\sigma_{yy} = \lambda \epsilon_{xx}^e + (\lambda + 2\mu) \epsilon_{yy}^e + \lambda \epsilon_{zz}^e$$

$$\sigma_{zz} = \lambda \epsilon_{xx}^e + \lambda \epsilon_{yy}^e + (\lambda + 2\mu) \epsilon_{zz}^e.$$

$$\sigma_{xy} = 2\mu \epsilon_{xy}^e \quad \sigma_{yz} = 2\mu \epsilon_{yz}^e \quad \sigma_{xz} = 2\mu \epsilon_{xz}^e$$

$$\sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{bmatrix}$$

$$\bar{\sigma} = \frac{1}{3} \sigma_{ii} \quad \leftarrow \text{Stress invariant.}$$

i.e., hydrostatic stress.

$$\Rightarrow \text{hydrostatic strain.} \quad \bar{\epsilon} = \frac{1}{3} \epsilon_{ii}$$

$$\bar{\sigma} = 3K \bar{\epsilon}^e$$

... characterizes the vol. change.

bulk modulus

deviatoric stress,

$$S_{ij} = \sigma_{ij} - \bar{\sigma} \delta_{ij} \quad \text{or} \quad \begin{bmatrix} \sigma_{xx} - \bar{\sigma} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{xy} & \sigma_{yy} - \bar{\sigma} & \sigma_{yz} \\ \sigma_{xz} & \sigma_{yz} & \sigma_{zz} - \bar{\sigma} \end{bmatrix}$$

deviatoric strain

$$e_{ij} = \epsilon_{ij} - \bar{\epsilon} \delta_{ij}$$

$$\hookrightarrow S_{ij} = 2\mu e_{ij}$$

↑ shear modulus

Given the strain, one can decompose it

into the hydrostatic part & deviatoric part.

$$\text{i.e.,} \quad \epsilon_{ij}^{\text{tot}} = \bar{\epsilon}^{\text{el}} \delta_{ij} + e_{ij}^{\text{el}} \quad \leftarrow \text{shape change}$$

↓ bulk mod.

Volume change assoc.

$$3K \bar{\epsilon}^{\text{el}} \delta_{ij} + 2\mu e_{ij}^{\text{el}} = \sigma_{ij}$$

→ obtain total stress

▷ Yield condition & flow rule.

$$f(\{\sigma_{ij}\}) = 0$$

$f(\cdot)$ takes all the six stress components
and $\rightarrow \mathbb{R}$.

$f < 0$ in the surface,

$f > 0$ outside the surface.

assumption: isotropic ... ①

Isotropic ... ②

Coordinate transformation.

$$\sigma'_{ij} = Q_{ip} Q_{jq} \sigma_{pq}$$

$$f(\{\sigma'_{ij}\}) = 0$$

$\sigma'_{ij} \rightarrow$ invariants \rightarrow phenomenological model.

Stress invariants

$$[\sigma_{ij}] \rightarrow \sigma_1, \sigma_2, \sigma_3$$

principal stresses.

$$I_1 = \text{tr}(\sigma_{ij})$$

$$= \sigma_1 + \sigma_2 + \sigma_3 = \sum_i \sigma_i$$

Not easy to compute

$$-I_2 = \frac{1}{2} (\text{tr}(\sigma_{ij} \sigma_{ij}) - \text{tr}(\sigma_{ij}) \text{tr}(\sigma_{ij})) = (\sigma_{xx} \sigma_{yy} + \sigma_{yy} \sigma_{zz} + \sigma_{zz} \sigma_{xx}) - (\sigma_{xy}^2 + \sigma_{yz}^2 + \sigma_{zx}^2)$$

$$I_3 = \det(\sigma_{ij}) = I_1 I_2 - I_3$$

$$= \sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1$$

$$f(\sigma) = f(I_1, I_2, I_3) = 0$$

↓ Bezoutian.

$$f(I_1, I_2, I_3) \rightarrow f(J_1, J_2, J_3) = 0$$

↓

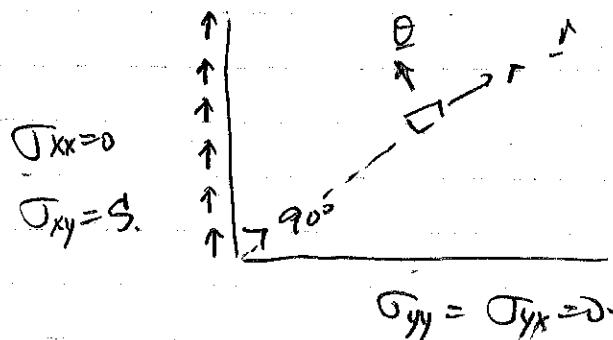
$$J_1 = \text{tr}(S_{ij}) = 0$$

$$f(J_2) = 0$$

$$J_2 = \frac{1}{2} S_{ij} S_{ij} \rightarrow \text{L2-norm.}$$

$$J_3 = \det(S_{ij})$$

Notches.



we use polar coord

(a) $\theta = 0$, $\sigma_{\theta\theta} = \sigma_{rr} = 0$.

(a) $\theta = \frac{\pi}{2}$, $\sigma_{\theta\theta} = 0$, $\sigma_{rr} = S$.

$$\sigma_{rr} \propto r^0 \rightarrow \phi(r, \theta) \propto r^2$$

$$\begin{aligned} \phi &= f(r) \cdot e^{in\theta} \\ &= r^m e^{in\theta} \end{aligned}$$

$$m = 2; \quad n = 0, 2$$

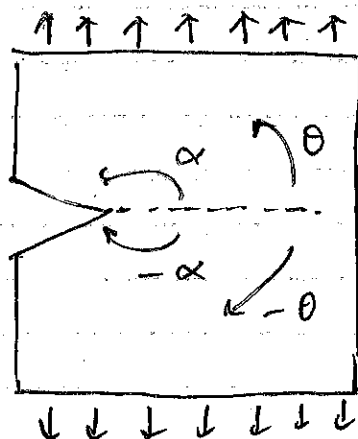
William Sol'n:
$$\phi(r, \theta) = r^{n+2} [A_1 \cos(n+1)\theta + A_2 \cos(n\theta) + A_3 \sin(n+1)\theta + A_4 \sin(n\theta)]$$

General sol'n
for notch problem.

$$\lambda = n-1, \quad \phi(r, \theta) = r^{\lambda+1} [A_1 \cos(\lambda+1)\theta + A_2 \cos(\lambda-1)\theta + A_3 \sin(\lambda+1)\theta + A_4 \sin(\lambda-1)\theta]$$

$$\sigma_{\theta\theta} = r^{\lambda-1} \left[A_1 \lambda(\lambda+1) \sin(\lambda+1)\theta + A_2 \lambda(\lambda-1) \sin(\lambda-1)\theta - A_3 \lambda(\lambda+1) \cos(\lambda+1)\theta - A_4 \lambda(\lambda-1) \cos(\lambda-1)\theta \right]$$

Notch



$\sigma_{\theta\theta}, \sigma_{\theta r}$ same symmetry
(from σ_{xx} & σ_{yy})

B.C.s @ $\theta = \pm \alpha$, traction free.

$$\sigma_{\theta\theta} = 0, \quad \sigma_{\theta r} = 0.$$

$$\sigma_{\theta\theta} \rightarrow \theta = +\alpha, -\alpha$$

$$\textcircled{1} \quad A_1 (\lambda+1) \sin(\lambda+1)\alpha + A_2 (\lambda-1) \sin(\lambda-1)\alpha - A_3 (\lambda+1) \cos(\lambda+1)\alpha - A_4 (\lambda-1) \cos(\lambda-1)\alpha = 0$$

$$\textcircled{2} \quad -A_2 (\lambda+1) \sin(\lambda+1)\alpha - A_2 (\lambda-1) \sin(\lambda-1)\alpha - A_3 (\lambda+1) \cos(\lambda+1)\alpha - A_4 (\lambda-1) \cos(\lambda-1)\alpha = 0$$

Solve for independent eqns for

$[A_1, A_2]$ & $[A_3, A_4]$.

$$\begin{bmatrix} M_1(\alpha) & 0 \\ 0 & M_2(\alpha) \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

③ & ④ from $O_{00} = 0$.

we now want to solve:

$$M_1 \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = 0.$$

M_1 is singular.

$$\det(M_1) = 0$$

$$\dots \begin{bmatrix} (\lambda+1) \sin(\lambda+1)\alpha & (\lambda-1) \sin(\lambda-1)\alpha \\ (\lambda+1) \cos(\lambda+1)\alpha & (\lambda+1) \cos(\lambda-1)\alpha \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = 0$$

Solve this.

$$\det \left(\begin{bmatrix} (\lambda+1) \sin(\lambda+1)\alpha & (\lambda-1) \sin(\lambda-1)\alpha \\ (\lambda+1) \cos(\lambda+1)\alpha & (\lambda+1) \cos(\lambda-1)\alpha \end{bmatrix} \right) = 0$$

$$A_1, A_2 \rightarrow \lambda \sin(2\alpha) + \sin(2\lambda\alpha) = 0$$

$$\lambda = 2\lambda\alpha$$

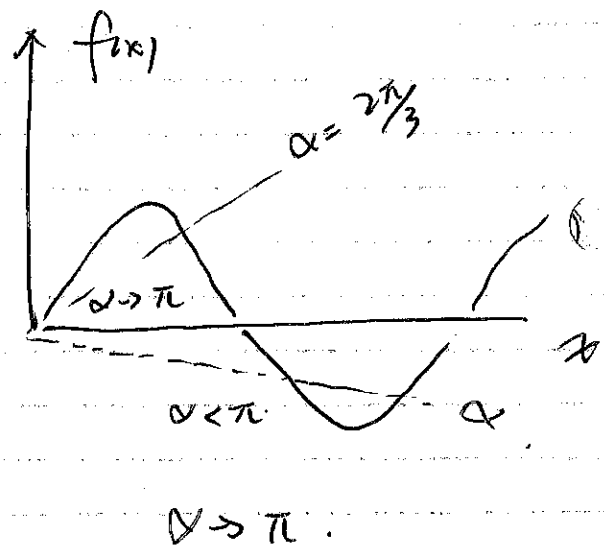
$$-\frac{\lambda}{2\alpha} \sin(2\alpha) = \sin(\lambda)$$

$$A_3, A_4 \rightarrow \lambda \sin(\alpha) - \sin(2\lambda\alpha) = 0$$

if $\alpha = \frac{2\pi}{3}$,

Slope of line

$$= \frac{-\sin(2 \times \frac{2\pi}{3})}{4\pi/3}$$



Solve for A_1, A_2

$$\lambda = 0, \pi, 2\pi, 3\pi, \dots$$

$$\begin{bmatrix} \cdot \\ \cdot \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$$

non-singular
not possible

$$A_1 = A(\lambda-1) \sin(\lambda-1)\alpha$$

$$\sigma \propto \lambda^{-1} \quad \left\{ \lambda = \frac{1}{2} \right\}$$

$$A_2 = -A(\lambda+1) \sin(\lambda+1)\alpha$$

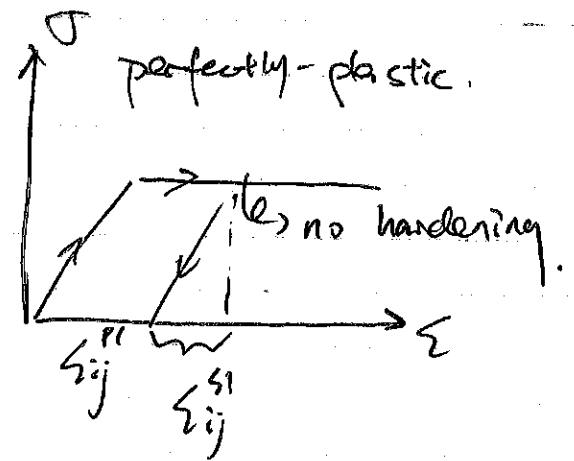
Plasticity

Strain: $\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$

Stress: $\sigma_{ij} = C_{ijkl} \epsilon_{kl}$

Compatibility cond'n.

↳ total strain ϵ_{ij} .



1). hydrostatic stress. $\rightarrow \bar{\sigma} = \sigma_{ii} / 3$.

$\rightarrow \sigma_{xx} + \sigma_{yy} + \sigma_{zz}$.

2) Deviatoric stress. $\epsilon_{ij} = \sigma_{ij} - \bar{\sigma} \delta_{ij}$.

hydrostatic stress + Deviatoric.

yield criteria: $f(\{\sigma_{ij}\}) = 0$.

... depends on stress invariants.

$\begin{bmatrix} \bar{\sigma} & & \\ & \bar{\sigma} & \\ & & \bar{\sigma} \end{bmatrix} \rightarrow$ not cause yield

$$f(J_2) = 0$$

Stress invariants

→ Stress tensor →

$$\begin{cases} I_1 & \dots & \text{tr}(\sigma_{ij}) \\ I_2 & \dots & -\frac{1}{2}(\sigma_{ii}\sigma_{jj} - \sigma_{ij}\sigma_{ji}) \\ I_3 & \dots & \end{cases}$$

$$\sigma_{ij} n_i = T_j$$

eigen val. problem

$$\det(\sigma_{ij} - \lambda I) = 0$$

$$\lambda^3 - I_1 \lambda^2 - I_2 \lambda - I_3 = 0 \quad \hookleftarrow$$

deviatoric :

$$\rightarrow \begin{cases} J_1 : & s_{11} + s_{22} + s_{33} = 0 \end{cases}$$

$$\begin{cases} J_2 : & \frac{1}{2} s_{ij} s_{ij} = \frac{1}{2} (s_{11}^2 + s_{22}^2 + s_{33}^2) \end{cases}$$

$$\begin{cases} J_3 : & s_{11} s_{22} s_{33} \end{cases}$$

$$\begin{bmatrix} s_{11} & & \\ & s_{22} & \\ & & s_{33} \end{bmatrix}$$

lecture 13. 5/13/2024

plasticity : $\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$

Generalized Hooke's law: $\sigma_{ij} = \lambda \epsilon_{kk}^{el} \delta_{ij} + 2\mu \epsilon_{ij}^{el}$

$\sigma_{ij} = \bar{\sigma} \delta_{ij} + s_{ij}$ \rightarrow deviatoric.
hydrostatic (spherical).

$$\bar{\sigma} = \frac{1}{3} \sigma_{kk} = \frac{1}{3} \text{tr}(\sigma_{ij})$$

$$\epsilon_{ij} = \bar{\epsilon} \delta_{ij} + e_{ij}$$

$$\bar{\epsilon} = \frac{1}{3} \epsilon_{kk} = \frac{1}{3} \text{tr}(\epsilon_{ij})$$

$$\bar{\sigma} = 3K \bar{\epsilon}, \quad s_{ij} = 2\mu e_{ij}$$

\nwarrow resp. elastic part.

Yield condition.

$$\rightarrow f(\sigma_{ij}) = 0$$

assumption : - isotropic.

$$\hookrightarrow f(\sigma_1, \sigma_2, \sigma_3) = 0$$

... Stress invariants:

$$I_1 = \text{tr}(\sigma_{ij}) = \sigma_1 + \sigma_2 + \sigma_3$$

$$- I_2 = \frac{1}{2} (\sigma_{ii} \sigma_{jj} - \sigma_{ij} \sigma_{ji})$$

$$I_3 = \det(\sigma_{ij}) = \sigma_1 \sigma_2 \sigma_3$$

\nwarrow principal stresses

(takes a lot of work to find them, avoid it...)

according to Beuzen.

equivalently: $f(I_1, I_2, I_3) = 0$ (yield)

$f(S_{ij}) = 0 \leftarrow \text{transform } I_1, I_2, I_3$

$\hookrightarrow f(J_1, J_2, J_3) \Rightarrow J_1, J_2, J_3$

$J_1 = \text{tr}(S_{ij}) =$

$J_2 = \frac{1}{2} S_{ij} S_{ij}$ 2-norm of the deviatoric stress.

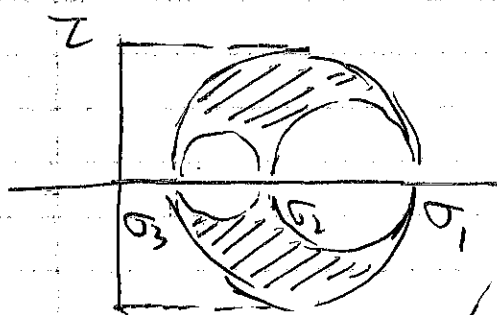
$J_3 = \dots$

Von Mises yield criteria

$f(J_2) = J_2 - k^2 = 0 \dots J_2 = k^2$

\therefore yield is satisfied when J_2 equals to some const.

Tresca yield condition



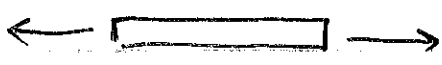
$\sigma_1 - \sigma_3 = 2k_T$ different k from Von Mises.

\hookrightarrow or the maximum difference between three principal stresses.

you can rewrite it.

in terms of J : $J(J_2, J_3) \Rightarrow$ (messy)

σ_Y : uniaxial tension.

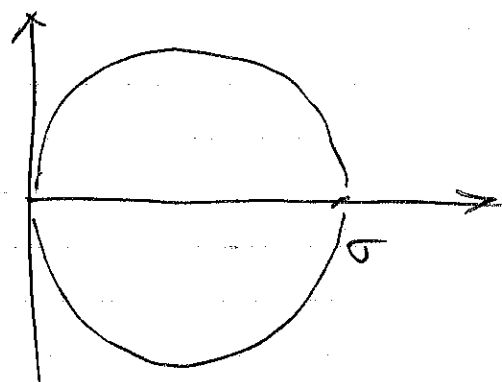

 $\sigma_{ij} = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$\bar{\sigma} = \frac{1}{3}\sigma \rightarrow S_{ij} = \begin{bmatrix} \frac{2}{3}\sigma & 0 & 0 \\ 0 & -\frac{1}{3}\sigma & 0 \\ 0 & 0 & -\frac{1}{3}\sigma \end{bmatrix}$

$J_2 = \frac{1}{2} \left(\frac{4}{9}\sigma^2 + \frac{1}{9}\sigma^2 + \frac{1}{9}\sigma^2 \right) = \frac{1}{2} \cdot \frac{6}{9}\sigma^2 = \frac{1}{3}\sigma^2$

$\frac{1}{3}\sigma_Y^2 = k^2 \quad ; \quad k = \frac{\sigma_Y}{\sqrt{3}}$

σ_Y : uniaxial tension



$\sigma_1 - \sigma_3 = \sigma$

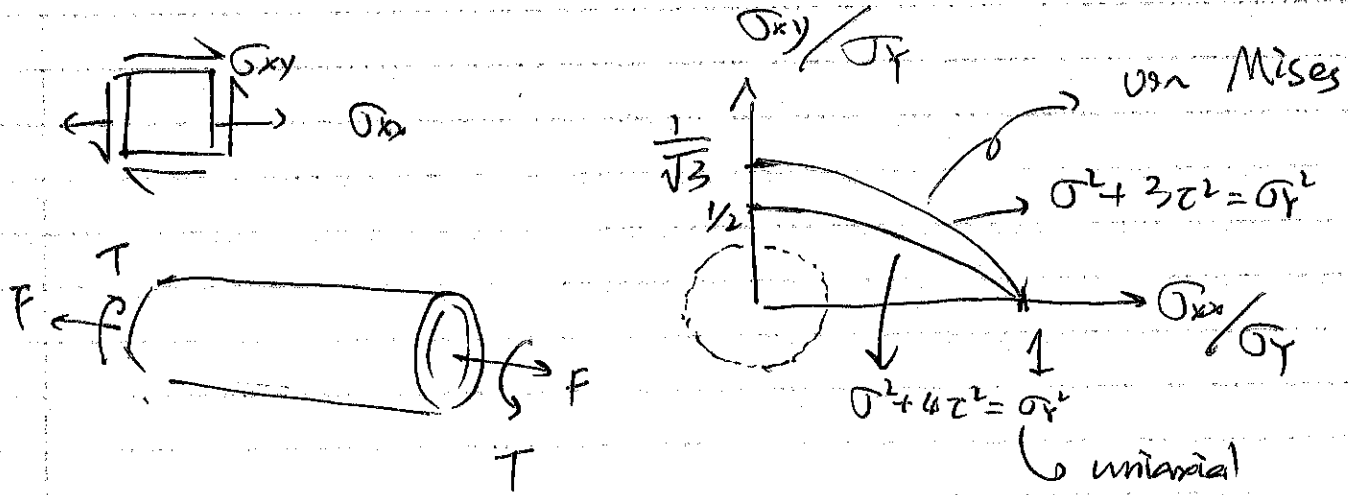
$\sigma_Y = 2k_T$

$k_T = \frac{\sigma_Y}{2}$

k & k_T are calibrated s.t. both VM.
 & Tresca predicts the same yield under
 uniaxial tension

Taylor & Quinney (1931)

tension & shear.



"New" stress tensor $\rightarrow \sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & 0 \\ \sigma_{xy} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$$\bar{\sigma} = \frac{1}{3} \sigma_{xx}$$

$$s_{ij} = \begin{bmatrix} \frac{2}{3} \sigma_{xx} & \sigma_{xy} & 0 \\ \sigma_{xy} & -\frac{1}{3} \sigma_{xx} & 0 \\ 0 & 0 & -\frac{1}{3} \sigma_{xx} \end{bmatrix}$$

Now, let's calc. J_2 :

$$J_2 = \frac{1}{2} \left(\frac{6}{9} \sigma_{xx}^2 + 2 \sigma_{xy}^2 \right) = \frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2$$

Same as in pure tension

$$\frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2 = k^2 = \frac{\sigma_Y^2}{3}.$$

pure shear: $\sigma_{xy}^2 = \frac{\sigma_Y^2}{3}.$

∴ von Mises

$$\sigma_{xy} = \frac{\sigma_Y}{\sqrt{3}}.$$

flow rule.

elastic perfectly-plastic material.

$$J_2 = k^2, \quad \dot{J}_2 = 0 \quad \leftarrow \text{von Mises, Carls}$$

$$J_2 = \frac{1}{2} S_{ij} S_{ij}, \quad \dot{J}_2 = S_{ij} \dot{S}_{ij} = 0$$

$$\sigma_{ij} = \bar{\sigma} \delta_{ij} + S_{ij} \quad \uparrow \text{realistic case.}$$

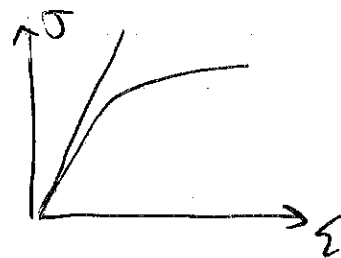
$$\bar{\sigma} = 3K \bar{\epsilon}^e$$

$$S_{ij} = 2\mu \cdot e_{ij}^e$$

$$\dot{\epsilon}_{ij}^{pl}$$



$$\epsilon_{ij}^{pl} = \int \dot{\epsilon}_{ij}^{pl}(t) dt.$$



← the "accepted" theory

$$\dot{\epsilon}_{ij}^{Pl} = \frac{\dot{\gamma}}{2\mu} S_{ij} \quad \dots \text{Associated flow rule.}$$

↑ looks like a fluid.

... gets deformed.

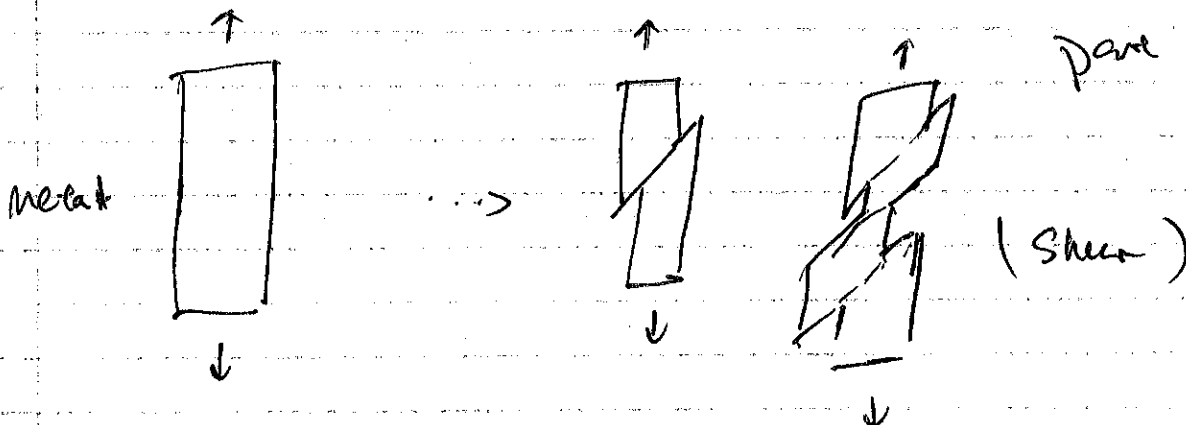
$$\epsilon_{ij}^{el} = \frac{1}{2\mu} S_{ij}$$

$$\text{tr} [\dot{\epsilon}_{ij}^{Pl}] = 0 \quad \text{tr} [\epsilon_{ij}^{Pl}] = 0 \quad \leftarrow \text{from Bridgman.}$$

$$[\epsilon_{ij}^{Pl}] = \frac{\dot{\gamma}^{Pl}}{2\mu} \delta_{ij} + [\epsilon_{ij}^{Pl}]$$

$$\epsilon_{ij}^{el} = \bar{\epsilon}^{el} \delta_{ij} + \epsilon_{ij}^{Pl}$$

← plastic strain has no volumetric part !!!



therefore, $\dot{\epsilon}_{ij}^{Pl} = \frac{\dot{\gamma}}{2\mu} S_{ij}$

lecture 14. 5/15/2024.

Plasticity yield criterion.

von Mises $J_2 - k^2 = 0$.

$$J_2 = \frac{1}{2} S_{ij} S_{ij} \quad k = \frac{\sigma_Y}{\sqrt{3}}$$

▷ flow rule $\rightarrow \dot{\epsilon}_{ij}^{pl} = 0$

$$3K \bar{\epsilon}^{el} = \bar{\sigma}$$

$$2\mu \dot{\epsilon}_{ij}^{pl} = \tilde{\lambda} S_{ij} \quad (2\mu \epsilon_{ij}^{el} = S_{ij})$$

$$\tilde{\lambda} = \frac{2\mu}{2k^2} \dot{W}$$

$$\dot{W} = S_{ij} \dot{\epsilon}_{ij} = S_{ij} (\dot{\epsilon}_{ij}^{el} + \dot{\epsilon}_{ij}^{pl})$$

↳ total strain rate (deformation)

(because in the experiment we impose the loading)

$$\dots 2\mu \dot{W} = S_{ij} (2\mu \dot{\epsilon}_{ij}^{el} + 2\mu \dot{\epsilon}_{ij}^{pl})$$

$$= S_{ij} (\dot{S}_{ij} + \tilde{\lambda} S_{ij}) \quad \dots \quad (TBC)$$

EPP: elastic perfectly-plastic if J_2 remains const.

↳ for spp.

$\dot{\epsilon} \perp \epsilon$

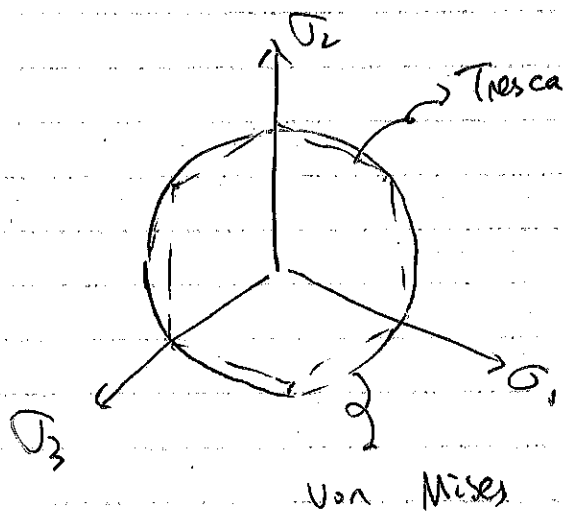
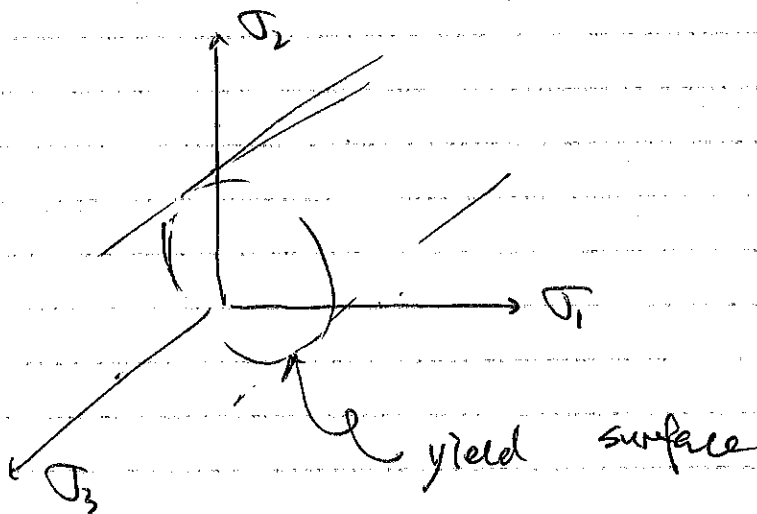


$$\dot{J}_2 = S_{ij} \dot{S}_{ij} = 0$$

$$\dots \tilde{\sigma} S_{ij} S_{ij} = \tilde{\sigma}^2 2k^2$$

$$\dot{W}^{tot} = \bar{\sigma} \dot{\bar{\epsilon}} + \dot{W}$$

if the material is isotropic, we can visualize it based on the principle stresses

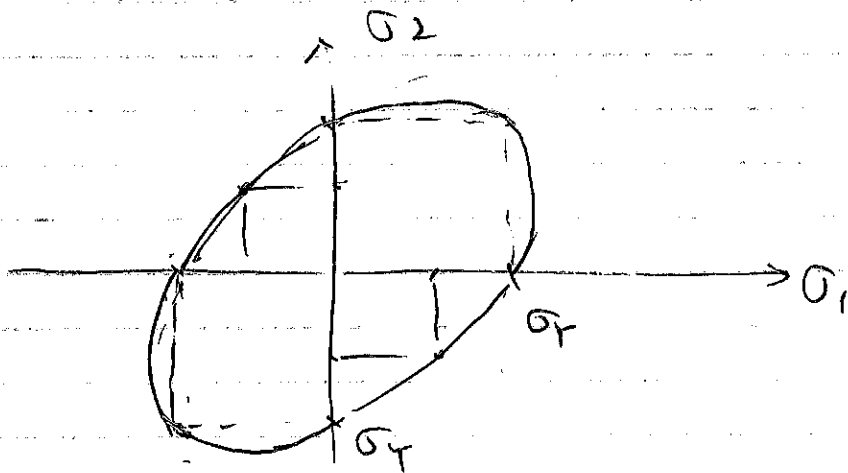


$$J_2 = \frac{1}{2} (S_1^2 + S_2^2 + S_3^2)$$

$$= \frac{1}{6} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]$$

In terms of
principle stresses

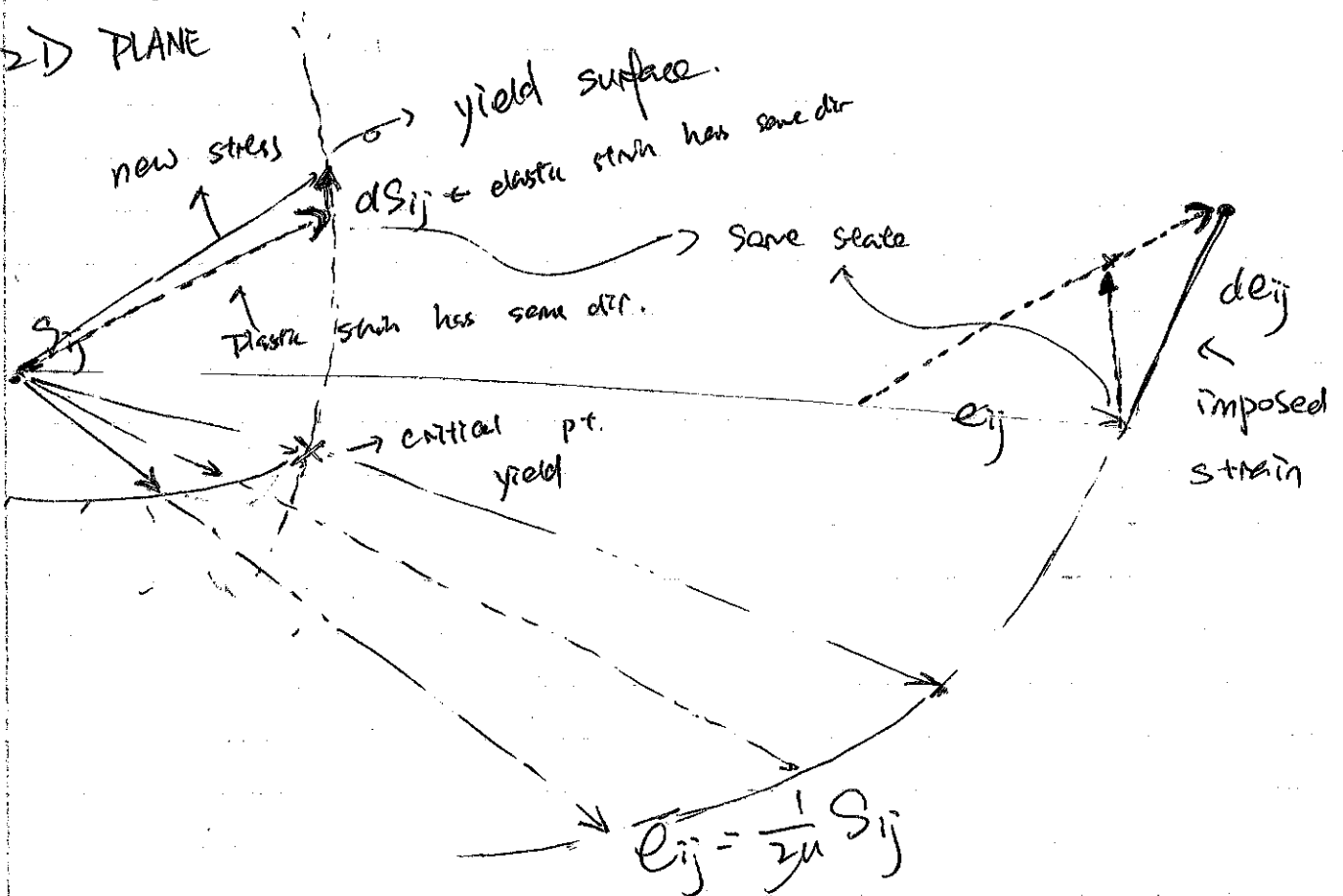
in Plane Stress.



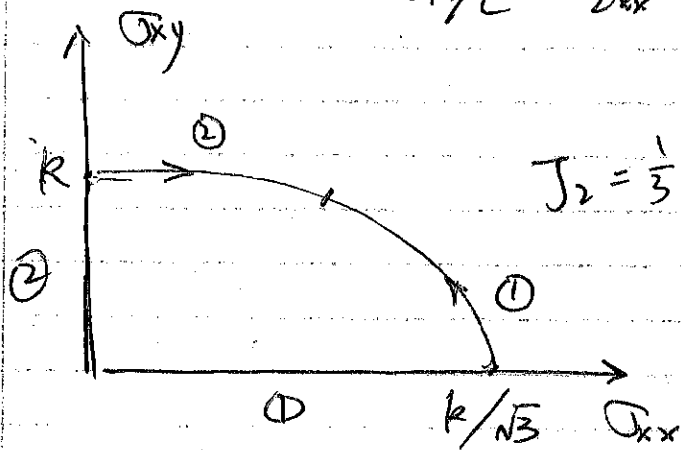
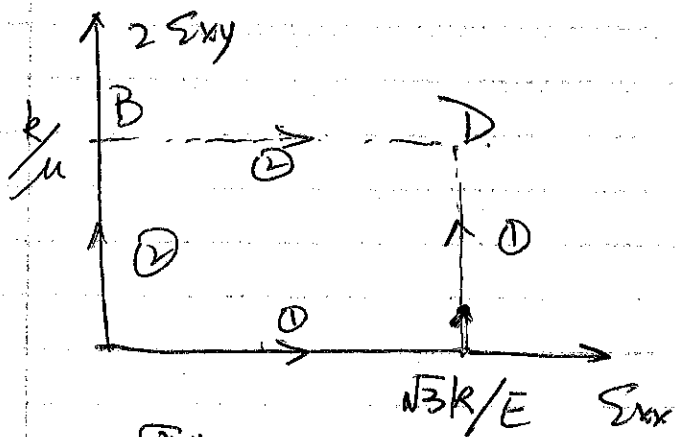
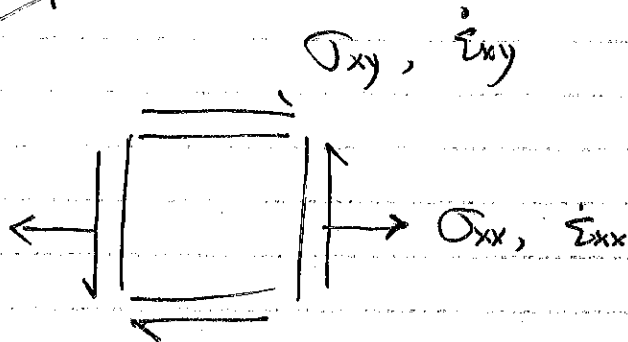
i.e. cutting a cylinder thru a perpendicular plane.

Flow Rule

2D PLANE



Example



$$J_2 = \frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2 = k^2$$

$$\dot{\epsilon}_{xy} = \dot{\epsilon}_{xy}^e + \dot{\epsilon}_{xy}^p$$

$$= \frac{\dot{\sigma}_{xy}}{2\mu} + \frac{\dot{W}}{2k^2} \sigma_{xy}$$

$$= \frac{\dot{\sigma}_{xy}}{2\mu} + \frac{\sigma_{xy} 2\dot{\epsilon}_{xy}}{2k^2}$$

Incompressible $\left\{ \begin{array}{l} \nu = 0.5 \\ E = 3\mu \end{array} \right.$

$$\dot{\epsilon}_{ij}^p = \frac{\dot{W}}{2k^2} S_{ij}$$

$$\dot{W} = S_{ij} \dot{\epsilon}_{ij}$$

$$= \sigma_{ij} \dot{\epsilon}_{ij} = \sigma_{xy} 2 \dot{\epsilon}_{xy}$$

$$\rightarrow \dot{\Sigma}_{xy} = \frac{\dot{\sigma}_{xy}}{2\mu} + \frac{\dot{\Sigma}_{xy}}{k^2} \cdot \sigma_{xy}^2 \quad \leftarrow \text{first expression.}$$

$$\left(1 - \frac{\sigma_{xy}^2}{k^2}\right) \dot{\Sigma}_{xy} = \frac{\dot{\sigma}_{xy}}{2\mu}$$

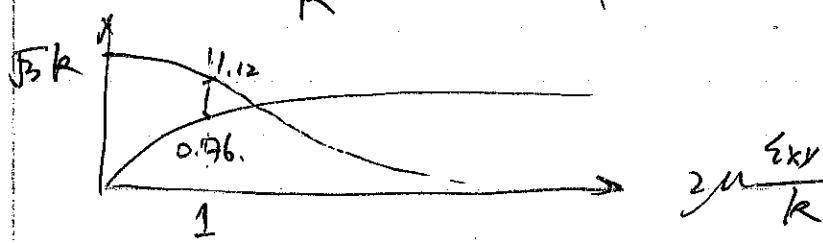
$$\frac{2\mu \dot{\Sigma}_{xy}}{k} = \frac{\dot{\sigma}_{xy}/k}{1 - \frac{\sigma_{xy}^2}{k^2}}$$

$$2\mu \frac{\dot{\Sigma}_{xy}}{k} = \frac{\frac{\dot{\sigma}_{xy}}{k}}{1 - \left(\frac{\sigma_{xy}}{k}\right)^2}$$

$\int dt$ on both sides.

$$2\mu \frac{\Sigma_{xy}(t)}{k} = \ln \tanh \left[\frac{\sigma_{xy}(t)}{k} \right]$$

$$\frac{\sigma_{xy}(t)}{k} = \tanh \left(2\mu \cdot \frac{\Sigma_{xy}(t)}{k} \right)$$



$$\tanh = \frac{\sinh}{\cosh} = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

Problem session #7

5/17/2014

Problem: first apply shear up to yield point

$$\sigma_{xy} = \sigma_Y$$

then apply tension to same strain ϵ_{xx} .

Assumptions: No strain hardening,

$$\nu = 0.5 \quad (\text{incompressible})$$

von Mises criteria. $J_2 = k^2$

VM criteria: $J_2 = k^2 = \frac{\sigma_Y^2}{3}$

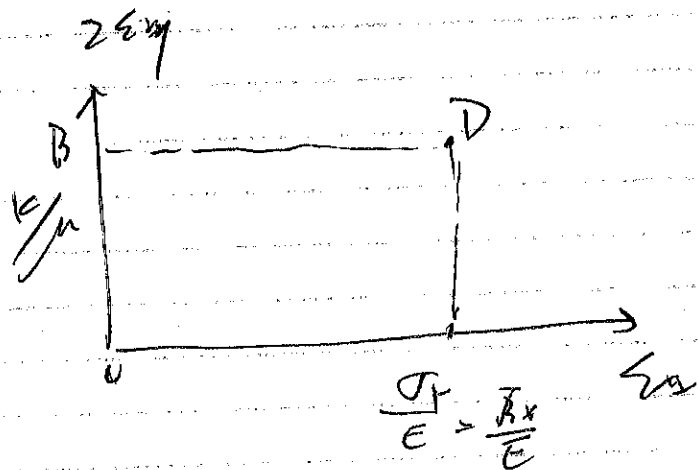
$$J_2 = \frac{1}{2} S_{ij} S_{ij}$$

EP: $J_2 = 0 \Rightarrow s_j s_j = 0$

Plastic strain rate: $\dot{\epsilon}_{ij}^P = \frac{\dot{\gamma}}{2\mu} S_{ij} = \frac{\dot{\gamma}}{2k^2} S_{ij}$

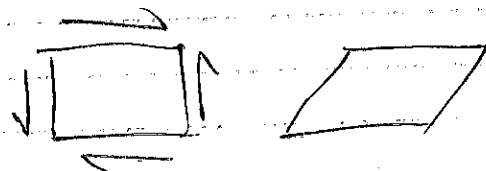
Shear tension Plasticity

$$J_2 = \frac{\sigma_{xx}^2}{3} + \sigma_{xy}^2 = k^2$$



$$\epsilon_{xy} = \epsilon_{xy}^{el} + \epsilon_{xy}^P$$

$$\nu = 0.5 \rightarrow E = 2(1+\nu)\mu$$



① Along path OB. \rightarrow pure elastic strain.

$$\sigma_{xy} = 2\mu \epsilon_{xy} \quad (\text{goes from 0 to } k).$$

$$\sigma_{xx} = \sigma_{yy} = \sigma_{zz} = \sigma_{xz} = \sigma_{yz} = 0$$

$$\epsilon_{xx} = \epsilon_{yy} = \epsilon_{zz} = \epsilon_{xy} = \epsilon_{yz} = 0$$

② Along path BD

$$J_2 = \frac{\sigma_{xx}^2}{3} + \sigma_{xy}^2 = k^2$$

$$\dot{\epsilon}_{ij}^{PI} = \frac{\dot{W}}{2k^2} S_{ij}$$

$$\dot{W} = S_{ij} \dot{\epsilon}_{ij} = S_{xx} \dot{\epsilon}_{xx} \quad \left. \begin{array}{l} \epsilon_{xy} = \text{const.} \\ \epsilon_{yz} = 0 \end{array} \right\}$$

shape change
rate of work

$$\dot{W} = S_{xx} \dot{\epsilon}_{xx} = \frac{2}{3} \sigma_{xx} \dot{\epsilon}_{xx}$$

$$\rightarrow \dot{\epsilon}_{xx}^{PI} = \frac{\dot{W}}{2k^2} \cdot S_{xx} = \frac{\dot{W}}{3k^2} \sigma_{xx}$$

$$\dot{\epsilon}_{xx} = \dot{\epsilon}_{xx}^{el} + \dot{\epsilon}_{xx}^{pl}$$

$$\cancel{\dot{\epsilon}} + \dot{\epsilon}_{xx}^{el}$$

$$\left(\frac{\dot{\sigma}_{xx}}{E} \right)$$

$$\hookrightarrow \frac{\dot{\sigma}_{xx}}{E} + \frac{\dot{\epsilon}_{xx}}{3k^2} \sigma_{xx}$$

$$= \frac{\dot{\sigma}_{xx}}{E} + \frac{\dot{\epsilon}_{xx}}{3k^2} (\sigma_{xx})^2$$

$$\dot{\epsilon}_{xx} \left(1 - \frac{\sigma_{xx}^2}{3k^2} \right) = \frac{\dot{\sigma}_{xx}}{E}$$

$$\frac{E \dot{\epsilon}_{xx}}{\sqrt{3} k} = \frac{\dot{\sigma}_{xx}}{1 - \left(\frac{\sigma_{xx}}{\sqrt{3} k} \right)^2}$$

some algebra

$$\operatorname{atan}'(x) = \frac{1}{1-x^2}$$

Integrate both sides:

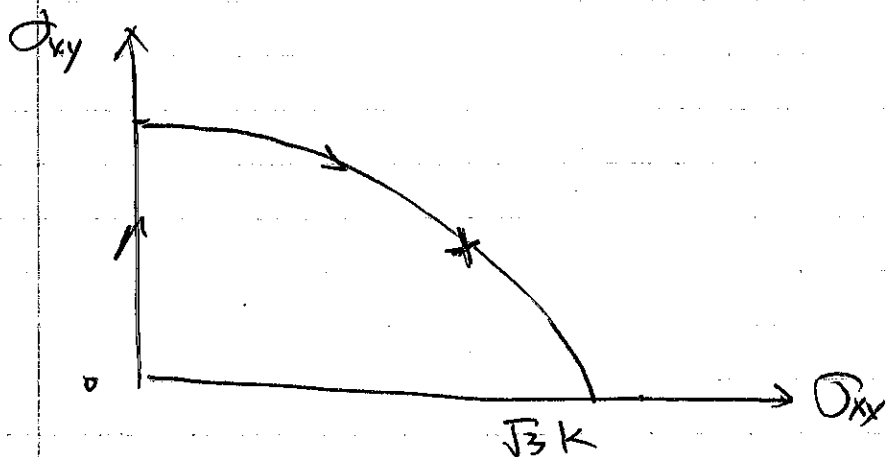
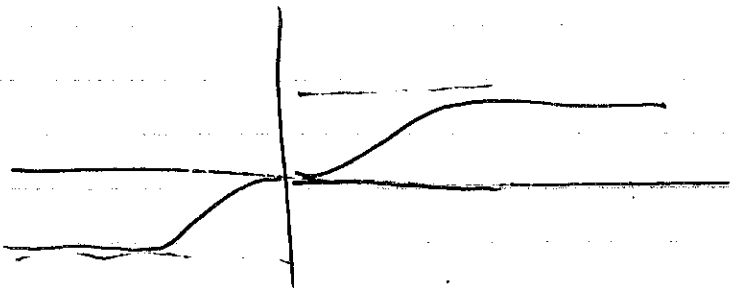
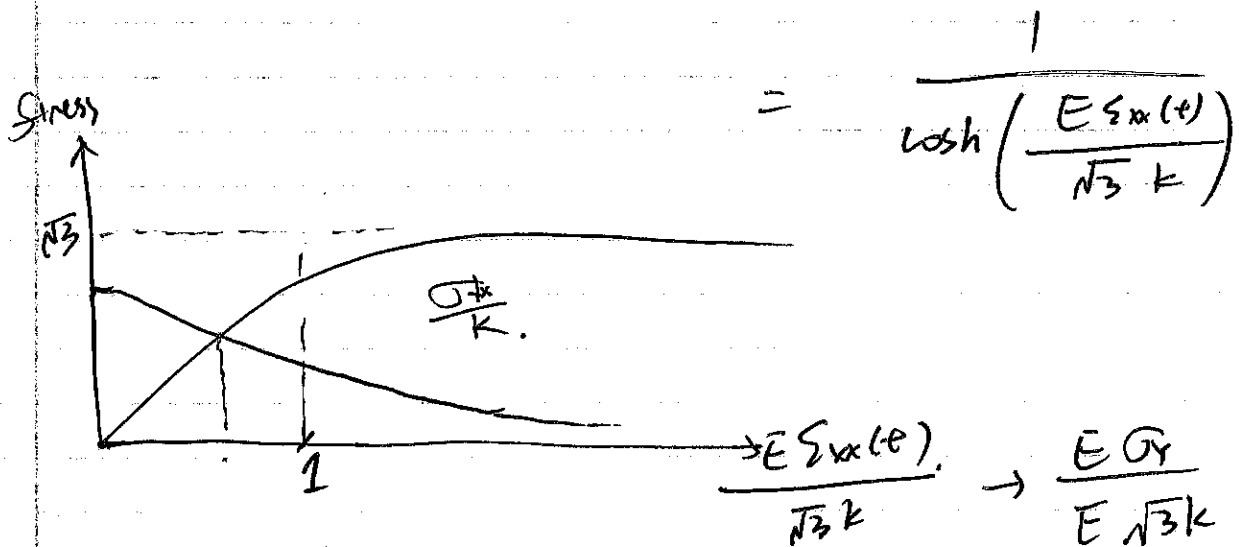
$$\frac{E \epsilon_{xx}(t)}{\sqrt{3} k} = \operatorname{atanh} \left(\frac{\sigma_{xx}(t)}{\sqrt{3} k} \right)$$

$$\frac{\sigma_{xx}(t)}{\sqrt{3} k} = \tanh \left(\frac{E \epsilon_{xx}(t)}{\sqrt{3} k} \right)$$

Using $J_2 = k^2$

$$\frac{\sigma_{xx}^2}{3} + \sigma_{xy}^2 = k^2 \Rightarrow \frac{\sigma_{xy}}{k} = \sqrt{1 - \left(\frac{\sigma_{xx}}{\sqrt{3}k}\right)^2}$$

$\hookrightarrow \tanh^2$



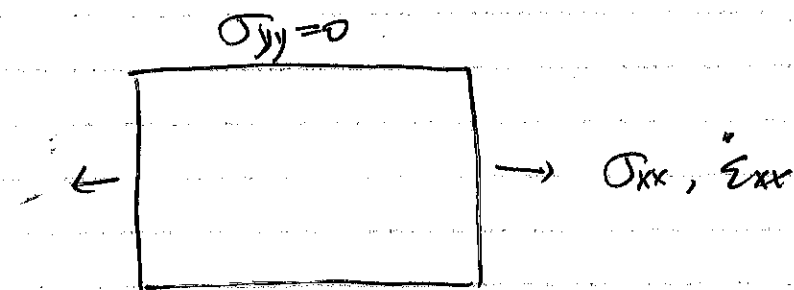
If $\nu < 0.5$ (not incompressible).



no analytical soln



numerical methods.



plane strain prob.

$$J_2 = K^{\nu} = \frac{\sigma_y^2}{3}$$

$$\sigma_{zz} = \nu \sigma_{xx}$$

$$= \frac{1}{2} (\sigma_{xx}^2 + \sigma_{yy}^2 + \sigma_{zz}^2)$$

$$\sigma_{xx} = \frac{\sigma_y}{\sqrt{\nu^2 + 1}} > \sigma_y$$

Finite time steps.

$$\sigma_{xx}(t), \sigma_{zz}(t), \epsilon_{xx}(t), \epsilon_{zz}(t)$$

$$\epsilon_{xx}(t + \Delta t), \epsilon_{zz}(t + \Delta t)$$

$$\text{Unknowns: } \sigma_{xx}(t + \Delta t), \sigma_{zz}(t + \Delta t) \\ (\pi/2 \mu)$$

$$\Delta \bar{\sigma} = \bar{\sigma}(t + \Delta t) - \bar{\sigma}(t)$$

$$\Delta S_{xx} = S_{xx}(t + \Delta t) - S_{xx}(t)$$

$$\Delta S_{yy} = S_{yy}(t + \Delta t) - S_{yy}(t)$$

Total strains. elastic

$$\begin{aligned} \Delta \epsilon_{xx}^{el} &= \Delta \bar{\epsilon} + \Delta e_{xx}^{el} \\ &= \frac{\Delta \bar{\sigma}}{3k} + \frac{\Delta S_{xx}}{2\mu} \end{aligned}$$

$$\Delta \epsilon_{xx}^{pl} = \dots$$

plastic strain

$$\Delta \epsilon_{xx}^{pl(t)} = \frac{\tilde{\lambda} \Delta e}{2\mu} \cdot \left(\frac{S_{xx}(t) + S_{xx}(t + \Delta t)}{2} \right)$$

$$\dot{\epsilon}_{xx}^{pl} = \frac{\tilde{\lambda}}{2\mu} S_{xx}$$

↓

$$\frac{\Delta \epsilon_{xx}^{pl}}{\Delta t}$$

$$\Delta \epsilon_{xx}^{pl} = \dots$$

Final eqns.

$$\epsilon_{xx}(t) + \Delta \epsilon_{xx}^{el} + \Delta \epsilon_{xx}^{pl} - \epsilon_{xx}(t + \Delta t) = 0$$

$$\epsilon_{zz}(t) + \Delta \epsilon_{zz}^{el} + \Delta \epsilon_{zz}^{pl} - \epsilon_{zz}(t + \Delta t) = 0$$

$$\rightarrow \frac{1}{2} \left[S_{xx}(t+\Delta t)^2 + S_{yy}(t+\Delta t)^2 + S_{zz}(t+\Delta t)^2 \right] = K^2$$

$$T_2 = K^2$$

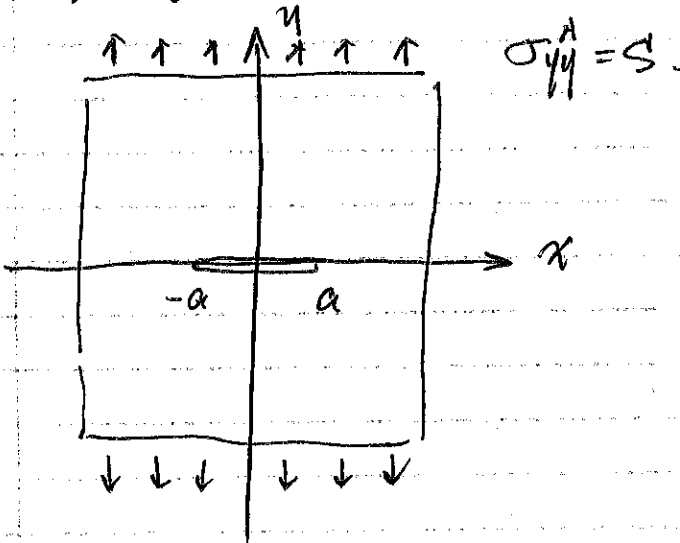
5/20/24

Lecture 15

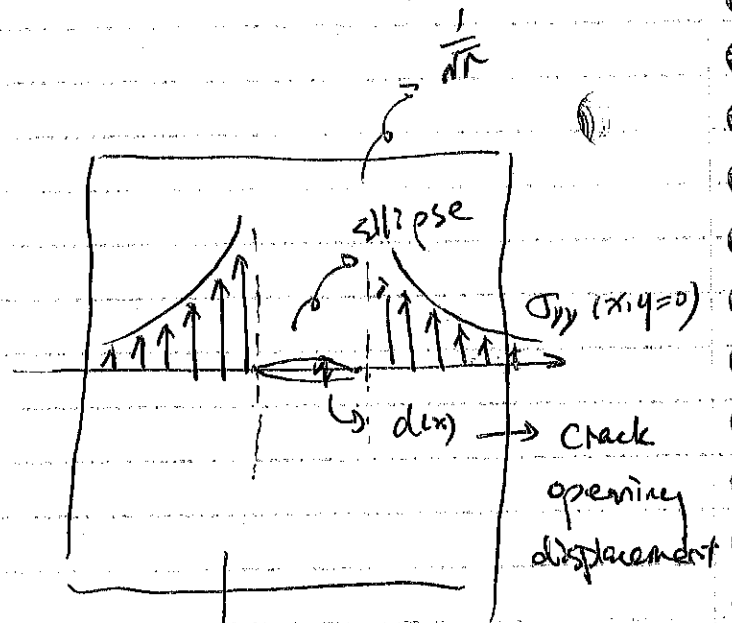
LEFM \rightarrow EPFM

"recall previous lecture"

Stt. line crack



$$\sigma_{yy}^A = S$$



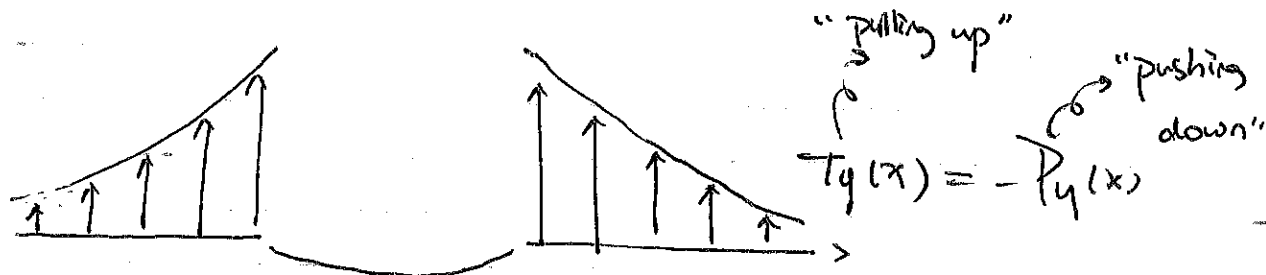
Def'n: stress intensity factor

$$\sim \frac{K_I}{\sqrt{2\pi r}} \rightarrow r = x - a$$

we want to know K_I

growth

View the crack problem as the half-space.



surface displacement.

half-space.

$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} T_y(x') \left(-\frac{\kappa+1}{4\pi\mu} \right) \log|x-x'| dx'$$

from surface Green's function.

Invert it to solve for T_y

$$T_y(x) = \left[\int \frac{u_y'(x')}{\dots} \right] + \frac{Ax+B}{(x+a)^{1/2}(x-a)^{1/2}}$$

$\rightarrow = 0$

even func. of x

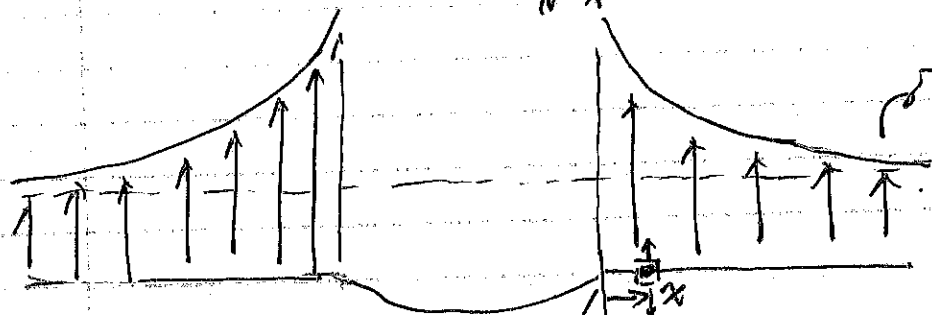
$$T_y(x) = \frac{Ax+B}{(x+a)^{1/2}(x-a)^{1/2}} = \frac{A+B/x}{\sqrt{1-(a/x)^2}}$$

$$T_y(x) = \frac{A}{\sqrt{1-(a/x)^2}} = \frac{S}{\sqrt{1-(a/x)^2}}$$

"elegant sol'n"

$$\sigma_{yy}(x, y=0) = \frac{S \cdot |x|}{\sqrt{x^2 - a^2}}$$

to make sure the loading is still an even function



plane strain.

"converging to S when $x \rightarrow \infty$ ".

$$\sigma_{yy}(x, y=0) = T_y(x).$$

look at point "x"

Analogous to the flat punch

$$x = a + r$$

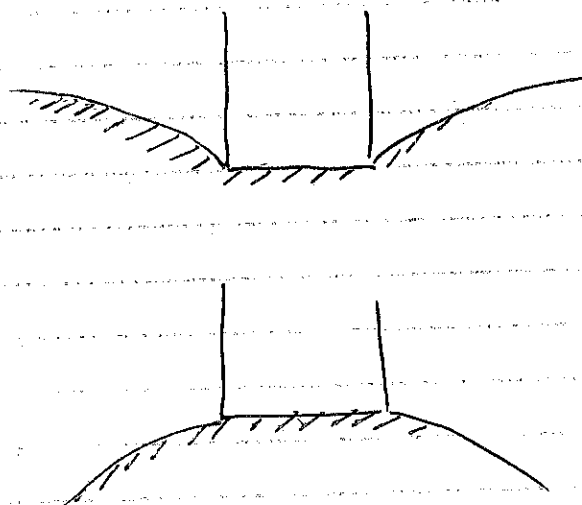
$$\sigma_{yy}(x, y=0)$$

$$= \sigma_{\theta\theta}(r, \theta=0)$$

$$= \frac{S(a+r)}{\sqrt{(a+r)^2 - a^2}}$$

$$= \frac{Sa}{\sqrt{2ar}}$$

lim $r \rightarrow 0$



~ Stress Intensity factor

$$= S \sqrt{\frac{a}{2}} \cdot \frac{1}{\sqrt{r}} = \frac{K_I}{\sqrt{2\pi r}}$$

for mode-I fracture

↑ unit: $[Pa \cdot m^{1/2}]$

$$K_I = S \sqrt{a\pi}$$

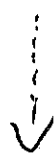
← IMPORTANT

Q: why $[Pa \cdot \sqrt{m}]$.

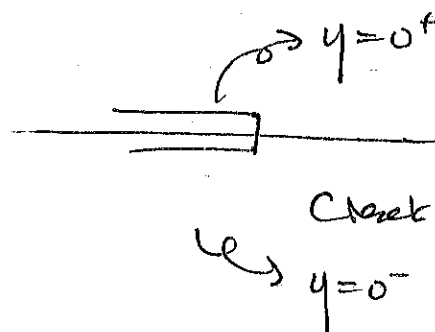
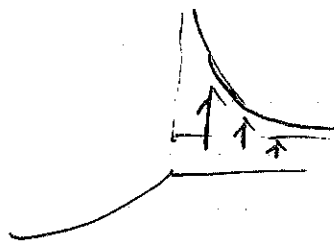
... K divide by \sqrt{r} to get stress.

$$\tilde{u}_y(x) = - \frac{K+1}{4\mu} S a \sqrt{1 - \left(\frac{x}{a}\right)^2}$$

$$|x| < a, y = 0^-$$



$$d(x) = -2 \tilde{u}_y(x)$$

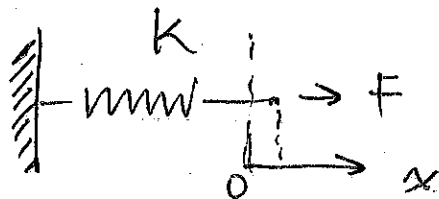


$$= \frac{2(1-\nu)}{\mu} S a \sqrt{1 - \left(\frac{x}{a}\right)^2}$$

IMPORTANT RESULT

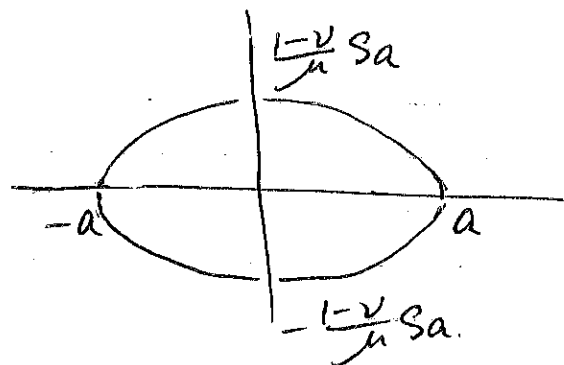
Enthalpy

Example



$$F = Kx$$

$$E = \frac{1}{2} Kx^2$$



$$\text{enthalpy: } H = E - \Delta W_{\text{ext.}}$$

$$\downarrow$$

$$\Delta W_{\text{ext}} = Fx$$

Principle: under load mechanism, system go

to the state where H is minimized

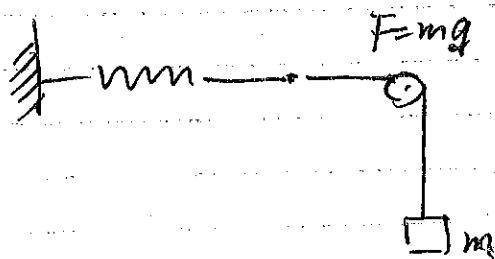
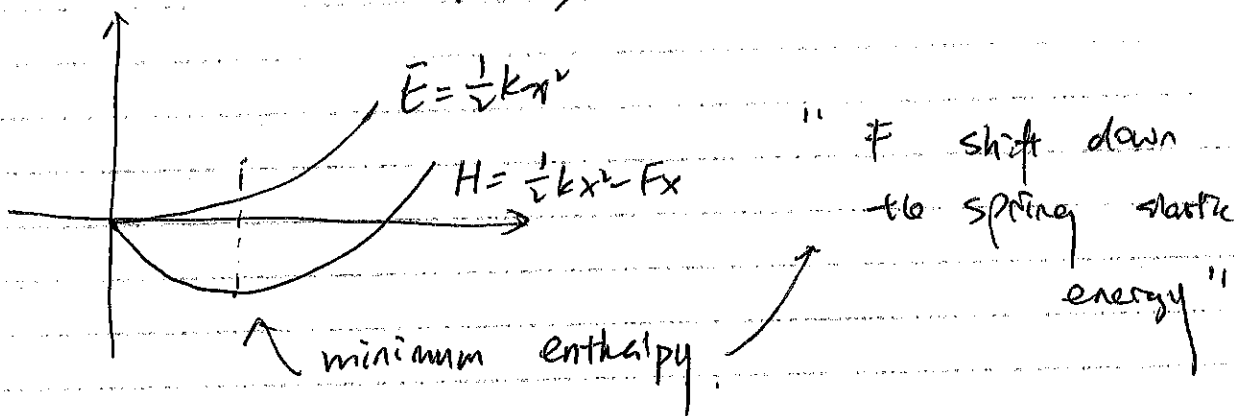
"When equilibrium is reached"

H is minimized.

formulate optimization problem.

$$\min_x \left(\frac{1}{2} kx^2 - Fx \right).$$

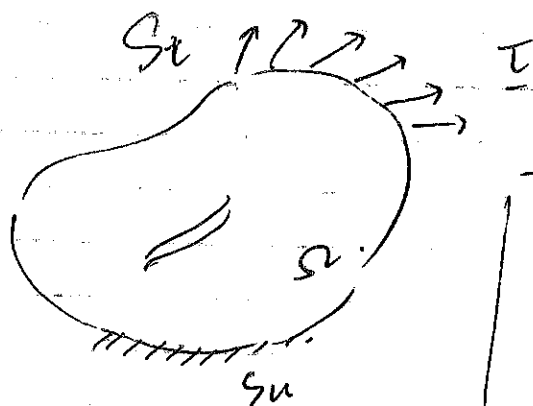
$$x = F/k.$$



$$E_{\text{tot}} = \frac{1}{2} kx^2 - mgx$$

Goal: minimize $H = E - \Delta W_{\text{in}}$

via some traction B.C.s



hypothesis: the system is minimizing H

$$H = \bar{E} - \Delta W_{\text{int}}$$

$$= \int_{\Omega} \frac{1}{2} \sigma_{ij} \epsilon_{ij} dV$$

$$- \int_{S_t} T_j u_j dS$$

Q: what is the enthalpy of the crack?

→ one may derive the enthalpy of the whole system

... "enthalpy of crack"

	System w/o crack	System w/ crack
energy	$E_0 = \int \frac{1}{2} \sigma_{ij}^A \epsilon_{ij}^A dV$	$E_{2a} \rightarrow \Delta E = E_{2a} - E_0$
enthalpy	H_0	H_{2a}

$$\Delta E = \frac{1-\nu}{2\mu} S^2 \pi a^2$$

Conclusion:

$$\Delta H = - \frac{1-\nu}{2\mu} S^2 \pi a^2$$

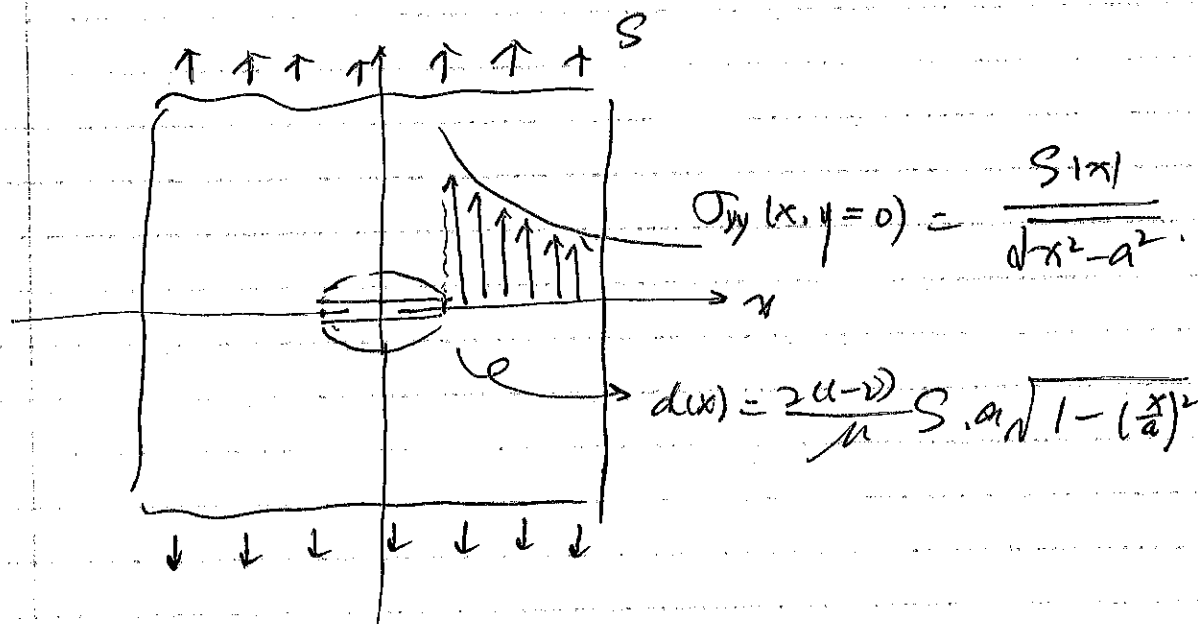
plane strain

$$\Delta H = H_{2a} - H_0$$

lecture 16.

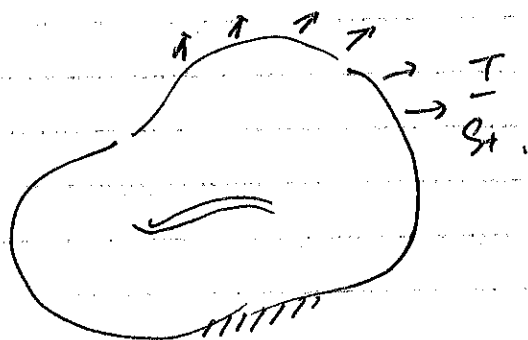
5/22/2024.

Slit-like crack.



Q: What is the enthalpy of the crack?

$$H = E - \Delta W_{int}.$$



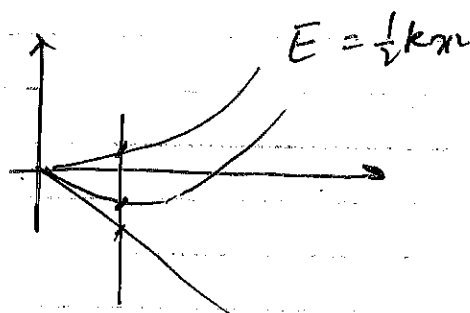
$$H = \int \frac{1}{2} \sigma_{ij} \epsilon_{ij} dV.$$

the system is trying to minimize H .

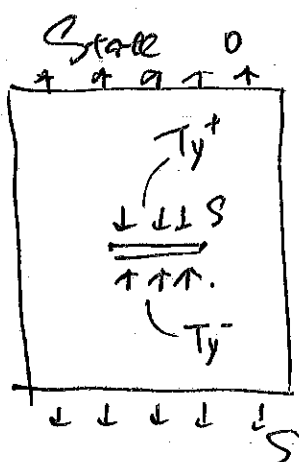
$$- \int_{S_1} T_i u_j dS.$$

... body with no pre-existing internal stress.
then $H = -E$

toy example



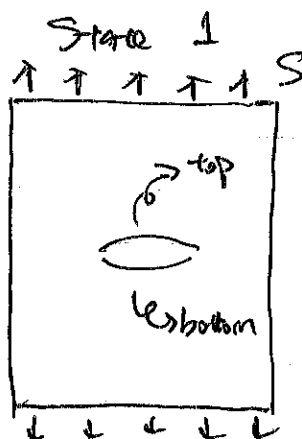
... thought experiment



$$E_0, H_0 = -E_0$$

$$E_0 = \frac{1}{2} \sigma_{yy}^A \cdot \epsilon_{yy}^A V$$

$$H_0 = -\frac{1}{2} \sigma_{yy}^A \cdot \epsilon_{yy}^A V$$

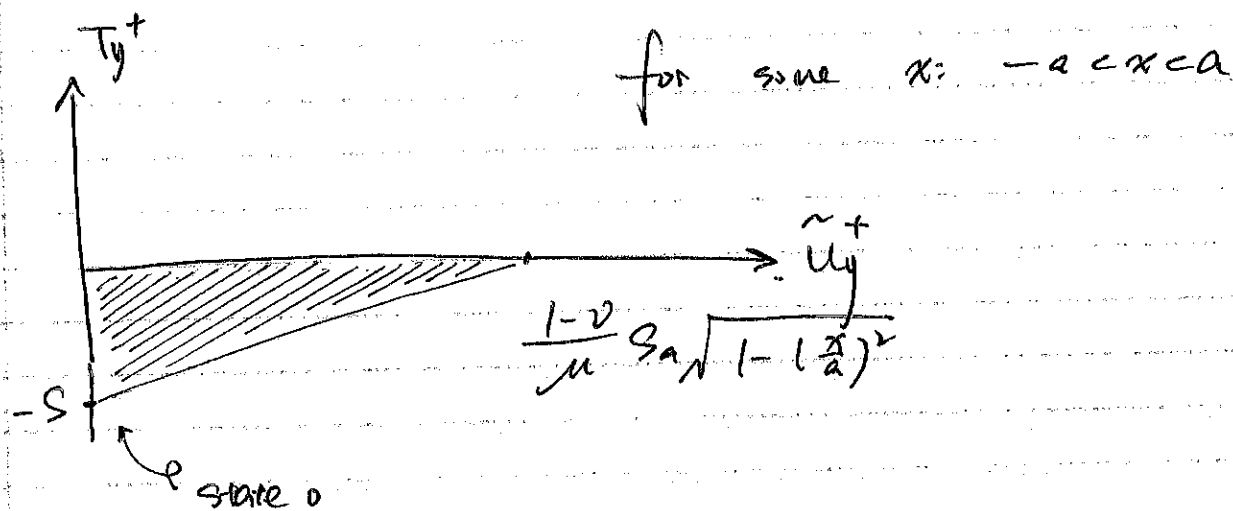


$$E_1, H_1 = -E_1$$

$$\Delta E = E_1 - E_0$$

$$\Delta H = H_1 - H_0 = -\Delta E$$

Calculate the work done along the path from the "closed crack" to the "opened crack".



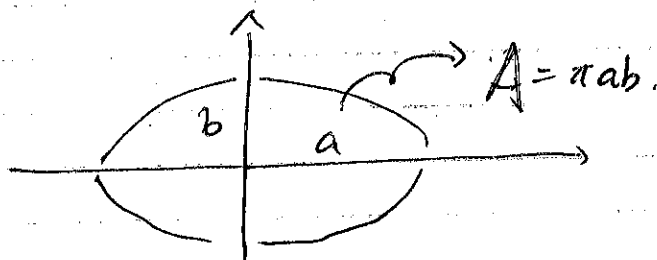
$$\Delta W^+ = \int_{-a}^a \frac{1}{2} S \frac{1-v}{\mu} S_a \sqrt{1 - \left(\frac{x}{a}\right)^2} dx.$$

$$\Delta H = 2\Delta W^+ = \int_{-a}^a \frac{1-v}{\mu} S^2 a \sqrt{1 - \left(\frac{x}{a}\right)^2} dx$$

$$\Delta H = -\frac{1-v}{2\mu} S^2 \pi a^2$$

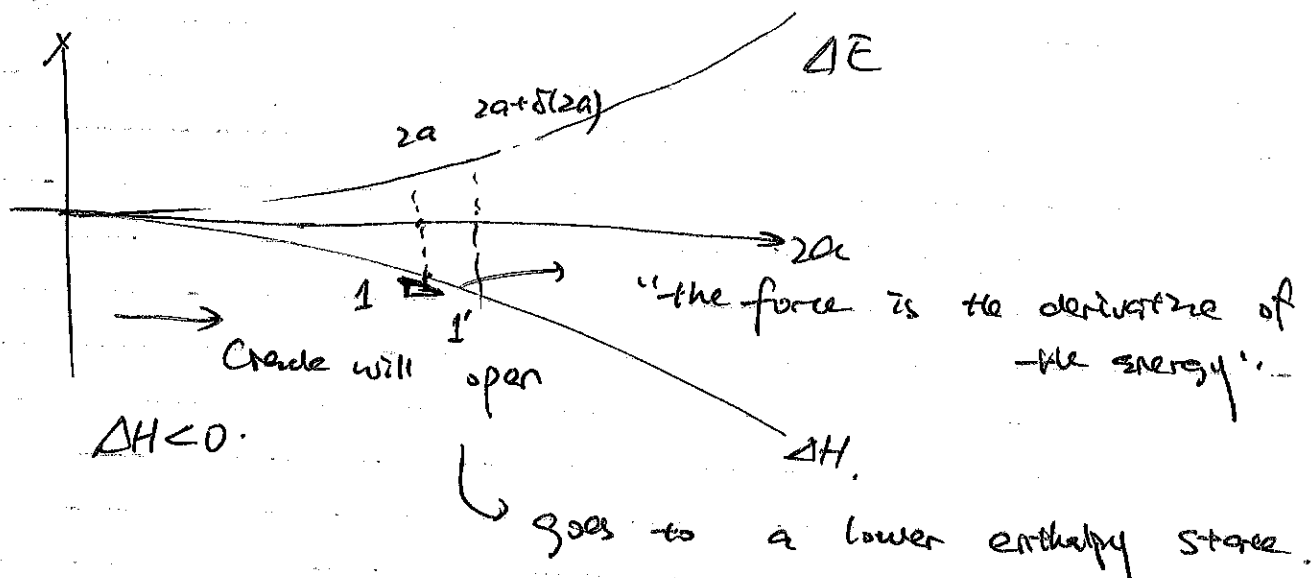
physically: the enthalpy of crack is

$-\frac{1}{2} S$ multiplies the area of the crack opening.



$$\Delta H < 0$$

$$\Delta H = -\frac{1}{2} S A$$



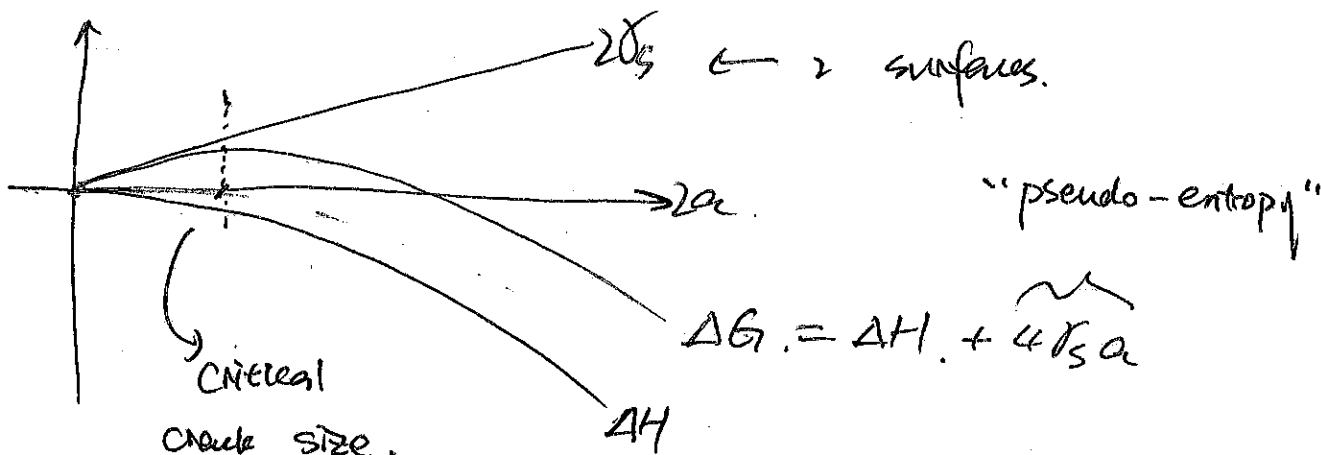
Driving force for crack extension,

$$f_{el} = - \frac{\partial(\Delta H)}{\partial(2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a$$

$$K_I = S \sqrt{\pi a}, \quad f_{el} = \frac{1-\nu}{2\mu} K_I^2$$

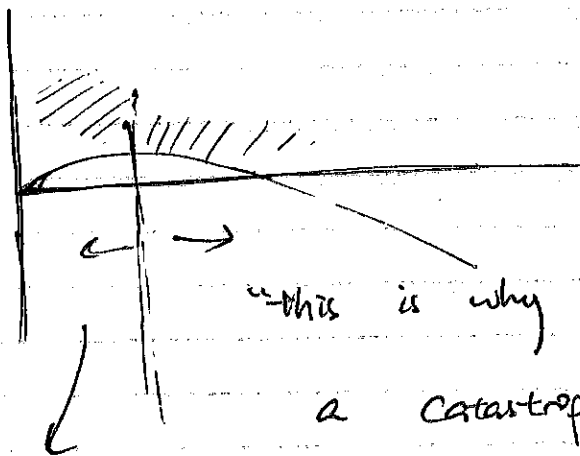
Stress intensity relationship.

Griffith's Criteria. (1921).



$$2a_c = \frac{8\mu}{\pi(1-\nu)} \frac{\gamma_s}{s^2}$$

↳ critical crack size for fracture.



"this is why crack is usually a catastrophic process".

"stable crack size"

$$s_c = \sqrt{\frac{8\mu \gamma_s}{\pi(1-\nu)(2a)}}$$

↳ plane stress.

$$f_a = 2\gamma_s$$

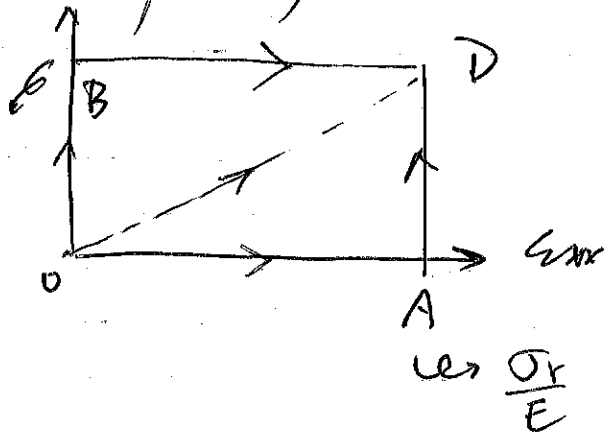
↑ surface energy

Crack-driving force.

Problem Session 8

Plasticity code for numerical soln

$$2\varepsilon_{xy} \rightarrow \delta_{xy}$$



$$\sigma_{ij} = C_{ijkl} \cdot \varepsilon_{kl}$$

Differential \rightarrow algebraic

Numerical methods

At any time t known: $\sigma_{xx}(t)$, $\sigma_{xy}(t)$
 \downarrow
 yield point $\varepsilon_{xx}(t)$, $\varepsilon_{xy}(t)$.

Up to yield \rightarrow Hooke's law is valid $\varepsilon_{xx}(t+\Delta t)$, $\varepsilon_{xy}(t+\Delta t)$.

Unknowns: $\sigma_{xx}(t+\Delta t)$, $\sigma_{xy}(t+\Delta t)$.

Equations.

$$\frac{\sigma}{2\mu}$$

① change in stress. finite time steps

$$\Delta \bar{\sigma} = \bar{\sigma}(t+\Delta t) - \bar{\sigma}(t)$$

$\hookrightarrow \Delta t, \rightarrow \Delta \sigma_{xx}, \Delta \sigma_{xy}, \text{etc.}$

$$\left\{ \begin{array}{l} \bar{\sigma}(t+\Delta t) = \frac{\sigma_{xx}(t+\Delta t)}{3} \\ \bar{\sigma}(t) = \frac{\sigma_{xx}(t)}{3} \end{array} \right.$$

$$\sigma_{xx}(t+\Delta t) = \sigma_{xx}(t+\Delta t) - \bar{\sigma}(t+\Delta t)$$

$$S_{xy}(t + \Delta t) = \tau_{xy}(t + \Delta t)$$

② → change in elastic strain.

$$\Delta \epsilon_{xx}^{el} = \Delta \bar{\epsilon}^{el} + \Delta \epsilon_{xx}^{pl}$$

$$\Delta \epsilon_{xx}^{el} = \frac{\Delta S_{xx}}{2\mu}$$

$$\Delta \bar{\epsilon} = \frac{\Delta \bar{\sigma}}{3K}$$

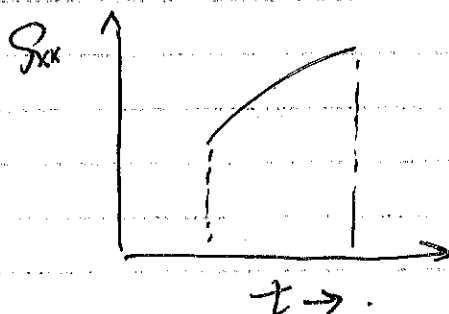
$$\Delta \epsilon_{xy}^{el} = \frac{\Delta S_{xy}}{2\mu}$$

③ - change in plastic strain.

$$\dot{\epsilon}_{xx}^{pl} = \frac{\bar{\sigma}}{2\mu} S_{xx} \rightarrow \text{analytical.}$$

$$\downarrow$$

$$\frac{\Delta \dot{\epsilon}_{xx}^{pl}}{\Delta t}$$



From $t \rightarrow t + \Delta t$.

$$\int_t^{t+\Delta t} \dot{\epsilon}_{xx}^{pl} dt = \frac{\bar{\sigma}}{2\mu} \int_t^{t+\Delta t} S_{xx}(t) dt \leadsto \Delta \epsilon_{xx}^{pl}$$

Assume $\bar{\sigma}$ is const. from $t \rightarrow t + \Delta t$.

$$= \frac{\bar{\sigma}}{2\mu} \left(\frac{S_{xx}(t) + S_{xx}(t + \Delta t)}{2} \right)$$

Similarly for

$$\Delta \epsilon_{xy}^{el} = \frac{\tilde{\gamma}}{2\mu} \left(\frac{\sigma_{xy}(t) + \sigma_{xy}(t+\Delta t)}{2} \right)$$

Find 3 eqns

$$1). \sigma_{xx}(t) + \Delta \epsilon_{xx}^{el} + \Delta \epsilon_{xx}^{pl} = \sigma_{xx}(t+\Delta t)$$

$$2). \sigma_{xy}(t) + \Delta \epsilon_{xy}^{el} + \Delta \epsilon_{xy}^{pl} = \sigma_{xy}(t+\Delta t)$$

$$3). J_2 = K^2$$

$$\frac{1}{2} (\sigma_{xx}^2 + \sigma_{yy}^2 + \sigma_{zz}^2) + \sigma_{xy}^2 = K^2$$

$$(or) \left(\frac{\sigma_{xx}^2}{3} + \sigma_{xy}^2 \right)_{(t+\Delta t)} = K^2$$

and solve: $\frac{\tilde{\gamma}}{2\mu}$

MATLAB `fsolve (fun, [trial], hyper param ...)`

↗ current stress state, 0

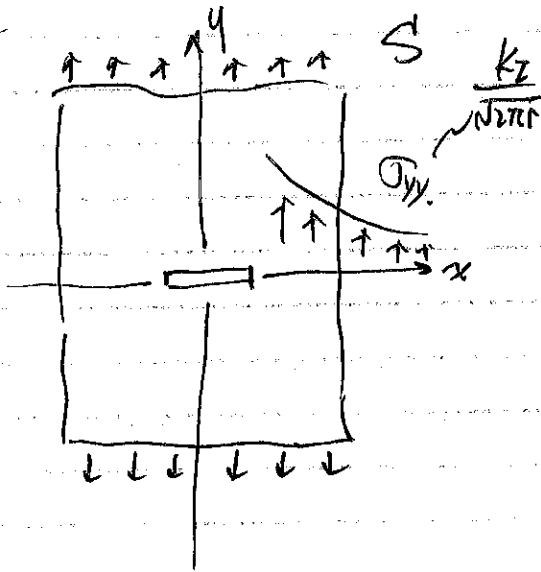
σ_{xx}, σ_{xy}

↘

5/29/2024.

lecture 17.

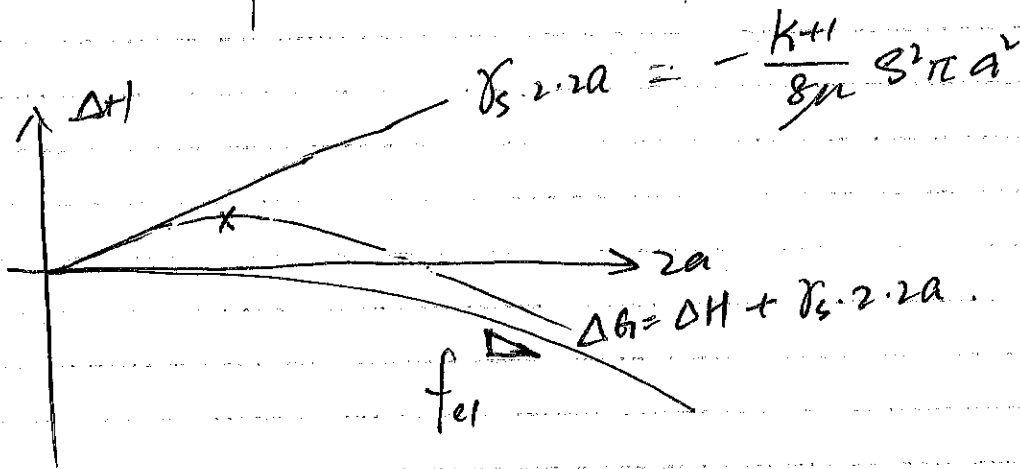
Recap



$$\Delta H = H_1 - H_0$$

$$= -\frac{1-\nu}{2\mu} S^2 \pi a^2$$

(plane strain)



$$f_{el} = -\frac{\partial \Delta H}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a \quad (\text{plane strain})$$

$$\Delta G = -\frac{1-\nu}{2\mu} S^2 \pi a^2 + 4\gamma_s a$$

$$f_{tot} = \frac{\partial \Delta G}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a - 2\gamma_s$$

... Griffith criteria. $\frac{\pi(1-\nu)}{2\mu} S^2 a \geq 2\gamma_s \quad \dots (*)$

energy release rate G

LHS of (*) \nearrow

$$\text{i.e., } G = \frac{\pi(1-\nu)}{2\mu} (\sigma_{yy}^A)^2 a \quad \dots (**)$$

\nearrow
replace S

RHS: critical energy release rate

$$G_c = 2\gamma_s \quad \dots (***)$$

Eqn. (**) can be rewritten as:

$$G = \frac{\pi(1-\nu)(1+\nu)}{E} (\sigma_{yy}^A)^2 a \quad (\text{plane strain})$$

$$\text{define } E' = \frac{E}{1-\nu^2} \quad \hookrightarrow \frac{\pi}{E'}$$

$$K_I = \sigma_{yy}^A \sqrt{\pi a} \quad \text{Stress intensity factor}$$

$$\dots \quad G = \frac{K_I^2}{E'}$$

\hookrightarrow for mode-I loading

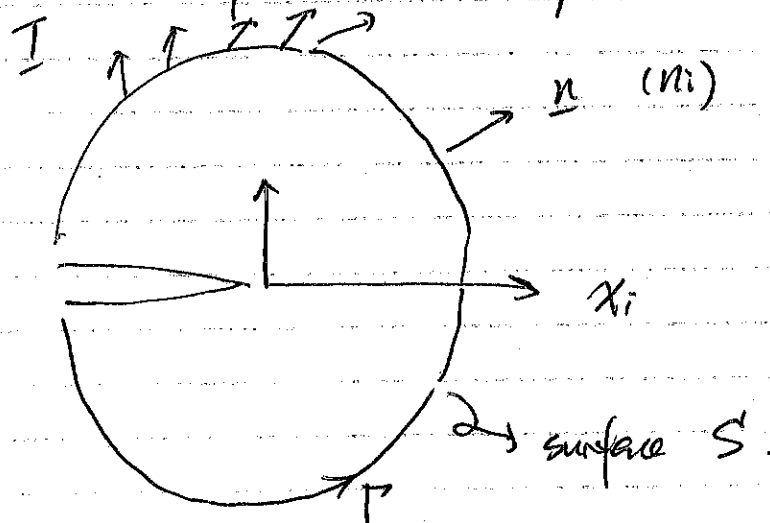


$$Q = \frac{k_1^2}{E'} + \frac{k_0^2}{E'} + \frac{k_{II}^2}{2\mu}$$

frasea critica: $G \geq G_c$

J- Integral

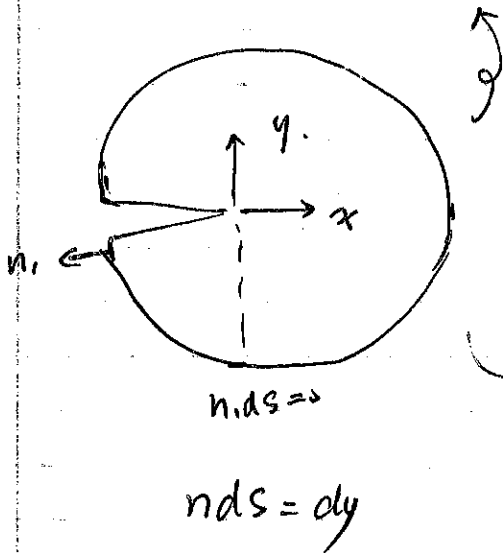
Q: what is the generalized force for any kinds of singularity?



$$J_i = \int_S (w n_i - T_j u_{j,i}) dS$$

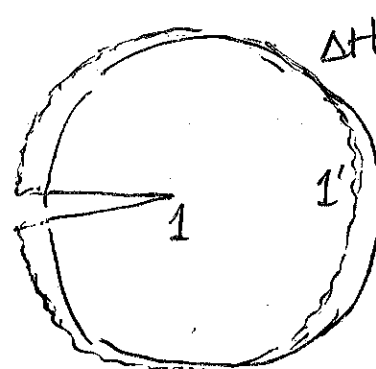
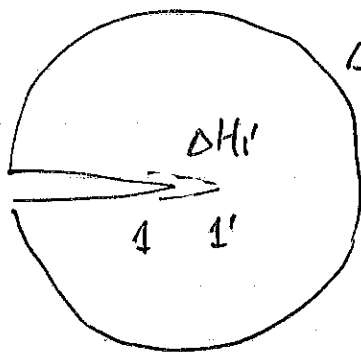
↑ general force
 ↑ surface
 energy density $\frac{1}{2} \sigma_{ij} \epsilon_{ij}$

$$J_1 = \int_P w \, dy - I \frac{\partial u}{\partial x} dS$$

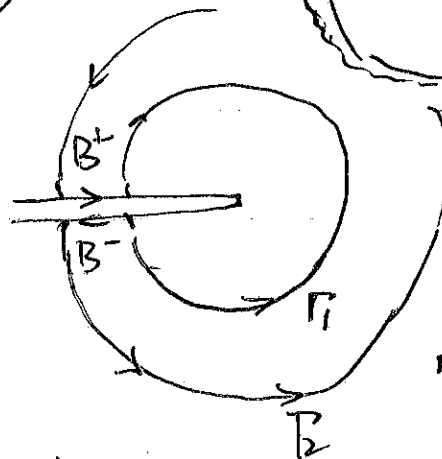


$$G = J$$

doesn't have to be a perfect circle.



Example 1



Contour integral along the crack surface

take any contour you want.

(Very nice!!!)

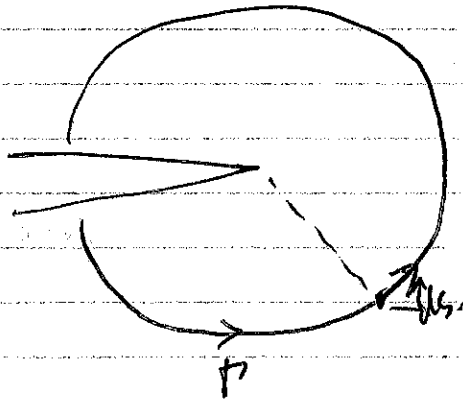
5/31/2014. Lecture 19.

Some review on fracture mechanics.

$$G \geq G_c$$

J-integral

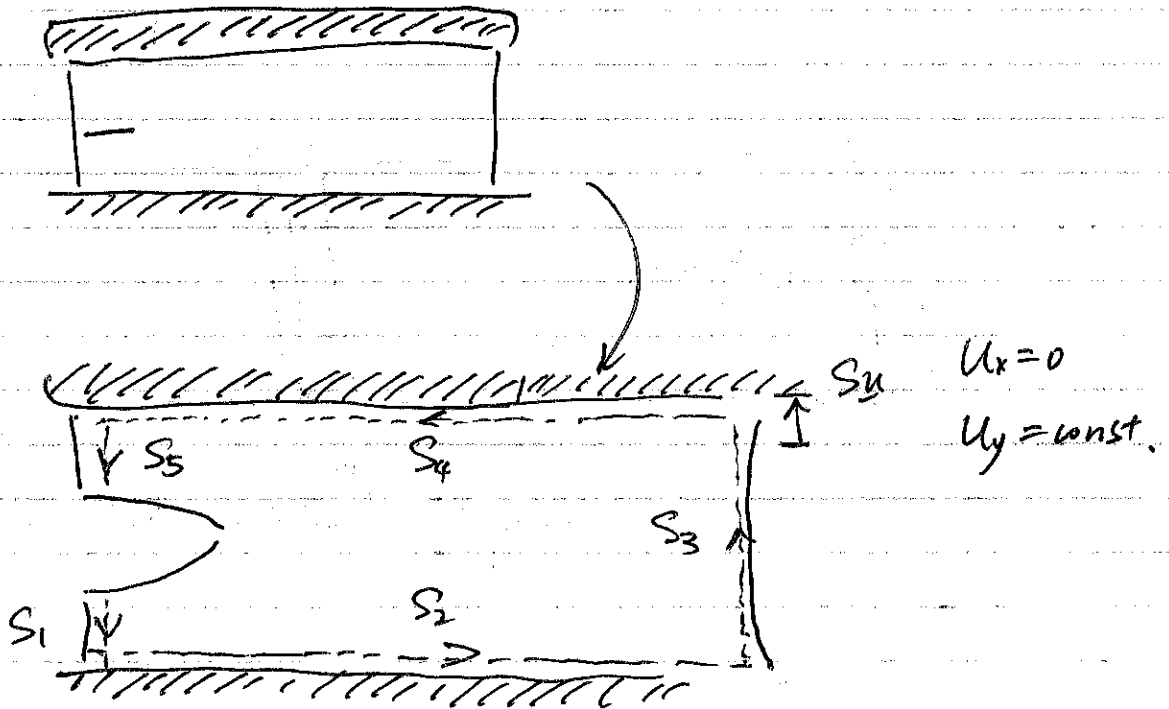
2D



$$J = \int \mathbf{w} d\mathbf{y}$$

$$- \int \mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{s}} d\mathbf{s}$$

Example 2



$$J(S_2) = \int \mathbf{w} d\mathbf{y} - \int \mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{s}} d\mathbf{s} = 0$$

$$J(S_4) = 0, \quad J(S_1) = \int \mathbf{w} d\mathbf{y} - \int \mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{s}} d\mathbf{s} \quad \text{almost zero}, \quad J(S_5) = 0$$

the only J survived.

$$J(s_3) = \int w dy - \cancel{I \frac{\partial u}{\partial x} ds} = wh$$

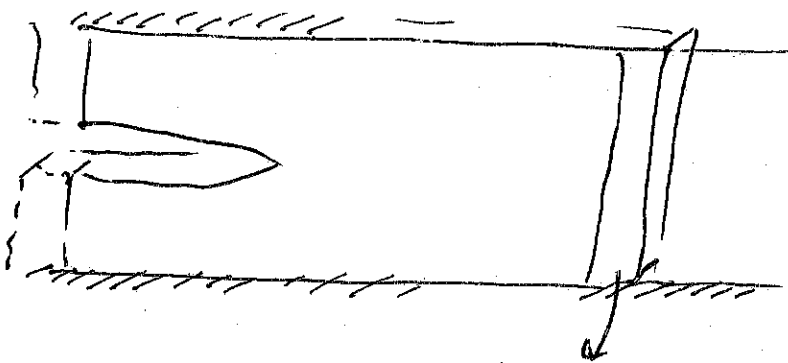
strain energy.

$$G = J = wh$$

$$G \geq G_c$$

not the material
properties

we are just solving for the force
(LHS).

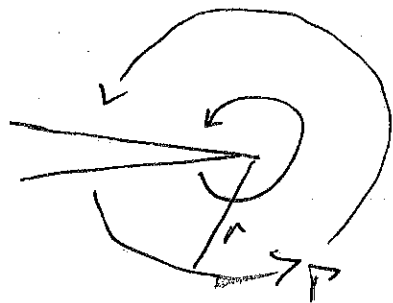


physics intuition behind $G = wh$.

if this 3D. it

should consider the
whole plate

Example 3



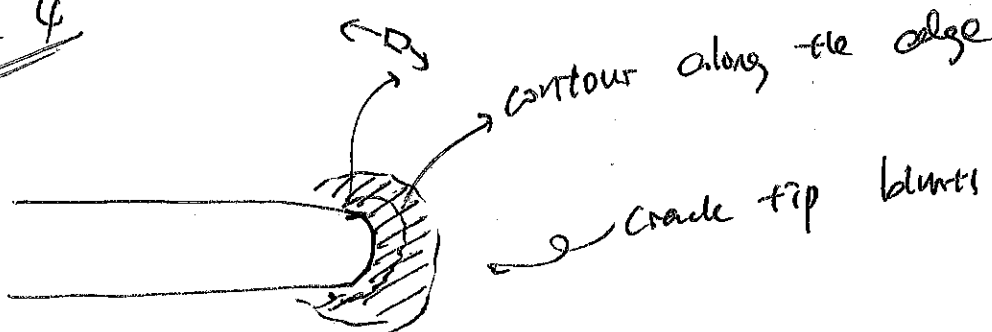
$$\sigma_{rr} = \frac{K_I}{\sqrt{2\pi r}} \left(\frac{I}{4} \cos \frac{\theta}{2} - \frac{1}{4} \cos \frac{3\theta}{2} \right)$$

↓

$$J = \frac{K_I^2}{E'}$$

(shrink the contour)

Example 4



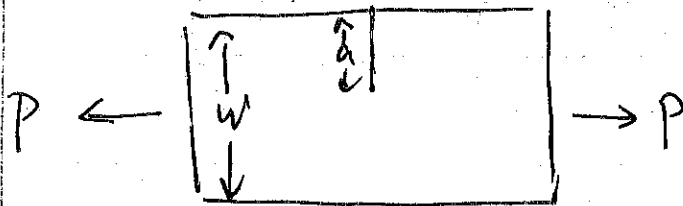
$$J = \int_{\Gamma} w dy - \int_{\Gamma} T \frac{\partial u}{\partial x} ds$$

$$= \int_{\Gamma} w dy \quad \left(w = \frac{\sigma^2}{2E} \right)$$

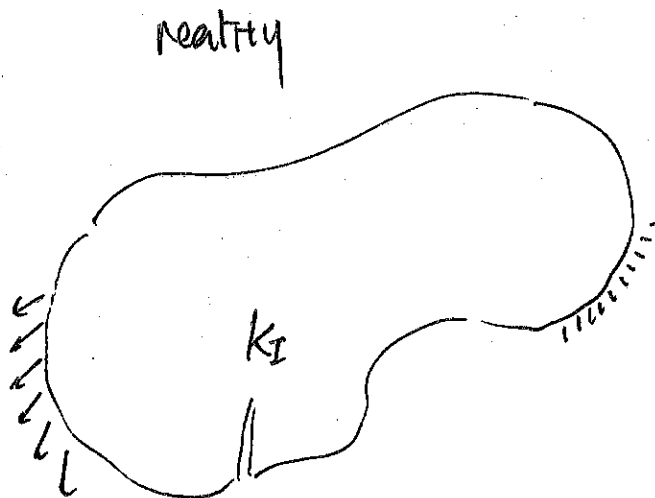
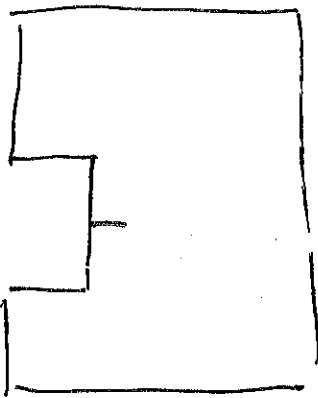
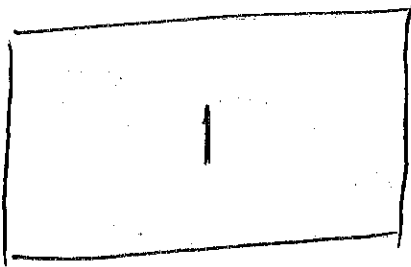
LEFM.

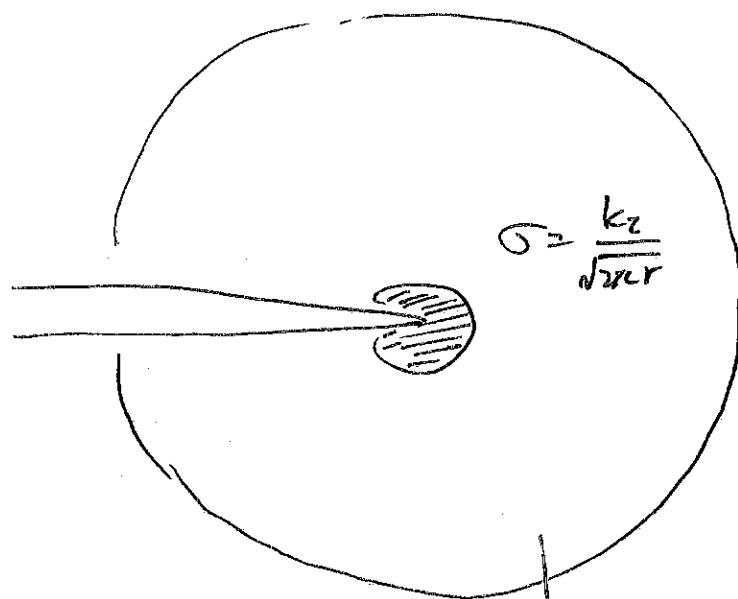
Perp. $G = \frac{K_I^2}{E'}$, $K_I = \sqrt{G E'}$, $K_{Ic} = \sqrt{G_c E'}$

$\rightarrow K_I \geq K_{Ic}$



$$K_I = \frac{P}{B\sqrt{w}}$$



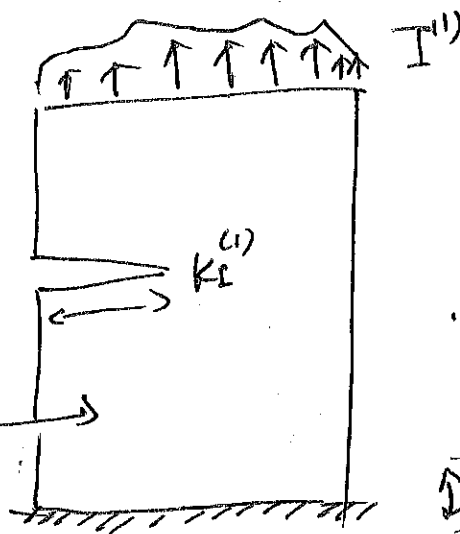


K-field
(Zone)

Rice (1992).

LEFM - K_I .

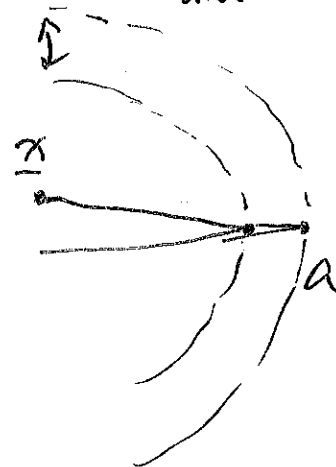
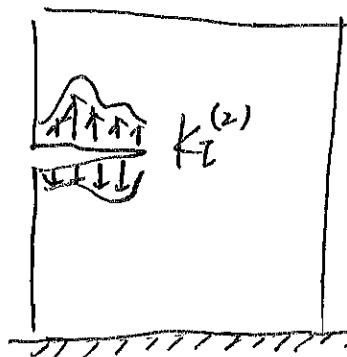
assume I have
the solution.



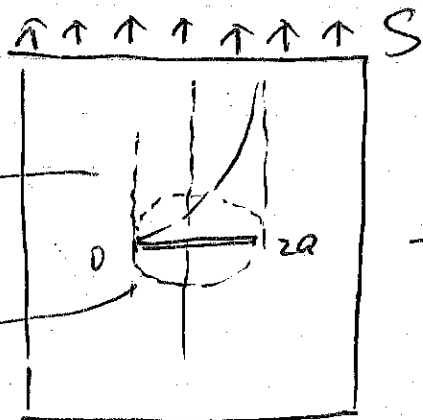
"coupling between
motion of crack
and loading"

$$K_2^{(1)} = \frac{E'}{2K_2^{(1)}} \int_{-I_1}^{I_2} I_i^{(2)} \frac{\partial u_i^{(1)}}{\partial a} dI$$

loading (1)



loading (1)



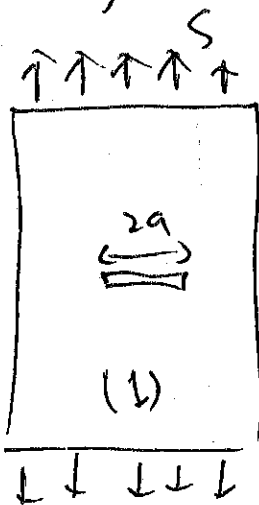
$$\frac{\partial u^{(1)}}{\partial a} = \sqrt{\frac{x}{2a-x}}$$

$$K_I^{(1)} = \frac{E'}{2K_I^{(1)}} \int S \sqrt{\frac{x}{2a-x}} dP$$

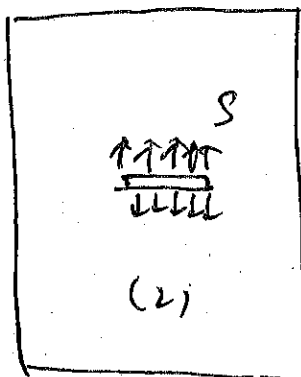
$$= S \sqrt{\pi a}$$

... results are the same.

loading (1)



$$K_I = S \sqrt{\pi a}$$



$$K_I = S \sqrt{\pi a}$$

Lecture 19

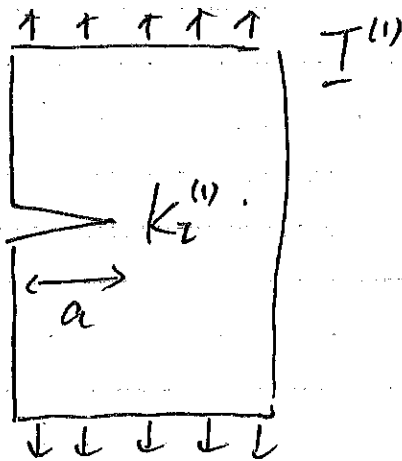
6/3/2024

EPFM.

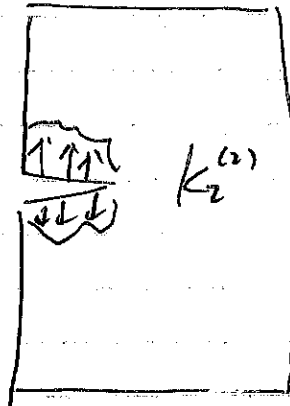
Recap

LEFM.

$$K_I \gg K_{Ic}$$



loading (1)

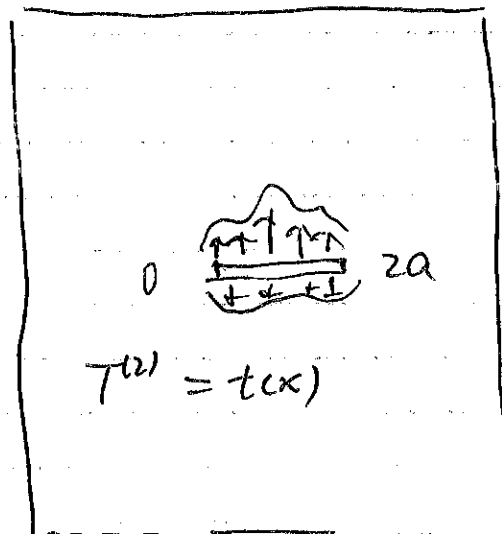
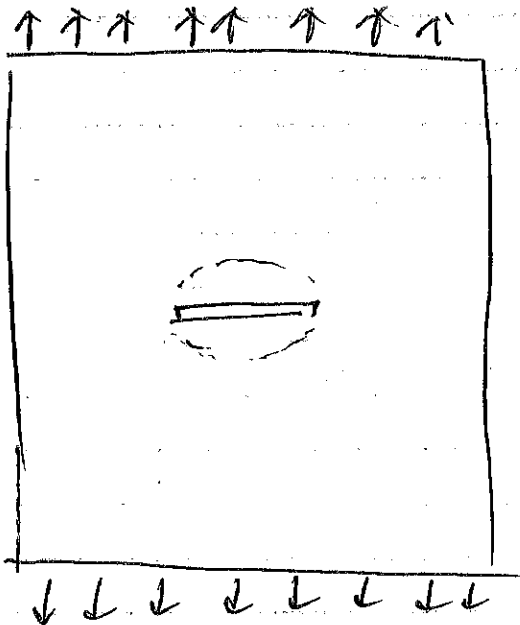


loading (2)

$$K_I^{(1)} = \frac{E'}{2K_I^{(1)}} \int \sigma_I^{(1)} \frac{\partial u_i^{(1)}}{\partial a} dT$$

Slit-like crack

S



$$K_I^{(2)} = \frac{1}{\sqrt{\pi a}} \int_0^{2a} t(x) \sqrt{\frac{x}{2a-x}} dx$$

(for $x=2a$)

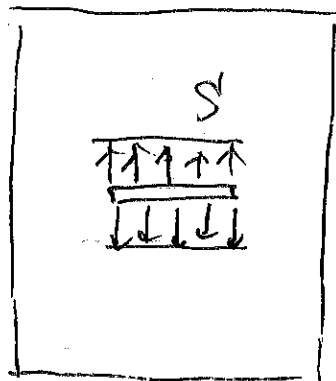
if we shift the coordinate:

$$K_I^{(2)} = \frac{1}{\sqrt{\pi a}} \int_{-a}^a t(x) \sqrt{\frac{a+x}{a-x}} dx$$

→ elasticity theory.

Crack: $-a \leq x \leq a$ for $x=a$

Example 1

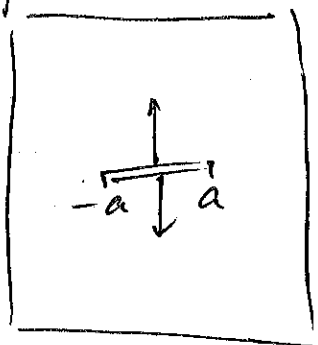


$$K_I^{(1)} = \frac{1}{\sqrt{\pi a}} \int_{-a}^a S \sqrt{\frac{a+x}{a-x}} dx$$

$$= \frac{1}{\sqrt{\pi a}} \cdot S \cdot \pi a$$

$$= S \sqrt{\pi a}$$

Example 2



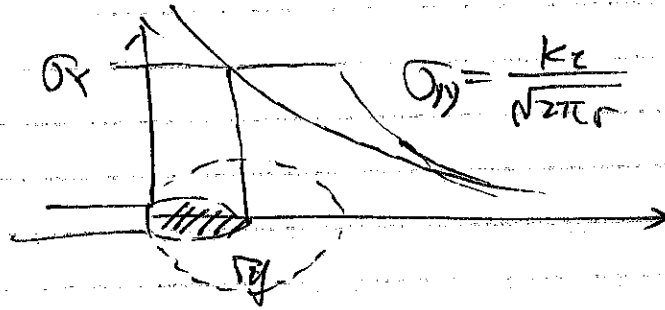
$$K_I^{(1)} = \frac{E'}{\sqrt{\pi a}} \int_{-a}^a F \delta(x) \sqrt{\frac{a+x}{a-x}} dx$$

$$= \frac{E' F}{\sqrt{\pi a}}$$

EPFM

Irwin's approach.

w/o plasticity



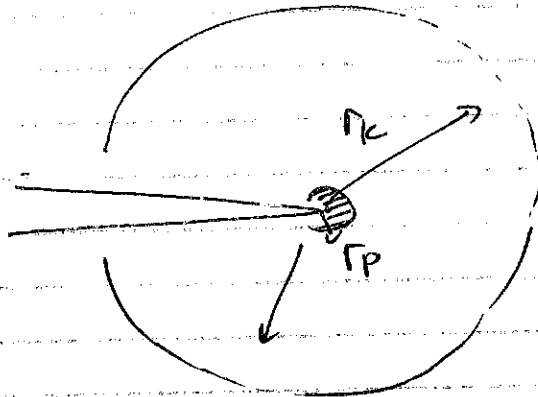
$$\sigma_y = \frac{K_I}{\sqrt{2\pi r_y}}$$

$$r_y = \frac{1}{2\pi} \left(\frac{K_I}{\sigma_y} \right)^2$$

Irwin did some "debug"

$$r_p = 2r_y = \frac{1}{\pi} \left(\frac{K_I}{\sigma_y} \right)^2$$

empirical



K-field

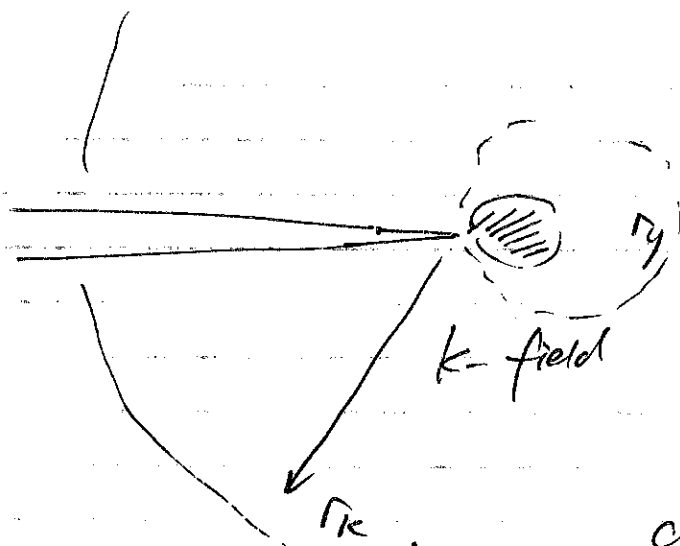
$$\sigma_{ij} \sim \frac{K_I}{\sqrt{2\pi r}} f(\theta)$$

$$K_I \geq K_{Ic}$$

how does plasticity change this criteria?

σ_y .

yield increases K_{Ic} (mat. param.)



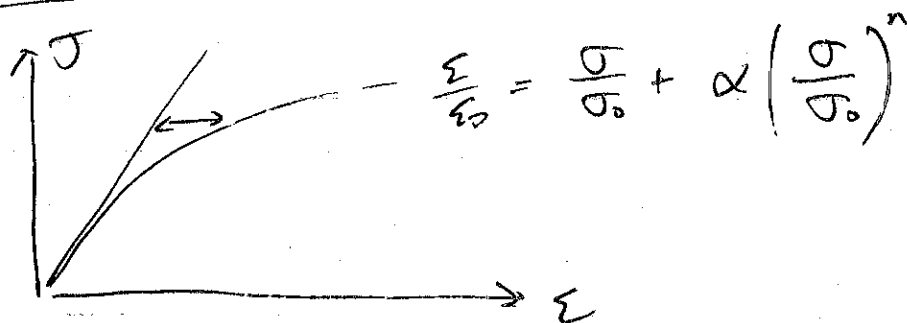
change of k -field

$$a_{eff} = a + r_y$$

$$K_{I,eff} = \frac{P}{B\sqrt{w}} f\left(\frac{a_{eff}}{w}\right)$$

HRR Solution

1968



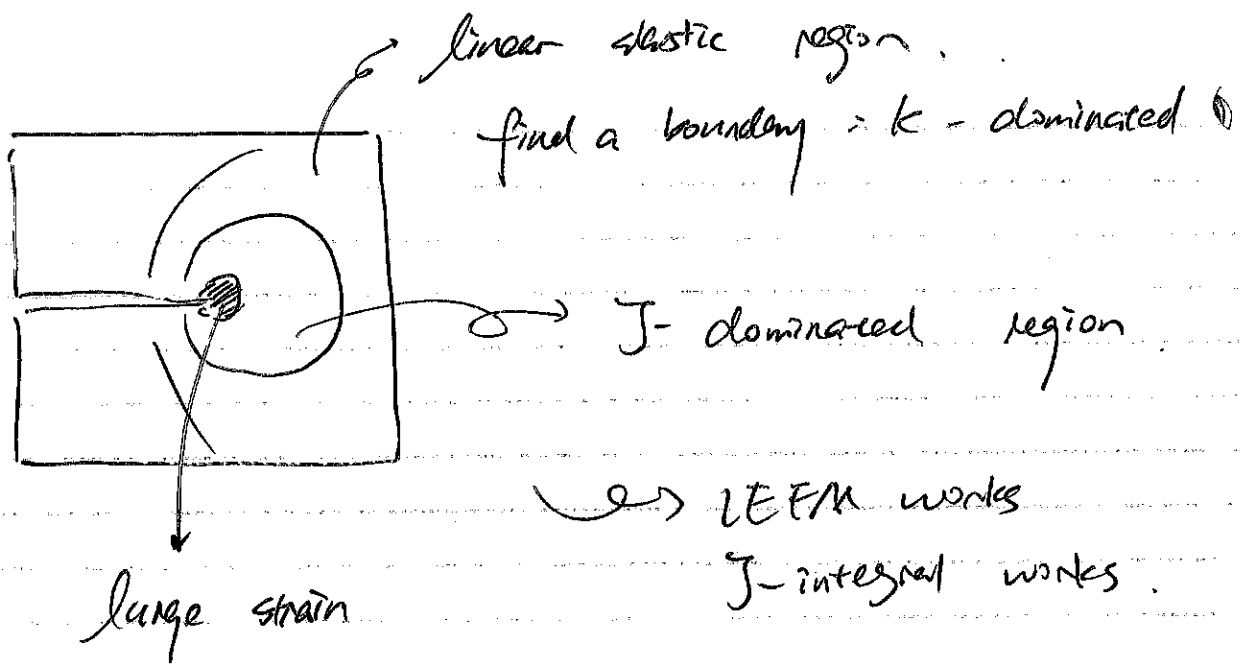
closer to the crack tip,

$$\sigma_{ij} = K_I \left(\frac{J}{r}\right)^{\frac{1}{n+1}}$$

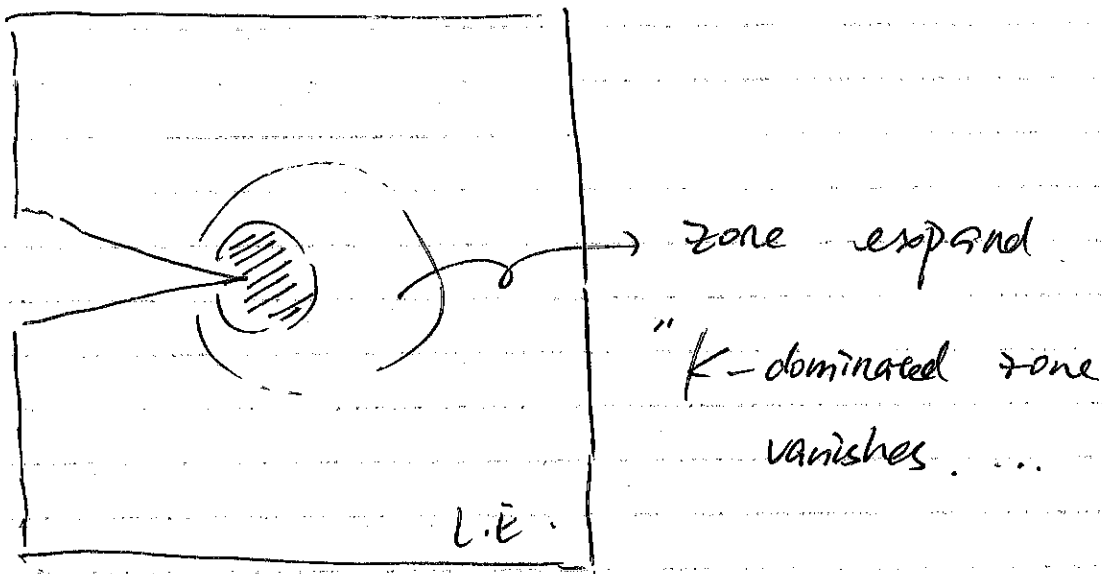
$$\sigma \cdot \varepsilon \propto \frac{1}{r}$$

$$\varepsilon_{ij} = K_{\varepsilon} \left(\frac{J}{r}\right)^{\frac{n}{n+1}}$$

... HRR singularity



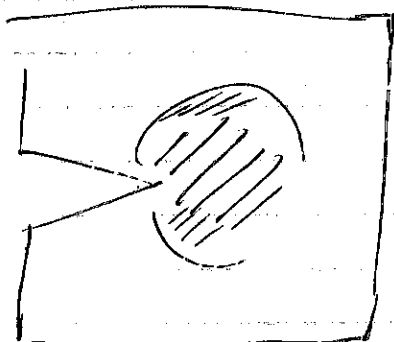
increasing the load.



keep loading

LEFM not works

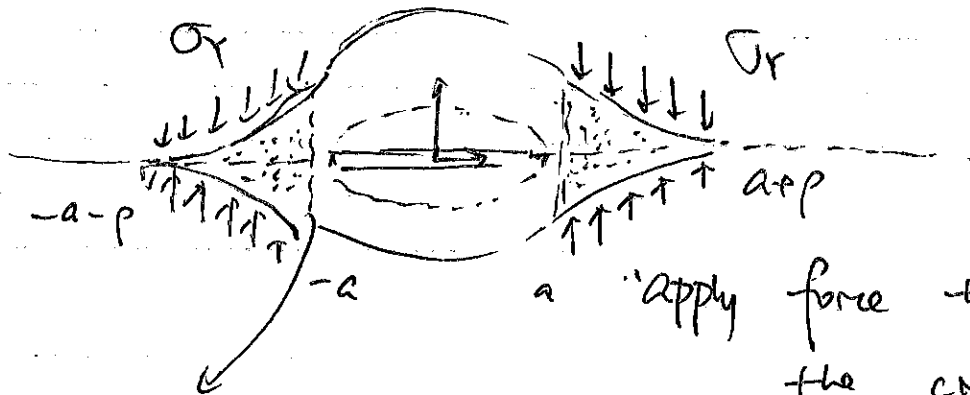
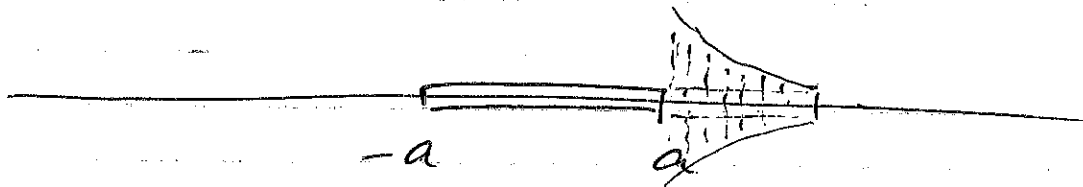
J-integral works



LEFM & J-integral

all done work.

Strip-yield model



Plastic flow.

blunts the crack tip.

$$K_I^{\text{tot}} = \sigma_Y \sqrt{\pi(a+p)} - 2 \sigma_Y \sqrt{\frac{a+p}{\pi}} \arccos\left(\frac{a}{a+p}\right)$$



= 0

Solve for the correct p .

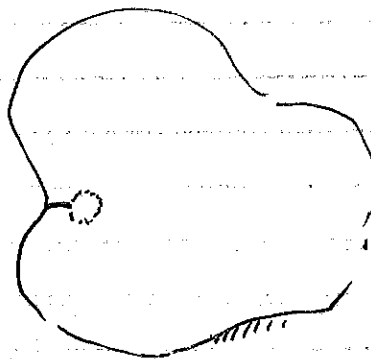
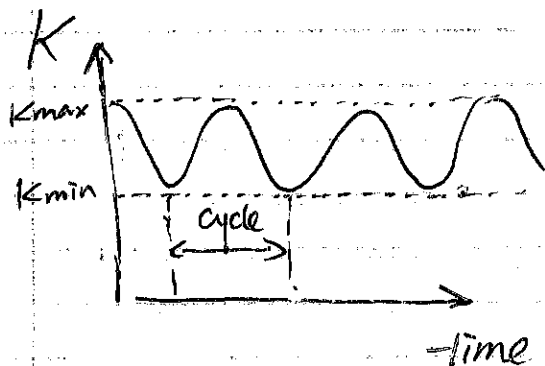
$$p = \frac{\pi}{8} \left(\frac{K_I^{\text{old}}}{\sigma_Y} \right)^2 \approx 0.393$$

lecture 20 6/5/2014.

Fatigue

Example, airplane, vehicles, etc. ...

Paris law.

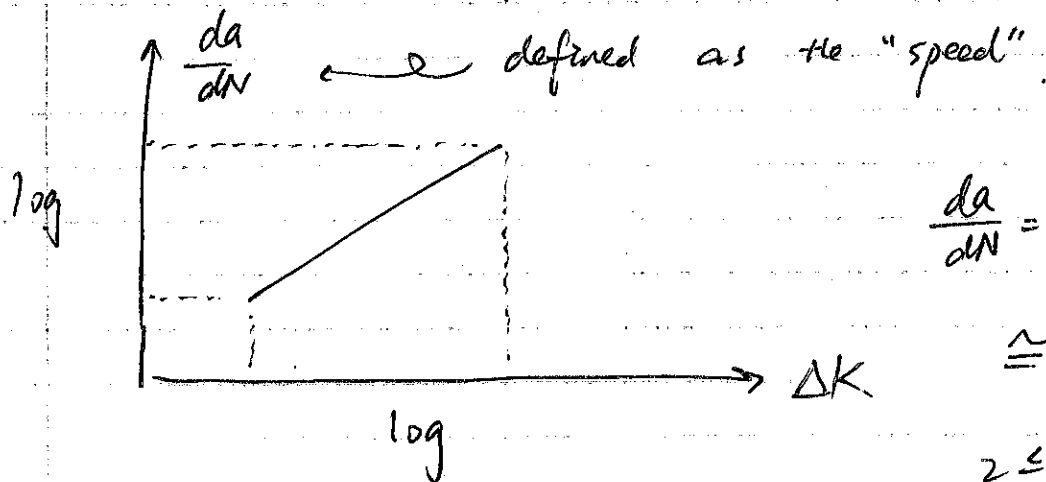


(2) not a time-dependent problem
in this approximation.

$$\Delta K = K_{\max} - K_{\min}$$

$$R = \frac{K_{\min}}{K_{\max}}$$

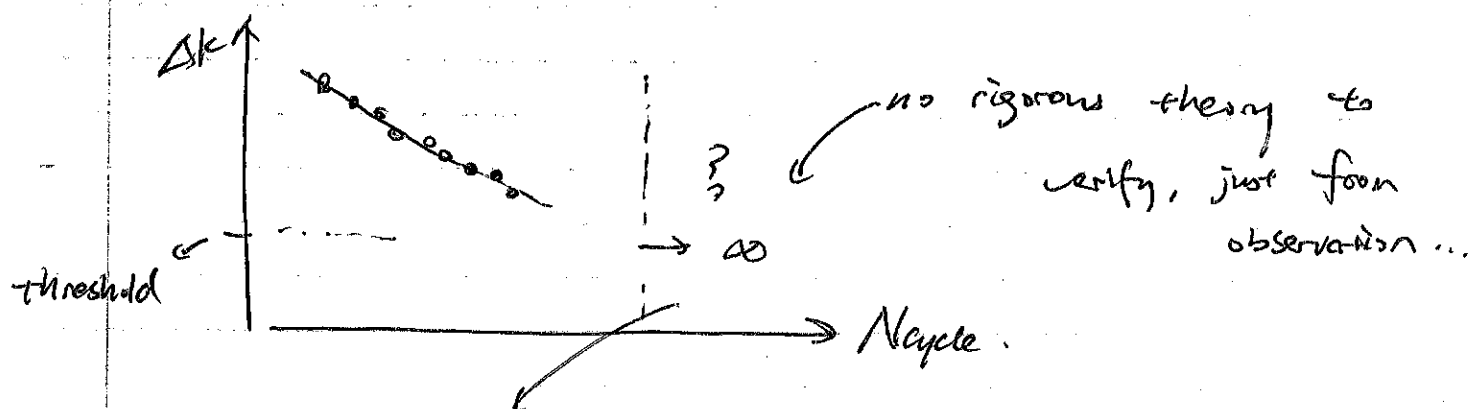
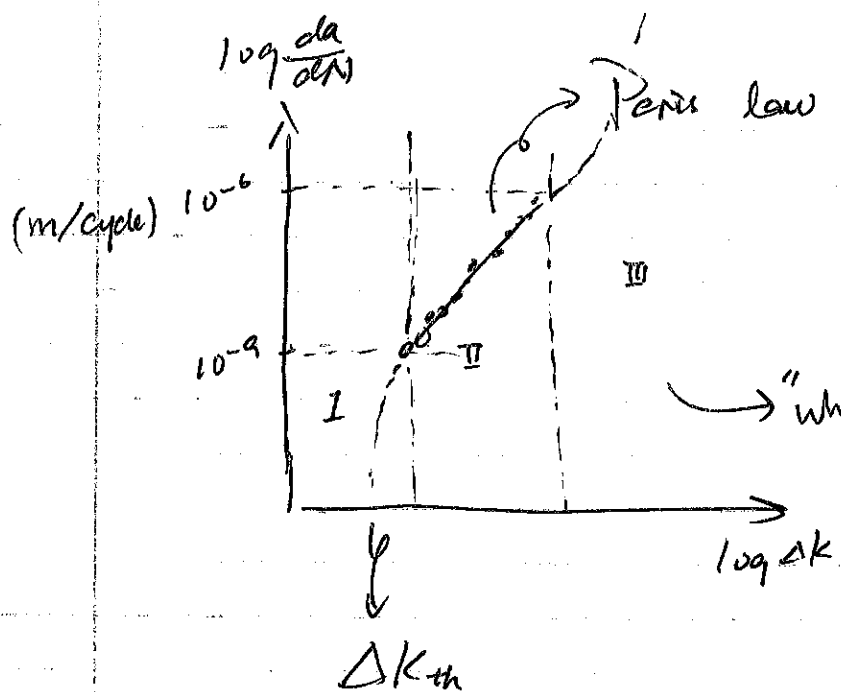
if you just focus on ΔK .



$$\frac{da}{dN} = f(\Delta K, R)$$

$$\approx C (\Delta K)^m$$

$$2 \leq m \leq 4 \quad m \sim 3$$



we don't know if there's a limit

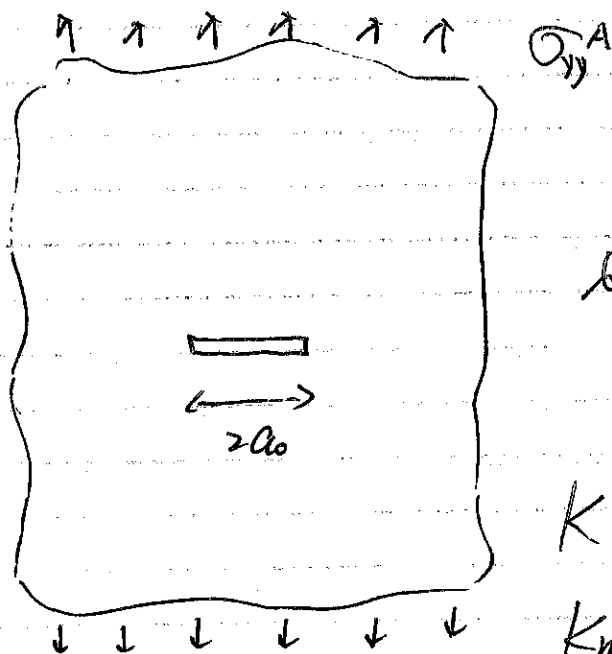
$$\frac{da}{dN} = C (\Delta K)^m \cdot \frac{\left(1 - \frac{\Delta K_{th}}{\Delta K}\right)^p}{\left(1 - \frac{K_{max}}{K_c}\right)^q}$$

material constants:

$C, m, \Delta K_{th}, K_c, p, q$.

↑ a modified theory for fatigue

Example



Q: How many cycles until fracture?

$$K = \sigma_{yy}^A \sqrt{\pi a}$$

$$K_{max} = S \sqrt{\pi a} = \Delta K$$

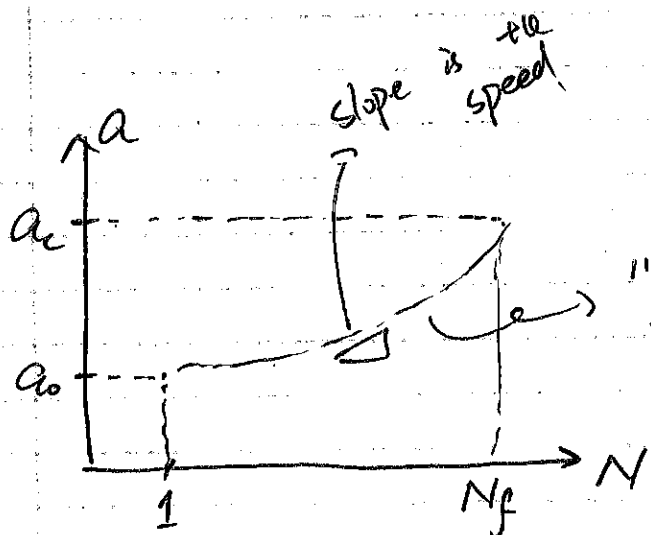
$$K_{min} = 0$$

assume $\frac{da}{dN} = C (\Delta K)^m$

we need to find critical size a_c

when $K = K_{IC}$

$$\sigma_{yy}^A \sqrt{\pi a_c} = K_{IC} \Rightarrow a_c = \frac{1}{\pi} \left(\frac{K_{IC}}{S} \right)^2$$



$$\Delta K = S \sqrt{\pi a}$$

$$\frac{da}{dN} = C (\Delta K)^m = C S^m (\pi a)^{\frac{m}{2}}$$

$$\frac{dN}{da} = \frac{1}{C S^m \pi^{m/2}} a^{-\frac{m}{2}}$$

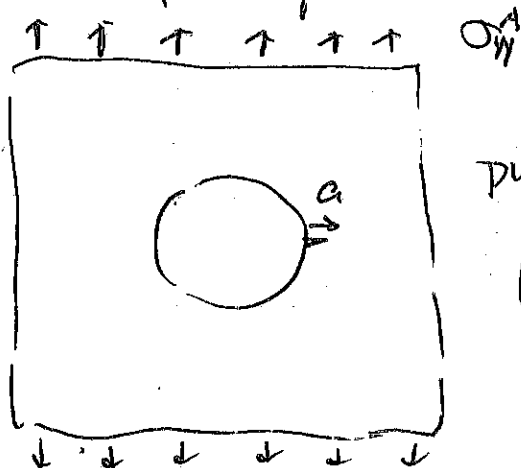
$$N = \int_{a_0}^{a_c} \frac{1}{C S^m \pi^{m/2}} a^{-\frac{m}{2}} da$$

$$N_f = \frac{1}{(-\frac{m}{2}+1) C S^m \pi^{m/2}} \left(a_c^{-\frac{m}{2}+1} - a_0^{-\frac{m}{2}+1} \right)$$

$$N_f = \frac{a_0^{-\frac{m}{2}+1} - a_c^{-\frac{m}{2}+1}}{(\frac{m}{2}-1) C \cdot S^m \cdot \pi^{m/2}}$$

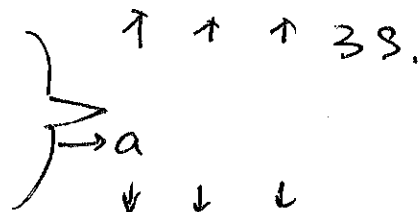
Example 2

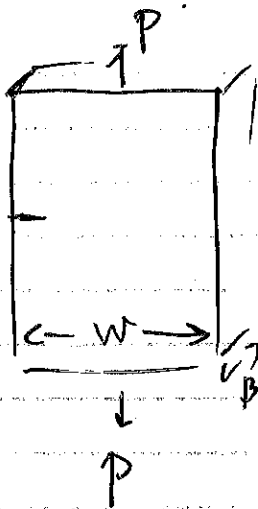
infinite plate



pure white, stress concn. factor 3

locally





$$K_I = \frac{P}{B\sqrt{W}} \left[\frac{\sqrt{2 \tan\left(\frac{\pi a}{2W}\right)}}{\cos\left(\frac{\pi a}{2W}\right)} \left(0.752 + 2.02 \frac{a}{W} \right) \right]$$

from table

$$W \rightarrow \infty \rightarrow \frac{P}{B\sqrt{W}} \sqrt{\frac{\pi a}{W}} (0.752 + 0.37)$$

$$= \frac{P}{BW} \leftarrow \text{just the stress}$$

$$\cdot \sqrt{\pi a} \cdot 1.122$$

$$= 1.122 \sigma_y^{\text{app}} \sqrt{\pi a}$$

3S

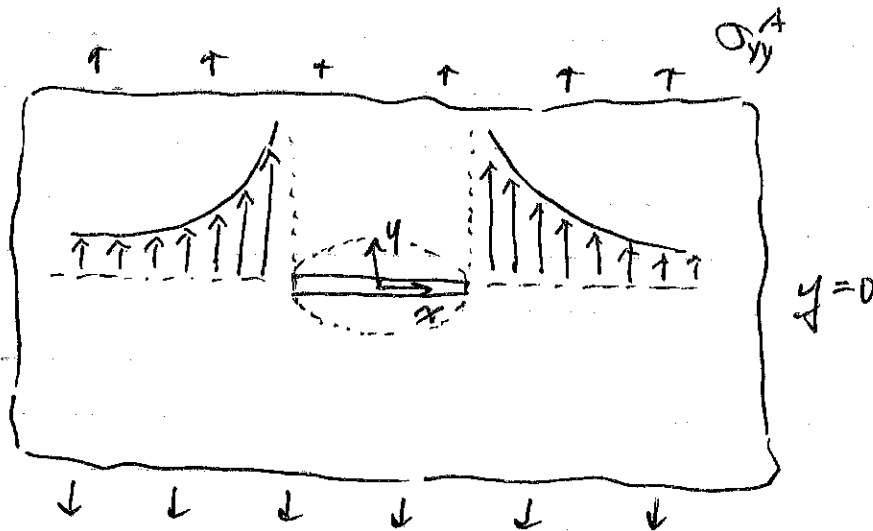
from the hole

solution

Problem Session 10

6/7/2014

LEFM \rightarrow Slit-like crack.



$$q(x) = \int_{-\infty}^{\infty} \frac{p(x')}{x-x'} dx', \quad p(x) = \frac{S|x|}{\sqrt{x^2-a^2}}$$

$$\frac{du(x)}{dx}$$

let $x = a + r$, $\lim_{r \rightarrow 0} \sigma_{yy}(x) = \frac{K_I}{\sqrt{2\pi r}}$ @ $x, y=0$.

$$d(x) = \frac{2(1-\nu)}{\pi} \sqrt{1 - \left(\frac{x}{a}\right)^2} \quad -a \leq x \leq a.$$

enthalpy: $H = E - W_{int} = -E$ linear elastic medium.

should decrease during loading. \downarrow

$\rightarrow F$ $W = Fx$

Kn. pre-existing

this kind of system: $W_{int} = 2E$ Stress.

internal energy

State 0

↓
no crack

E_0, H_0

→ $H_0 = -E_0$

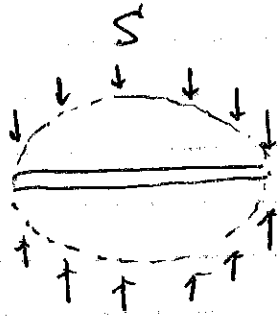
State 1

↓
With crack & opened.

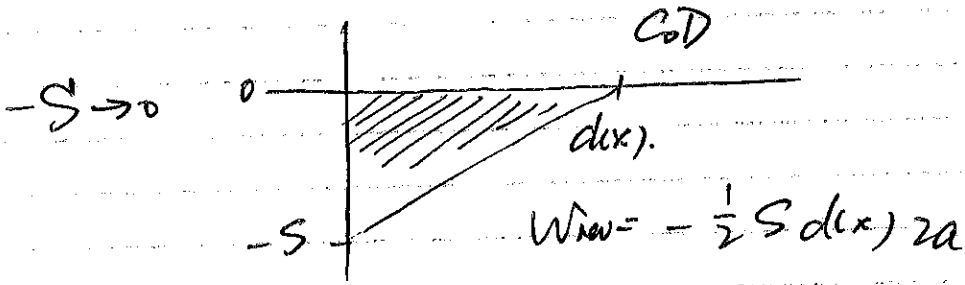
E_1, H_1

$\Delta H = -\Delta E$

↓
neg. → $\Delta E > 0$

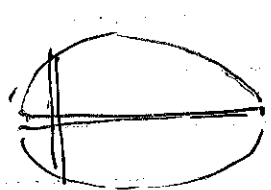


apply $S \rightarrow$ State 0



if stress is changing: $\int_{-a}^a \left[\frac{1}{2} dF dx) \right]$
↓
 $S dx$

We obtain: $\Delta H = -\frac{(1-\nu)}{2\mu} S^2 \pi a^2$



Shft-like crack

Griffith Criteria

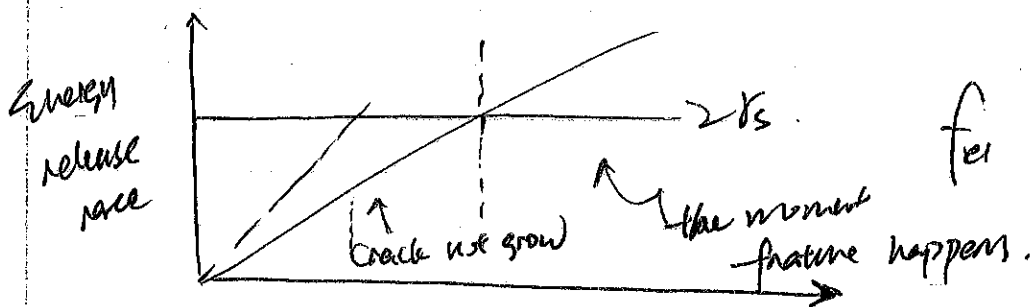
$$f_{el} = - \frac{\partial (\Delta H)}{\partial (\text{Crack length})} = - \frac{\partial (\Delta H)}{\partial (2a)}$$

Slit-like.
↑

$$f_{tot} = - \frac{\partial (\overbrace{\Delta H + 2 \gamma_s \cdot 2a}^{\Delta G})}{\partial (2a)} \rightarrow \text{two surfaces.}$$

← Griffith

$$= - \frac{\partial (\Delta H)}{\partial (2a)} - 2 \gamma_s \leftarrow \text{material property}$$



$$\Delta H = - \frac{(1-\nu)}{2\mu} S^2 \pi a^2 \rightarrow f_{el} = \frac{\pi (1-\nu)}{2\mu} S^2 a$$

↪ $\frac{(2a)^2}{4}$

$$f_{el} = 2 \gamma_s \quad S_c = \sqrt{\frac{8\mu \gamma_s}{\pi (1-\nu) (2a)}} \leftarrow \text{crack length fixed}$$

$$\text{or } 2a_c = \frac{8\mu \gamma_s}{\pi (1-\nu) S^2} \leftarrow \text{stress fixed}$$

mode - I loading

Energy release rate

$$G = - \frac{\partial(\Delta H)}{\partial(\text{crack length})}$$

$$= \frac{\pi(1-\nu)}{2\mu} S^2 a$$

slit-like

generalised
suppression



$$= \frac{K_I^2}{E'} \left\{ \begin{array}{l} K_I = S\sqrt{\pi a} \\ E' = \frac{E}{1-\nu} \text{ (plane strain)} \end{array} \right.$$

True loadings

$\sigma_{yy}^{(1)}$

$\sigma_{yy}^{(2)}$

$K_I^{(1)}$

$K_I^{(2)}$

can use principles of
superposition due to
linear elasticity.

$$G = \frac{(K_I^{(1)} + K_I^{(2)})^2}{E'}$$

Multiple modes

$$G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{III}^2}{2\mu}$$

J-Integral

$$G \geq G_c \rightarrow \text{material property}$$

$$\frac{K_I^2}{E'} \geq \frac{K_{Ic}^2}{E'}$$

\Rightarrow

$$K_I \geq K_{Ic}$$

Crack growth
Condition



fracture toughness

$$J_i = \int_S (w n_i - T_j u_{j,i}) dS.$$

x, y, z

In 1D, $J_x = \int_{\Gamma} \left(w dy - I \frac{\partial u}{\partial x} \right) dS$

$\frac{dy}{dx} \frac{dS}{ds}$

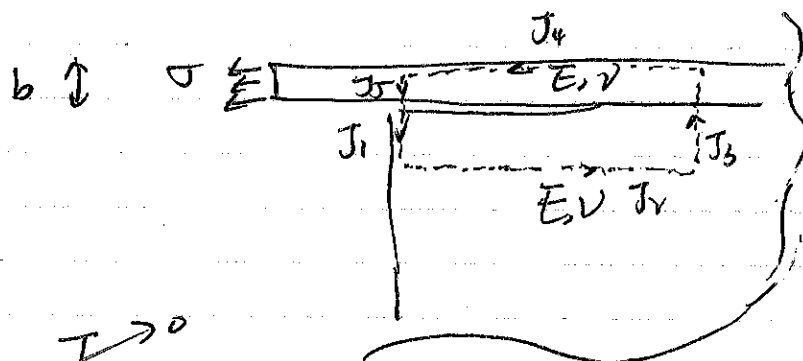
path $\rightarrow dx \underline{i} + dy \underline{j}$

$dS \rightarrow dy \underline{i} - dx \underline{j}$

$$J_x = \int_{\Gamma} w dy - \left(T_x \frac{\partial u}{\partial x} + T_y \frac{\partial u}{\partial y} \right) dS.$$

Example

$$J_x = \sum_{i=1}^5 J_i$$



①: $w \rightarrow 0$

$I \rightarrow 0$

J_i by surface

②: $dy \rightarrow 0$

$\frac{\partial u}{\partial x} \rightarrow 0$

Q: B-dia.?

③: $w \rightarrow 0$

$I \rightarrow 0$

(infinitely far away)

④: $w dy \rightarrow 0$

$I \rightarrow$
traction free.

$$⑤: \int w dy = \int_b^0 \frac{1}{2} \nabla_{ij} \epsilon_{ij} dy$$

$$dS = dx \underline{i} + dy \underline{j}$$

$$W = \frac{1}{2} \sigma \epsilon$$

$$W = \frac{\sigma^2}{2E} \quad \epsilon_{xx} = \frac{\sigma_{xx}}{E}$$

$$\int_0^b w dy = \frac{\sigma^2 b}{2E}$$

$$\int_0^b T_x \frac{\partial u_x}{\partial x} dy$$

$$T_x = \sigma_{xx} = \sigma$$

$$= - \int_0^b \sigma_{xx} \epsilon_{xx} dy$$

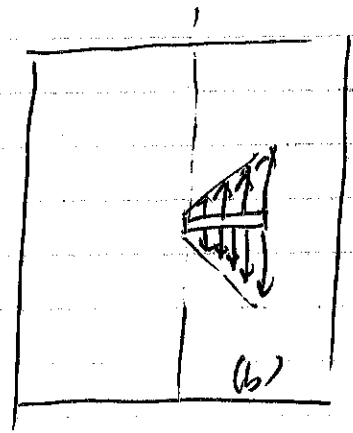
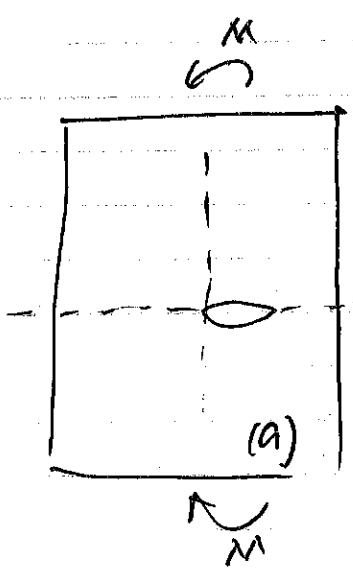
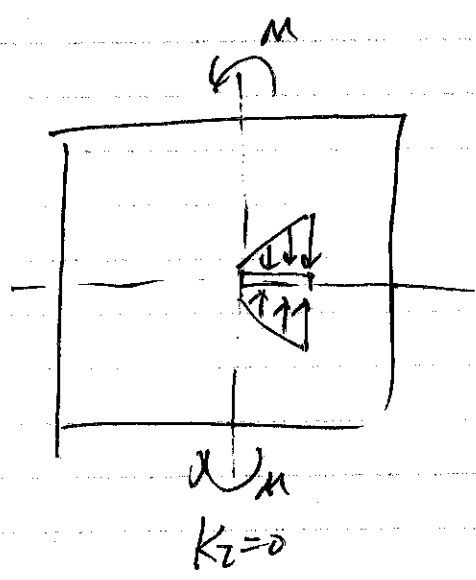
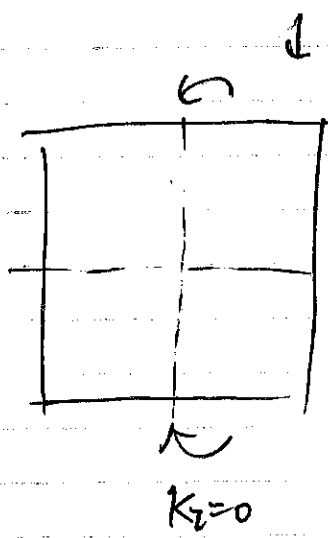
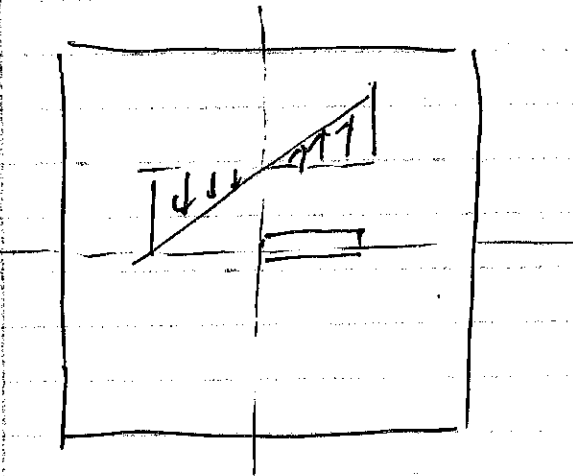
$$\frac{\partial u_x}{\partial x} = \epsilon_{xx}$$

$$= - \int_0^b \frac{\sigma^2}{E} dy = - \frac{\sigma^2 b}{E}$$

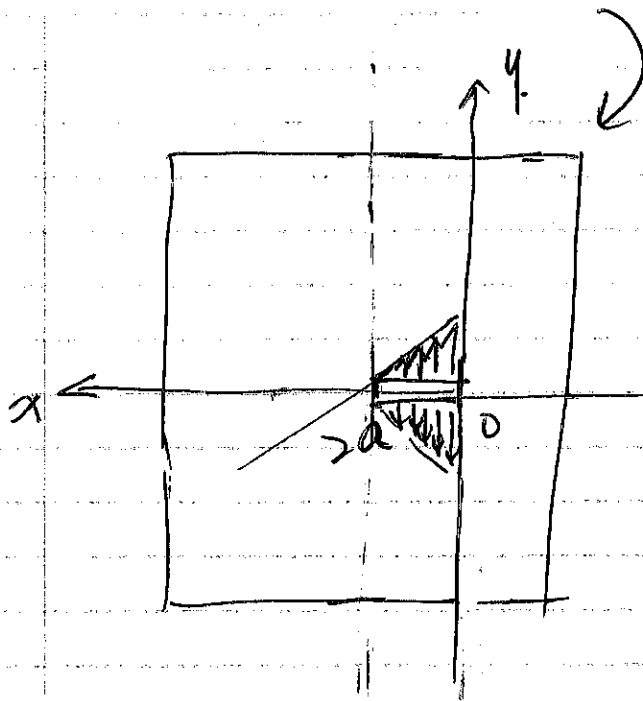
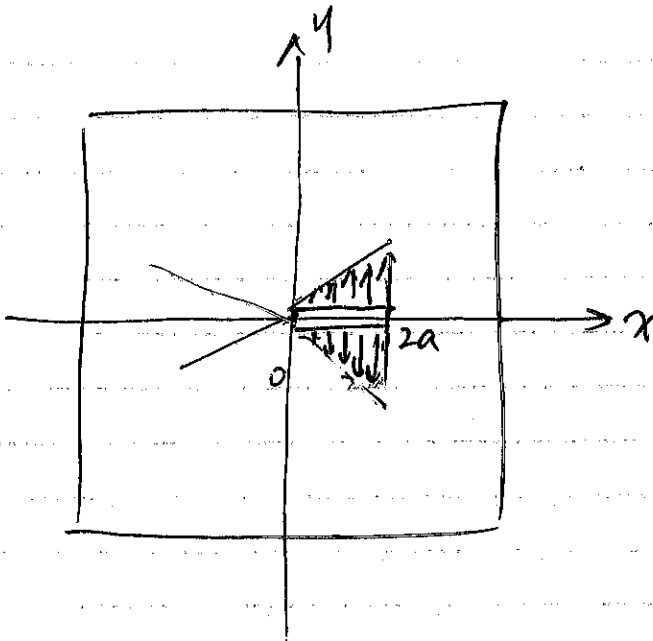
$$J_x = \frac{\sigma^2 b}{2E} - \left(- \frac{\sigma^2 b}{E} \right) = \frac{3 \sigma^2 b}{2E} = \frac{K_D^2}{E}$$

↑ plane stress

for plane strain, we replace E with E' .



$$K_z^{(a)} = K_I^{(b)}$$



looking from the back side.

"Shift coordinate to obtain K_L or
the left side \rightarrow integral goes from $0 \rightarrow 2a$ ".

Fracture mechanics review

Contact problem

from the surface Green function we know
the equation for contact:

$$\frac{du_0}{da} = \frac{K+1}{4\pi\mu} \int_{-c}^c \frac{P_y(x')}{x-x'} dx'$$

→ integral equation soln:

$$P_y(x) = - \frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} \cdot \frac{4\pi\mu}{K+1} \frac{du_0(x')}{dx'}}{x-x'} dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

From the flat punch contact we know

$$P_y \sim \frac{F}{\pi} (2cr)^{-1/2}$$

$$\rightarrow \sigma_{yy} \propto \frac{1}{\sqrt{r}}$$

Wedge and Notch

Trial soln for wedge:

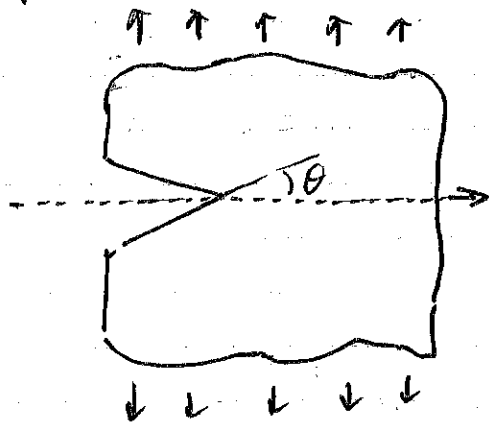
$$\phi = r^2 (A_1 \cos 2\theta + A_2 + A_3 \sin 2\theta + A_4 \theta)$$

$$\sigma_{rr} = -2A_1 \cos 2\theta + 2A_2 - 2A_3 \sin 2\theta + 2A_4 \theta$$

$$\sigma_{r\theta} = 2A_1 \sin 2\theta + 0 - 2A_3 \cos 2\theta - A_4$$

$$\sigma_{\theta\theta} = 2A_1 \cos 2\theta + 2A_2 + 2A_3 \cos 2\theta + 2A_4 \theta$$

formulate the notch problem.



William's soln. ($\lambda = \lambda - 1$).

$$\phi = r^{2\lambda} \{ A_1 \cos(\lambda\pi) \theta + A_2 \cos(\lambda-1)\pi \theta + A_3 \sin(\lambda+1)\pi \theta + A_4 \sin(\lambda-1)\pi \theta \}$$

$\dots \rightarrow \sigma_{rr}, \sigma_{\theta\theta}, \sigma_{r\theta}$

Find the symmetric & anti-symmetric part based on the nature of the loading.

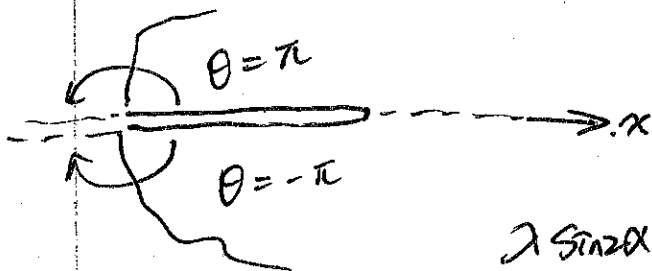
$$\det(M_1) = 0$$

\uparrow
Symmetric

$$\det(M_2) = 0$$

\uparrow
anti-symmetric.

$\dots \rightarrow$ when the notch turns into a crack



$$\alpha = 2\pi$$

$$\downarrow$$

$$\sin 2\alpha = 0.$$

$$\lambda \sin 2\alpha \pm \sin 2\lambda\alpha = 0 \dots \rightarrow \sin \pi\lambda = 0$$

$$\lambda = 0, \frac{1}{2}, 1, \frac{3}{2}$$

\uparrow Stress fields non-singular.

Strain energy is infinite.

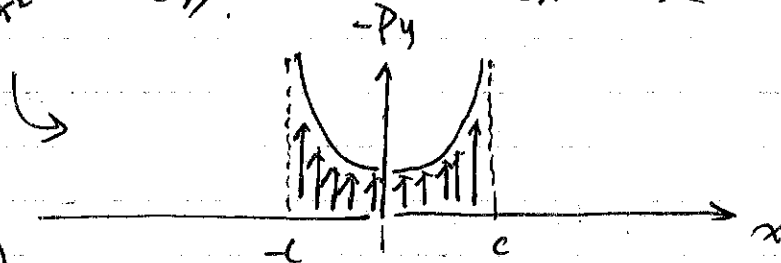
$$\sigma \sim \frac{1}{\sqrt{r}} \dots \text{Crack tip singularity.}$$

Equivalence between crack & flat-punch problems

$$P_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}} = -\sigma_{yy}$$

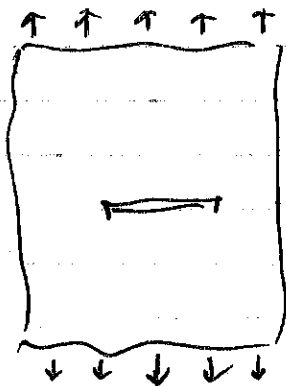


$$P_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}} = \sigma_{yy}$$

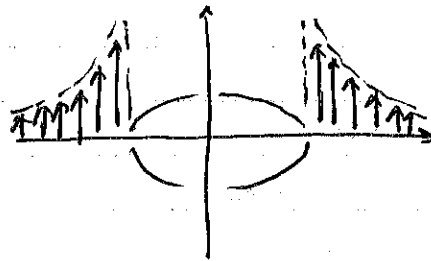


(... skip plasticity)

Slit-like Crack



Equivalence between
contact & cracks



recall soln to the singular integral equation:

$$P_y(x) = -\frac{1}{\pi^2} \frac{(x-a)^{1/2}}{(x+a)^{1/2}} \left[\int_{-\infty}^{-a} + \int_a^{+\infty} \right] \frac{(x'+a)^{1/2}}{(x'-a)^{1/2}} \frac{q(x')}{x-x'} dx'$$

$$P_y(x) = \frac{A + B/x}{\sqrt{1 - (a/x)^2}} + \frac{Ax + B}{(x+a)^{1/2} (x-a)^{1/2}}$$

$$\dots \sigma_{yy}(x, y=0) = \frac{S \cdot |x|}{\sqrt{x^2 - a^2}}$$

to find the stress singularity at crack tip,

let $x = a + r$, (taking $r \rightarrow 0^+$)

$$\sigma_{yy} \sim \frac{S a}{\sqrt{2 a r}} = S \sqrt{\frac{a}{2}} \frac{1}{\sqrt{r}}$$

Recall Wedge & notch: $\sigma_{rr} = \frac{K_I}{\sqrt{2 \pi r}} \left(\frac{5}{4} \cos \frac{\theta}{2} - \frac{1}{4} \cos \frac{3\theta}{2} \right)$

$\rightarrow \sigma_{rr} = \frac{K_I}{\sqrt{2 \pi r}}$... stress intensity factor: $K_I = S \sqrt{\pi a}$

for slit-like crack:

$$\tilde{u}_y(x) = - \frac{1-\nu}{\mu} S a \cdot \sqrt{1 - (x/a)^2}$$

$$\rightarrow d(x) = -2 \tilde{u}_y(x) = \frac{2(1-\nu)}{\mu} S a \cdot \sqrt{1 - (x/a)^2}$$

Enthalpy of the crack.

$$H = E - \Delta W_{im}$$

linear elastic medium sub. traction force \underline{T} on S_t .
the enthalpy writes:

$$H = \int_{\Omega} \frac{1}{2} \sigma_{ij} \epsilon_{ij} dV - \int_{S_t} T_j u_j dS.$$

elastic strain energy

For slit-like crack,

works like magic !!!

$$\left\{ \begin{aligned} E &= \frac{1}{2} \sigma_{yy}^A \epsilon_{yy} V \end{aligned} \right.$$

$$\left\{ \begin{aligned} \Delta W_{im} &= (\sigma_{yy}^A A) \cdot (\epsilon_{yy} L) = \sigma_{yy}^A \epsilon_{yy} \cdot V. \end{aligned} \right.$$

$$H = \frac{1}{2} \sigma_{yy}^A \epsilon_{yy} V - \sigma_{yy}^A \epsilon_{yy} V = - \frac{1}{2} \sigma_{yy}^A \epsilon_{yy} V = -E$$

enthalpy: $\Delta H = \Delta W^+ + \Delta W^-$

$$= \frac{1}{2} S \int_{-a}^a 2 \tilde{u}_y(x) dx$$

$$= -\frac{1}{2} S \int_{-a}^a d(x) dx$$

crack-opening displacement:

$$d(x) = \frac{2(1-\nu)}{\mu} S a \sqrt{1 - \left(\frac{x}{a}\right)^2}$$

enthalpy change proportional to applied stress S :

$$\Delta H = -\frac{1-\nu}{2\mu} S^2 \pi a^2 \quad (\text{plane strain})$$

driving force for crack propagation.

$$f_a = -\frac{\partial \Delta H}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a = \frac{1-\nu}{2\mu} K_I^2$$

Griffith criteria, free energy:

$$\Delta G = \Delta H + \gamma_s \cdot 2 \cdot 2a \quad \leftarrow \text{slit-like.}$$

plug in: $\Delta G = -\frac{1-\nu}{2\mu} S^2 \pi a^2 + 4\gamma_s a$

$$f_{\text{tot}} = \frac{\pi(1-\nu)}{2\mu} S^2 a - 2\gamma_s$$

Solving for $f_{\text{tot}} = 0$, one can solve for the critical crack size & critical stress:

$$a_c = \frac{4\mu}{\pi(1-\nu)} \frac{\gamma_s}{S^2} \quad \& \quad S_c = \sqrt{\frac{4\mu\gamma_s}{\pi(1-\nu)a}}$$

(plane strain)

See eqn. (50) for general expression $d(x)$, ΔH , f_a , f_{tot} .

Energy release rate

mode - I, mode - II, mode - III.

Solutions for $\begin{cases} \sigma_{xx}^{(I)} \\ \sigma_{yy}^{(I)} \\ \sigma_{xy}^{(I)} \end{cases}, \begin{cases} \sigma_{xx}^{(II)} \\ \sigma_{yy}^{(II)} \\ \sigma_{xy}^{(II)} \end{cases}, \begin{cases} \sigma_{xz}^{(III)} \\ \sigma_{yz}^{(III)} \end{cases}$

energy release rate G (crack extension force)
elastic contribution.

$$G = - \frac{\partial (aH)}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} (\sigma_{yy}^A)^2 a$$

$$E' \equiv \frac{E}{1-\nu^2}$$

$$G = \frac{\pi}{E'} (\sigma_{yy}^A)^2 a$$

recall $K_I = \sigma_{yy}^A \sqrt{\pi a} \rightarrow G = \frac{K_I^2}{E'} \dots \text{mode - I}$

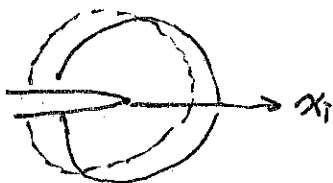
general crack case: $G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{III}^2}{2\mu}$

one may also derive the energy release rate based on the variation of H w.r.t. a .

J-Integral (2D) $J = \int_{\Gamma} w dy - \int_{\Gamma} T_i \frac{\partial u_i}{\partial x} ds$

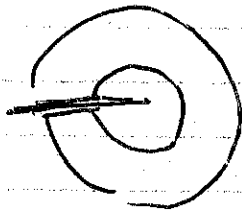
$$J = G = \int_V \frac{\partial w}{\partial x_i} dV - \int_S T_j \frac{\partial u_j}{\partial x_i} dS$$

→ the work done: $-J_i \delta x_i = \int_V w dV - \int_V w dV$



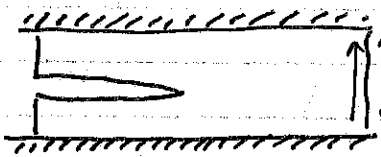
$$+ \int_{S'} T_j u_j dS - \int_S T_j u_j dS = H' - H$$

Example 1



no singularity, $J(P) = 0$.

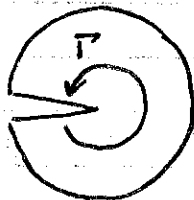
Example 2



$$J = wh$$

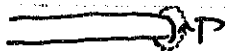
boundary work.

Example 3



$$J = \int_{\Gamma} w dy - \underline{I} \cdot \frac{\partial u}{\partial x} dS = \frac{1-\nu}{2\mu} K_I^2 = \frac{K_I^2}{E}$$

Example 4

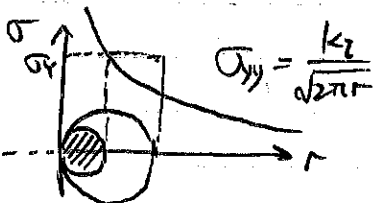


$$J = \int_{\Gamma} w dy - \underline{I} \cdot \frac{\partial u}{\partial x} dS$$



Elastic-Plastic Fracture Mechanics

fracture criteria: $J = J_c$



$$\sigma_y = \frac{K_I}{\sqrt{2\pi r_y}}$$

$$r_y = \frac{1}{2\pi} \left(\frac{K_I}{\sigma_y} \right)^2$$

$$r_p = 2r_y$$

Plastic yielding changes K_I .

$$K_I = \frac{P}{B\sqrt{w}} f\left(\frac{a_{eff}}{w}\right) \leftarrow \text{estimate: } a_{eff} = a + r_y$$

HRR Solution: $\frac{\epsilon}{\epsilon_0} = \frac{\sigma}{\sigma_0} + \alpha \left(\frac{\sigma}{\sigma_0} \right)^n$ Strain-hardening exp.

HRR singularity: $\sigma \cdot \epsilon \propto \frac{1}{r}$.

→ Strip yield model

$$K_{I+a} = \frac{P}{\sqrt{\pi a}} \sqrt{\frac{a+\pi}{a-\pi}}, \quad K_{I-a} = \frac{P}{\sqrt{\pi a}} \sqrt{\frac{a-\pi}{a+\pi}}$$

total stress intensity factor (a) $a+\rho = 0$

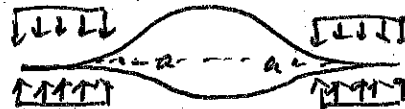
$$K_{tot} = \sigma_{yy}^A \sqrt{\pi(a+\rho)} + K_{closure} = 0$$

$$\sigma_{yy}^A \sqrt{\pi(a+\rho)} - 2\sigma_Y \sqrt{\frac{a+\rho}{\pi}} \arccos\left(\frac{a}{a+\rho}\right) = 0$$

↑
cancel singularity

... some algebra.

$$\rho \approx 0.393 \left(\frac{K_{I+ad}}{\sigma_Y} \right)^2$$



$$\Gamma_P = \frac{1}{\pi} \left(\frac{K_I}{\sigma_Y} \right)^2 = 0.318 \left(\frac{K_I}{\sigma_Y} \right)^2 \quad \text{... Irwin's approach.}$$

→ Crack tip opening displacement

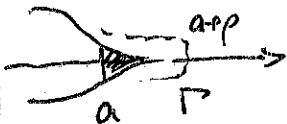
$$\delta = \frac{8\sigma_Y a}{\pi E'} \cdot \ln\left(\frac{a+\rho}{\rho}\right)$$

$$\delta = \frac{8\sigma_Y a}{\pi E'} \ln \left[\sec\left(\frac{\pi}{2} \cdot \frac{\sigma_{yy}^A}{\sigma_Y}\right) \right]$$

at small σ_{yy}^A : $\delta \approx \frac{K_{I+ad}^2}{E' \sigma_Y}$ as $\sigma_{yy}^A \rightarrow \sigma_Y$, $\delta \rightarrow \infty$

→ energy release rate of strip yield.

$$G = J = \int_{\Gamma} w dy - \int \frac{\partial u}{\partial x} ds$$



$$= -\sigma_Y u_y(x=a, y=0) + \sigma_Y u_y(x=a, y=0^+)$$

$$= \sigma_Y \cdot \delta$$

... $G = J = \sigma_Y \cdot \delta$... fracture: $\sigma_Y \cdot \delta_c$
↑ fracture CTOD

Plasticity review

• Displacement: $\underline{u} = \underline{x} - \underline{X}$

• Strain: $\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$

• Stress: $T_j = \sigma_{ij} n_i$

→ same with
elasticity

• Equilibrium: $\sigma_{ij,i} + F_j = 0$

For strain: $\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$

Elastic constitutive relationship: $\sigma_{ij} = C_{ijkl} \epsilon_{kl}^{el}$

hydrostatic stress: $\bar{\sigma} \equiv \frac{1}{3} \sigma_{ii}$

↑
important

$$\hookrightarrow \bar{\sigma} = 3K \bar{\epsilon}$$

$$K = \frac{E}{3(1-2\nu)}$$

deviatoric stress & strain relationship. $\epsilon_{ij} = \frac{2}{3} \mu e_{ij}$

• Yield condition. $f(\{\sigma_{ij}\}) = 0$

original stress invariants: I_1, I_2, I_3 (too complicated!)

Solving eigensystem for deviatoric stress.

$$\det(\underline{\underline{S}} - \hat{\lambda} \underline{\underline{I}}) = \begin{vmatrix} \dots \end{vmatrix} = 0 \rightarrow \hat{\lambda}^3 - J_1 \hat{\lambda}^2 + J_2 \hat{\lambda} + J_3 = 0$$

after some algebra, we have $J_2 = \frac{1}{2} S_{ij} S_{ij}$

a measure of deviatoric stress.
can be think of as the norm.

The new stress invariants:

$$J_1 = 0, \quad J_2 = \frac{1}{2} S_{ij} S_{ij}, \quad J_3 = \det(S_{ij})$$

$$\rightarrow f(\bar{\sigma}, J_2, J_3) = 0 \quad \text{some further simplification:}$$

$$\dots f(J_2) = J_2 - K^2 = 0; \quad \text{if EP is assumed:}$$

$$\rightarrow \dot{J}_2 = 0 \quad \rightarrow \quad \dot{J}_2 = S_{ij} \dot{S}_{ij} = 0$$

* Q: How to determine \dot{S}_{ij}^{pl} ? a constraint on the stress rate.

$$\dot{S}_{ij}^{pl} = \int_0^t \dot{\dot{S}}_{ij}^{pl}(t) dt \quad \Rightarrow \quad \sum \dot{\dot{S}}_{ij}^{pl} = \dot{\dot{S}}_{ij} \quad (\text{flow rule})$$

$$\dots \text{recall} \quad \sum e_{ij}^{el} = S_{ij} \quad \& \quad \sum \dot{e}_{ij}^{el} = \dot{S}_{ij}$$

$$\sum \dot{e}_{ij} = \sum (\dot{e}_{ij}^{el} + \dot{\dot{S}}_{ij}^{pl}) = \dot{S}_{ij} + \dot{\dot{S}}_{ij}$$

total deviatoric strain rate

$$\text{define work rate: } \dot{W} = S_{ij} \dot{e}_{ij} = S_{ij} (\dot{e}_{ij}^{el} + \dot{\dot{S}}_{ij}^{pl})$$

With Eyring assumption: $2\mu \dot{\epsilon} = 2\tilde{\lambda} k^2$

$$\rightarrow \tilde{\lambda} = \frac{2\mu}{2k^2} \dot{\epsilon} \quad \dots \quad \dot{\epsilon}_{ij}^{PI} = \frac{\dot{\epsilon}}{2k^2} \dot{\epsilon}$$

Overall summary

$$\dot{\epsilon}_{ij} \left\{ \begin{array}{l} \dot{\bar{\epsilon}} = \frac{1}{3} \dot{\epsilon}_{ii} \rightarrow \bar{\sigma} = 3K \dot{\bar{\epsilon}} \\ \dot{e}_{ij} = \dot{\epsilon}_{ij} - \dot{\bar{\epsilon}} \delta_{ij} \end{array} \right. \quad \dot{\sigma}_{ij} = \dot{s}_{ij} + \bar{\sigma} \delta_{ij}$$

$$\sigma_{ij} \left\{ \begin{array}{l} \bar{\sigma} = \frac{1}{3} \sigma_{ii} \\ s_{ij} = \sigma_{ij} - \bar{\sigma} \delta_{ij} \end{array} \right. \quad \bar{w} = s_{ij} \dot{e}_{ij} \rightarrow \dot{s}_{ij} = 2\mu \left(\dot{e}_{ij} - \frac{\dot{\epsilon}}{2k^2} s_{ij} \right)$$